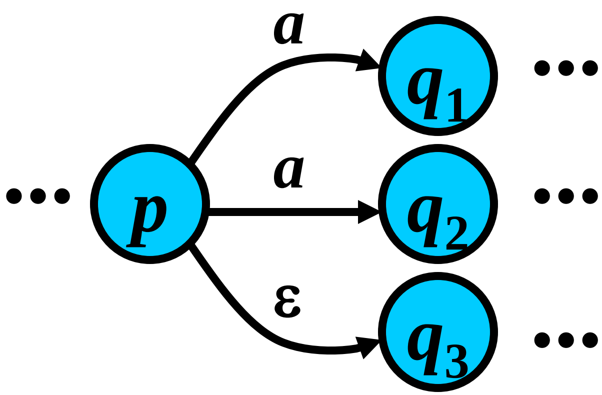
Restricted
Finite Automata

Theory vs. Practice

a) Configuration: pax

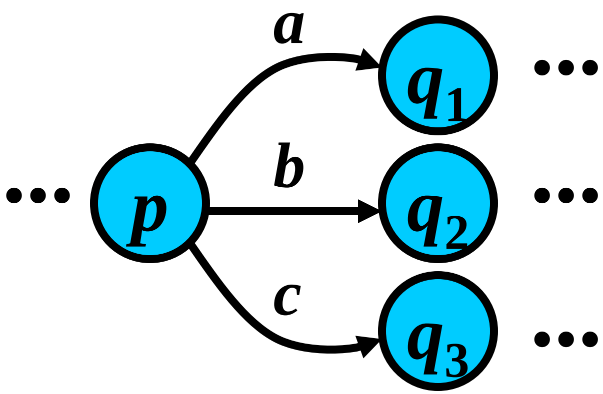


Next Configuration:
q_1x or q_2x or q_3ax **?**

Theory: ☺ × Practice: ☹

---

b) Configuration: pax



Next Configuration:
only q_1x

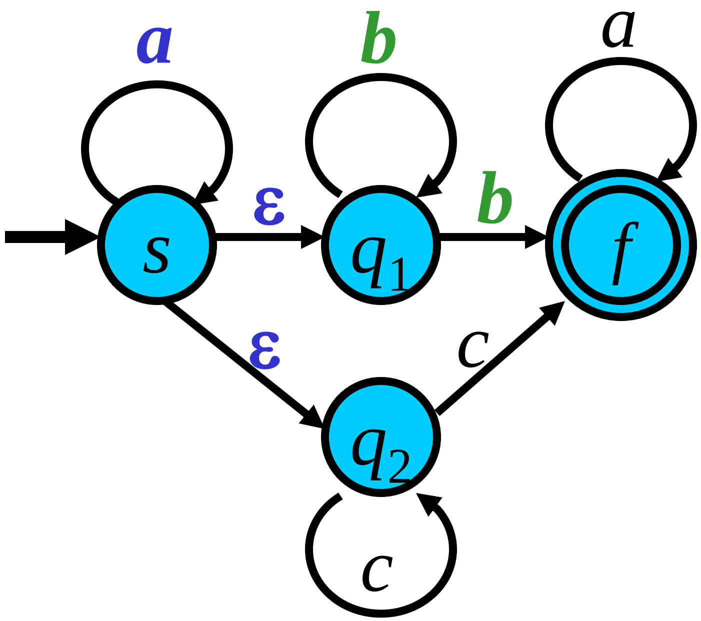
Theory: ☹ × Practice: ☺

Use of FA in General

Simulation of all possible moves from every configuration.

Example:

FA *M* is defined as:



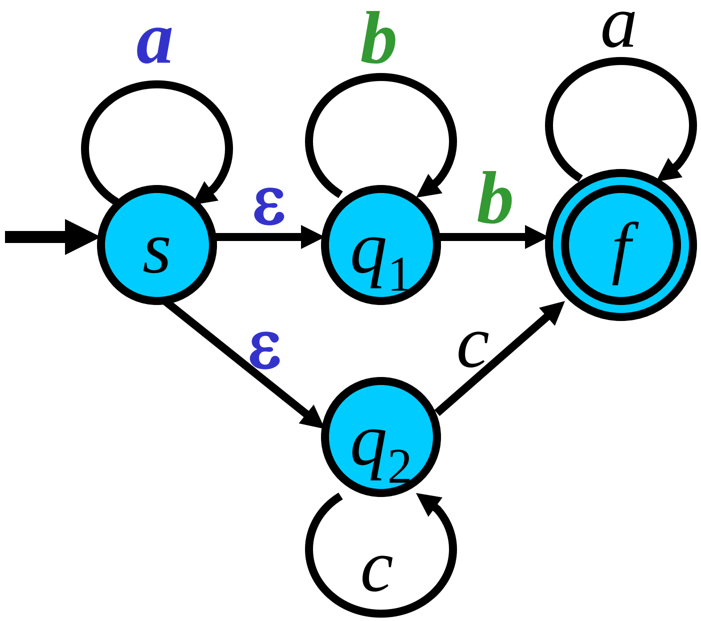
Question: $ab \in L(M)$ **?**

Use of FA in General

Simulation of all possible moves from every configuration.

Example:

FA *M* is defined as:



sab

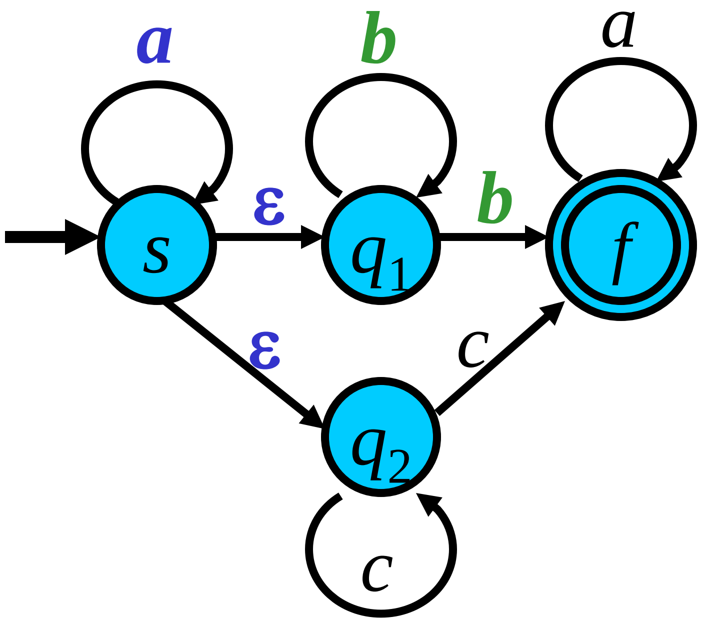
Question: $ab \in L(M)$ **?**

Use of FA in General

Simulation of all possible moves from every configuration.

Example:

FA *M* is defined as:



$$sab \left\{ \begin{array}{l} \vdash q_1ab \\ \vdash q_2ab \\ \vdash sb \end{array} \right.$$

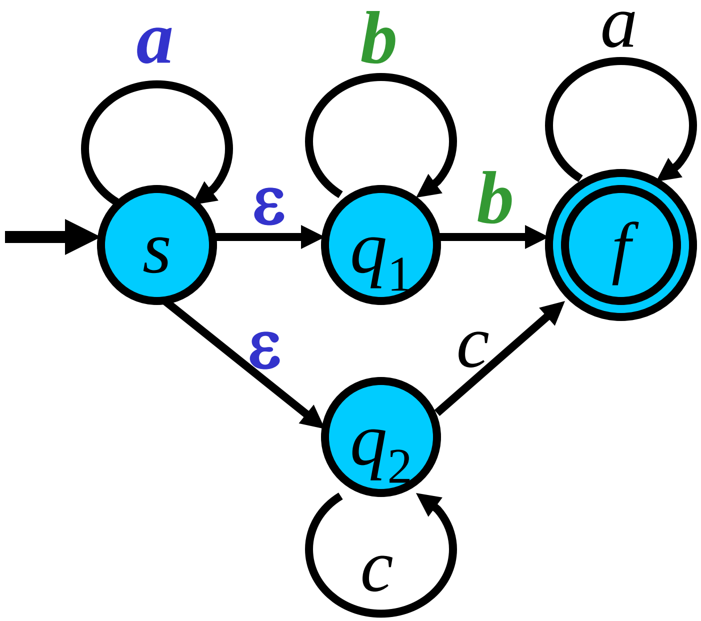
Question: $ab \in L(M)$ **?**

Use of FA in General

Simulation of all possible moves from every configuration.

Example:

FA M is defined as:



$$sab \begin{cases} \vdash q_1ab \\ \vdash q_2ab \\ \vdash sb \end{cases}$$

No next configuration

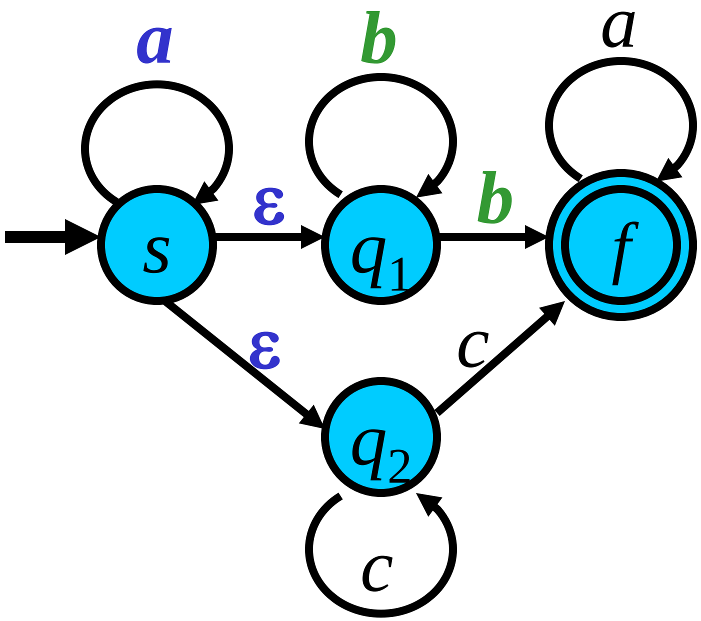
Question: $ab \in L(M)$ **?**

Use of FA in General

Simulation of all possible moves from every configuration.

Example:

FA M is defined as:



No next configuration

$$sab \left\{ \begin{array}{l} \vdash q_1ab \\ \vdash q_2ab \\ \vdash sb \end{array} \right.$$

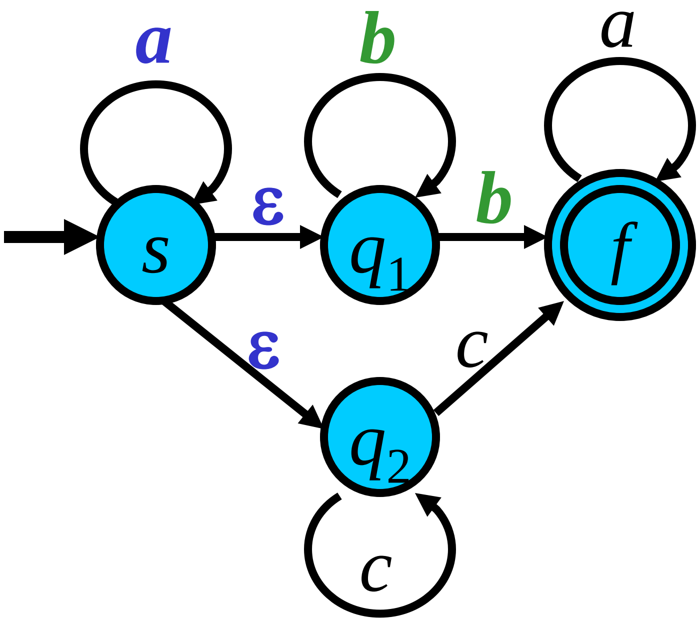
Question: $ab \in L(M)$ **?**

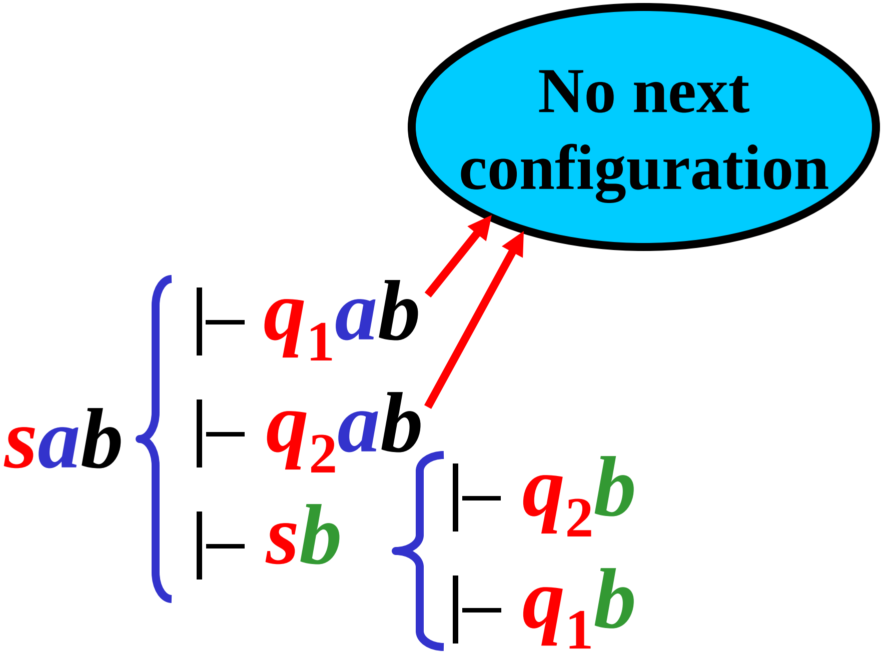
Use of FA in General

Simulation of all possible moves from every configuration.

Example:

FA M is defined as:





sab ⊢ q_1ab

⊢ q_2ab

⊢ sb ⊢ q_2b

⊢ q_1b

No next configuration

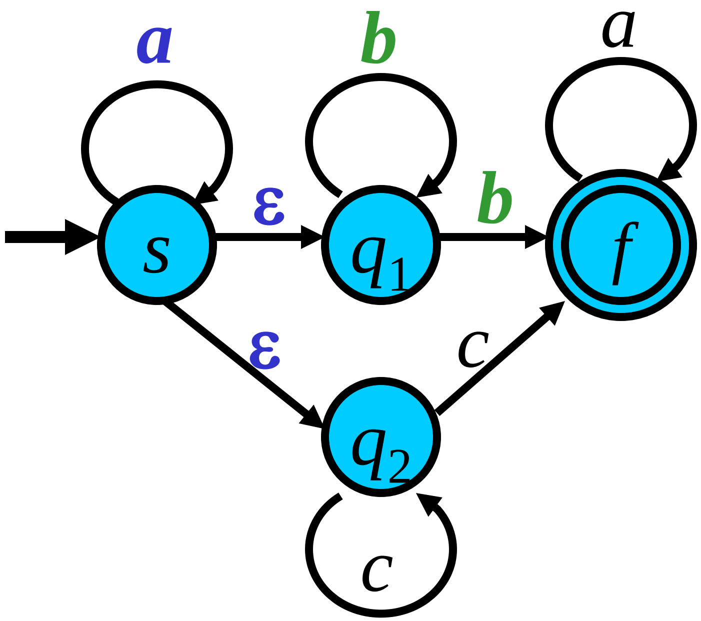
Question: $ab \in L(M)$ **?**

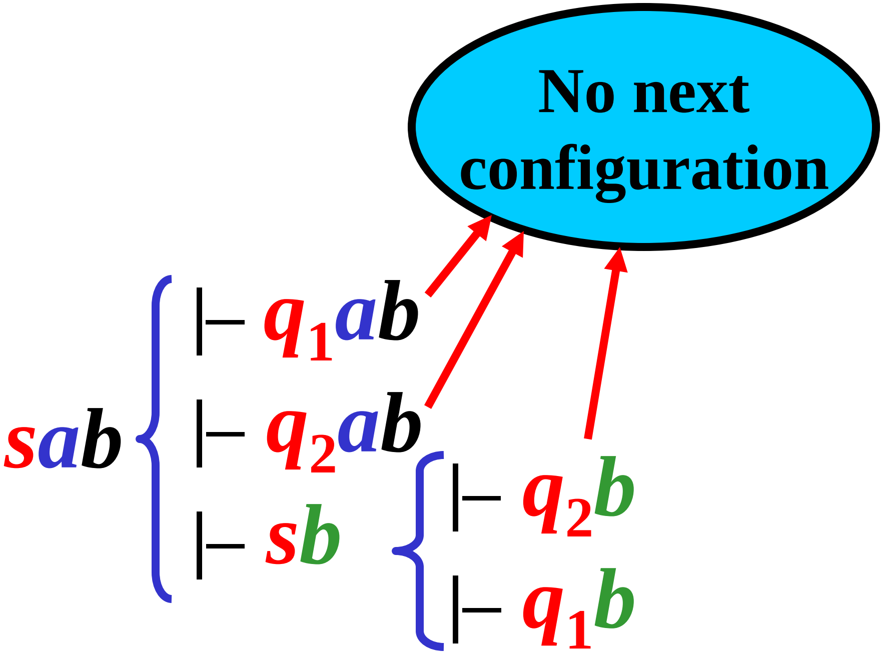
Use of FA in General

Simulation of all possible moves from every configuration.

Example:

FA M is defined as:





No next configuration

sab

$\vdash q_1ab$

$\vdash q_2ab$

$\vdash sb$

$\vdash q_2b$

$\vdash q_1b$

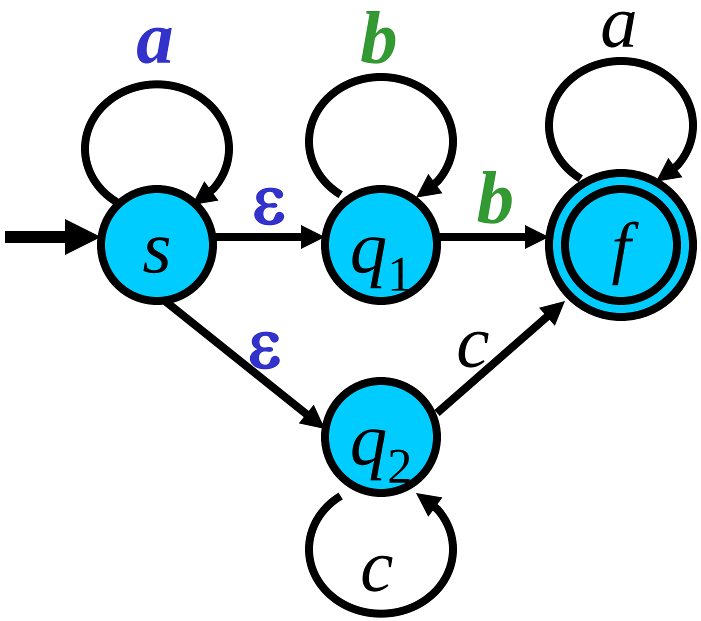
Question: $ab \in L(M)$ **?**

Use of FA in General

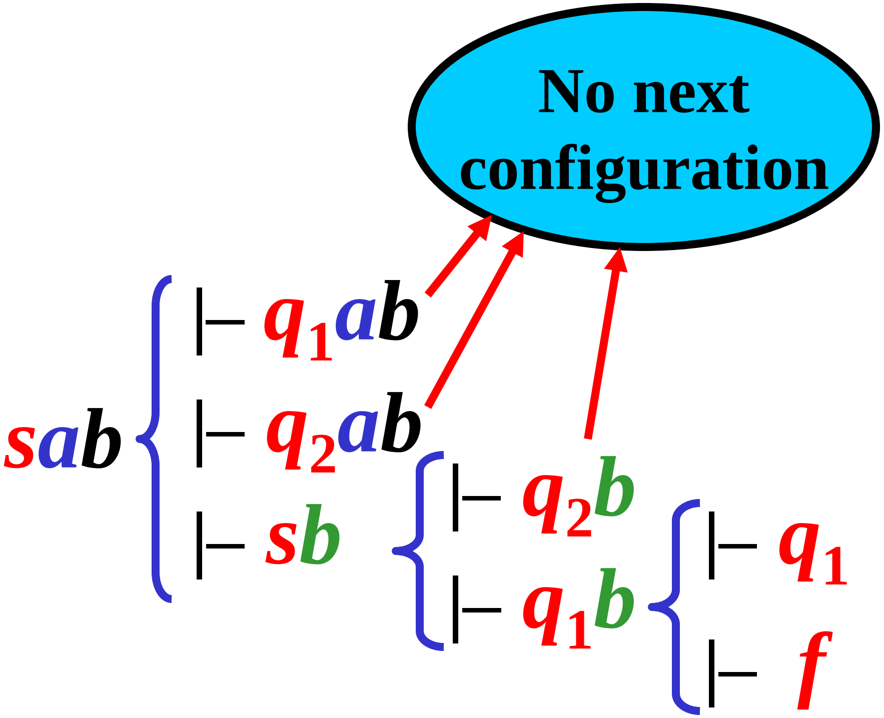
Simulation of all possible moves from every configuration.

Example:

FA *M* is defined as:



Question: $ab \in L(M)$?



No next configuration

$sab \vdash q_1ab$

$sab \vdash q_2ab$

$sab \vdash sb$

$sb \vdash q_2b$

$sb \vdash q_1b$

$q_1b \vdash q_1$

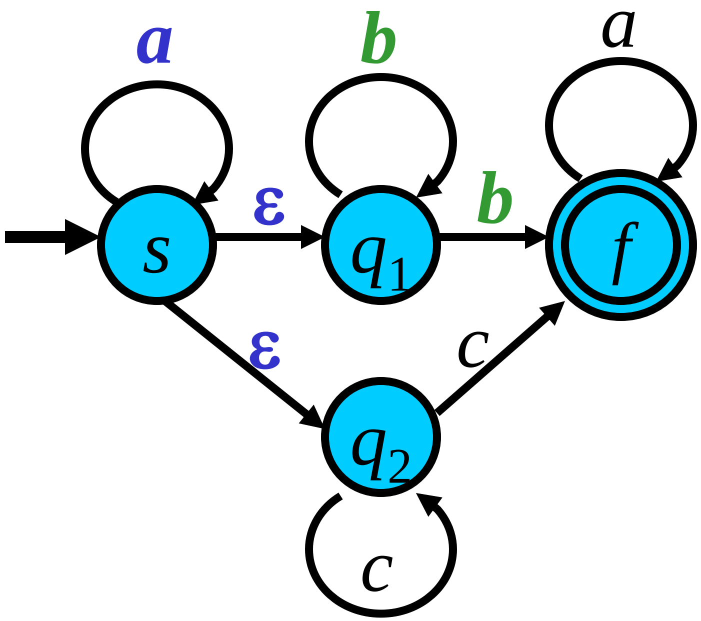
$q_1b \vdash f$

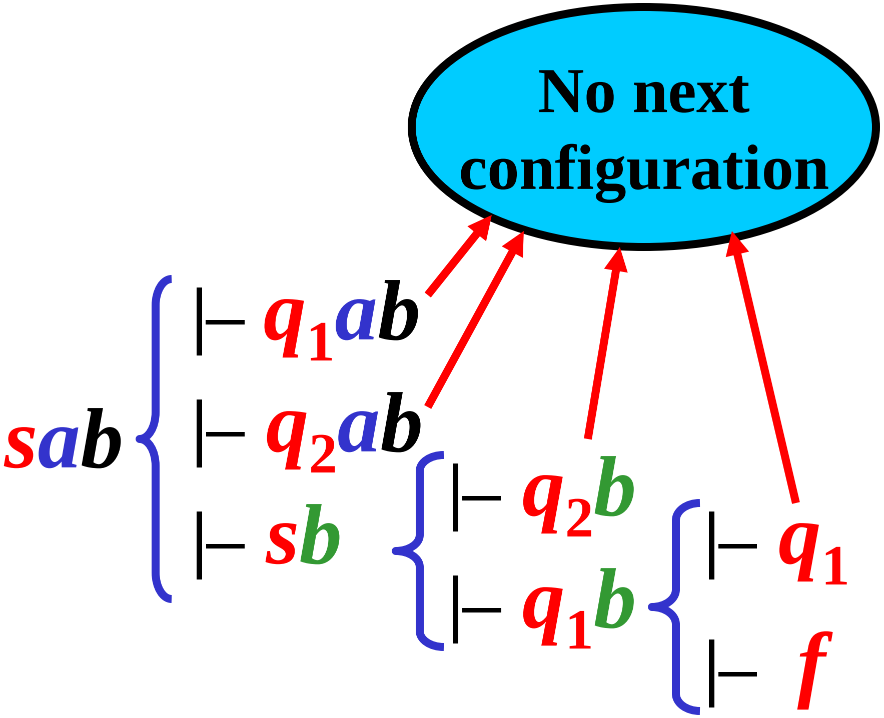
Use of FA in General

Simulation of all possible moves from every configuration.

Example:

FA M is defined as:




No next configuration

$sab \vdash q_1ab$

$sab \vdash q_2ab$

$sab \vdash sb$

$sb \vdash q_2b$

$sb \vdash q_1b$

$q_1b \vdash q_1$

$q_1b \vdash f$

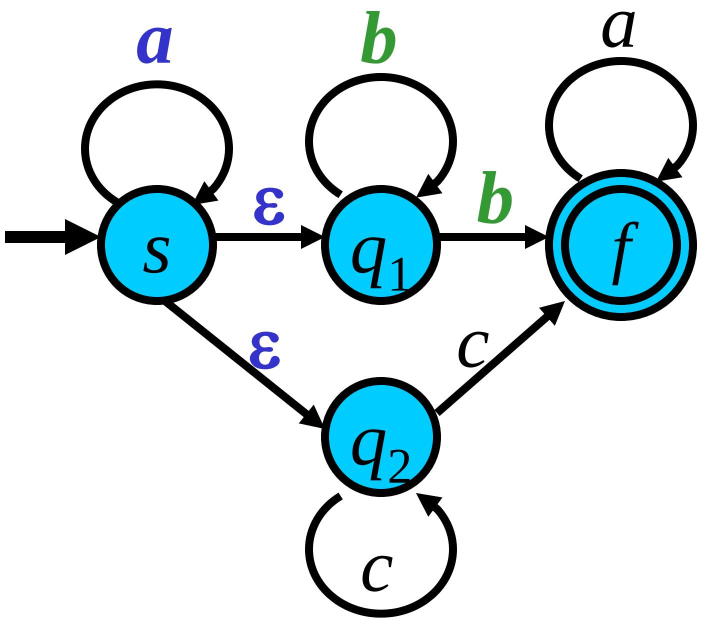
Question: $ab \in L(M)$ **?**

Use of FA in General

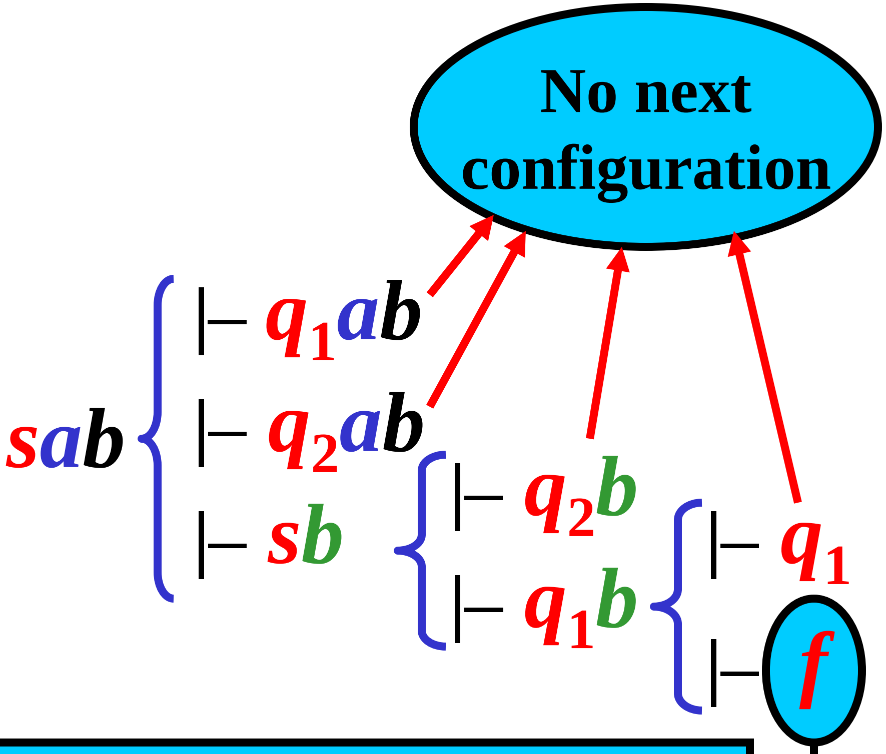
Simulation of all possible moves from every configuration.

Example:

FA M is defined as:



Question: $ab \in L(M)$ **?**



No next configuration

sab
$\vdash q_1ab$
$\vdash q_2ab$
$\vdash sb$

$\vdash q_2b$
$\vdash q_1b$

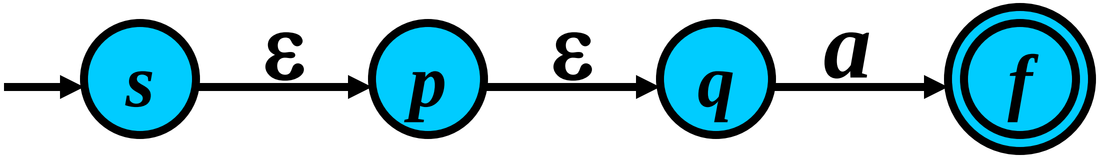
$\vdash q_1$
$\vdash f$

Answer: **YES**, $ab \in L(M)$
because $f \in F$.

From FA to DFA in Essence 1/2

Preference in practice: *Determinictic FA* (DFA) that makes no more than one move from every configuration.

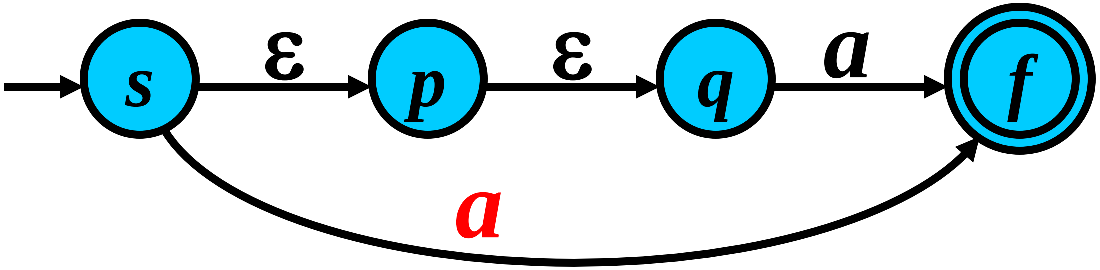
1) Gist: Removal of ε-moves



From FA to DFA in Essence 1/2

Preference in practice: *Determinictic FA* (DFA) that makes no more than one move from every configuration.

1) Gist: Removal of ε-moves

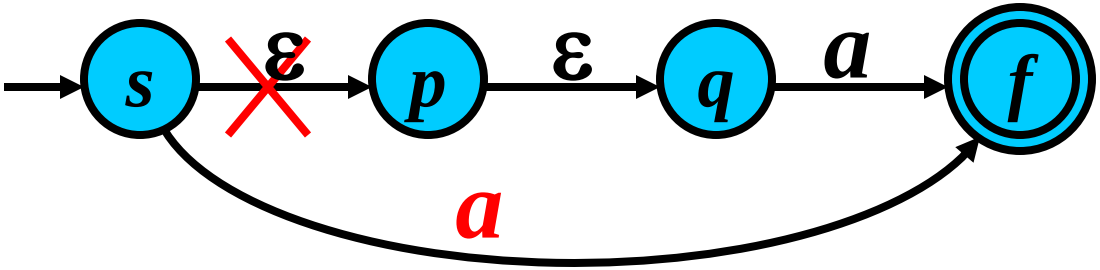


From FA to DFA in Essence 1/2

Preference in practice: *Determinictic FA* (DFA) that makes no more than one move from every configuration.

---

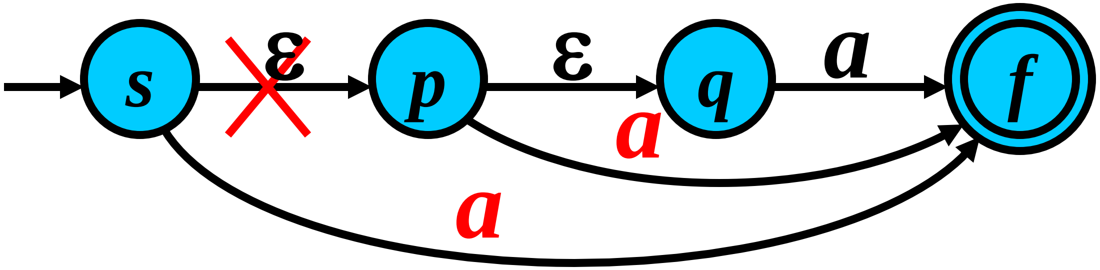
1) Gist: Removal of ε-moves



From FA to DFA in Essence 1/2

Preference in practice: *Determinictic FA* (DFA) that makes no more than one move from every configuration.

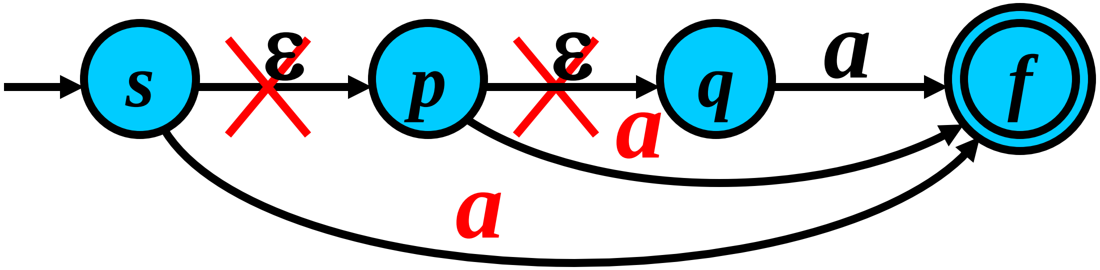
1) **Gist: Removal of ε-moves**



From FA to DFA in Essence 1/2

Preference in practice: *Determinictic FA* (DFA) that makes no more than one move from every configuration.

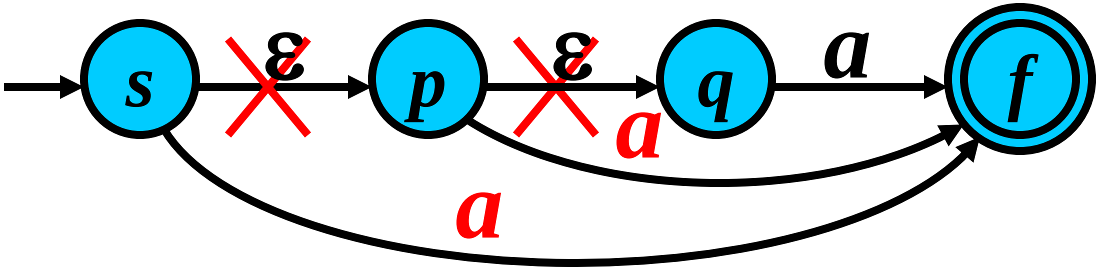
1) Gist: Removal of ε-moves



From FA to DFA in Essence 1/2

Preference in practice: *Determinictic FA* (DFA) that makes no more than one move from every configuration.

1) **Gist: Removal of ε-moves**

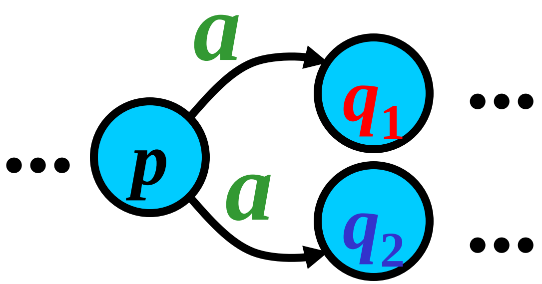


Definition: Let $M = (Q, \Sigma, R, s, F)$ be a FA. M is an ***ε-free finite automaton*** if for all rules $pa \to q \in R$, where $p, q \in Q$, holds

$$a \in \Sigma \; (a \neq \varepsilon)$$

From FA to DFA in Essence 2/2

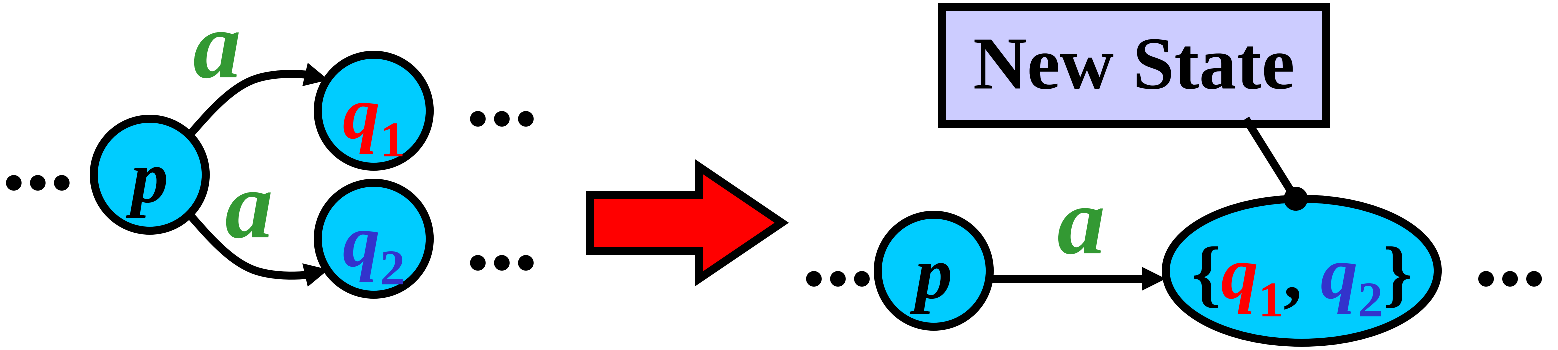
2) Gist: Removal of nodeterminism



Definition: Let $M = (Q, \Sigma, R, s, F)$ be an **ε-free FA**. M is a ***deterministic finite automaton*** (DFA) if for each rule $\boldsymbol{pa} \rightarrow \boldsymbol{q} \in R$ it holds that $R - \{\boldsymbol{pa} \rightarrow \boldsymbol{q}\}$ contains no rule with the left-hand side equal to $\boldsymbol{pa}$.

From FA to DFA in Essence 2/2

2) Gist: Removal of nodeterminism

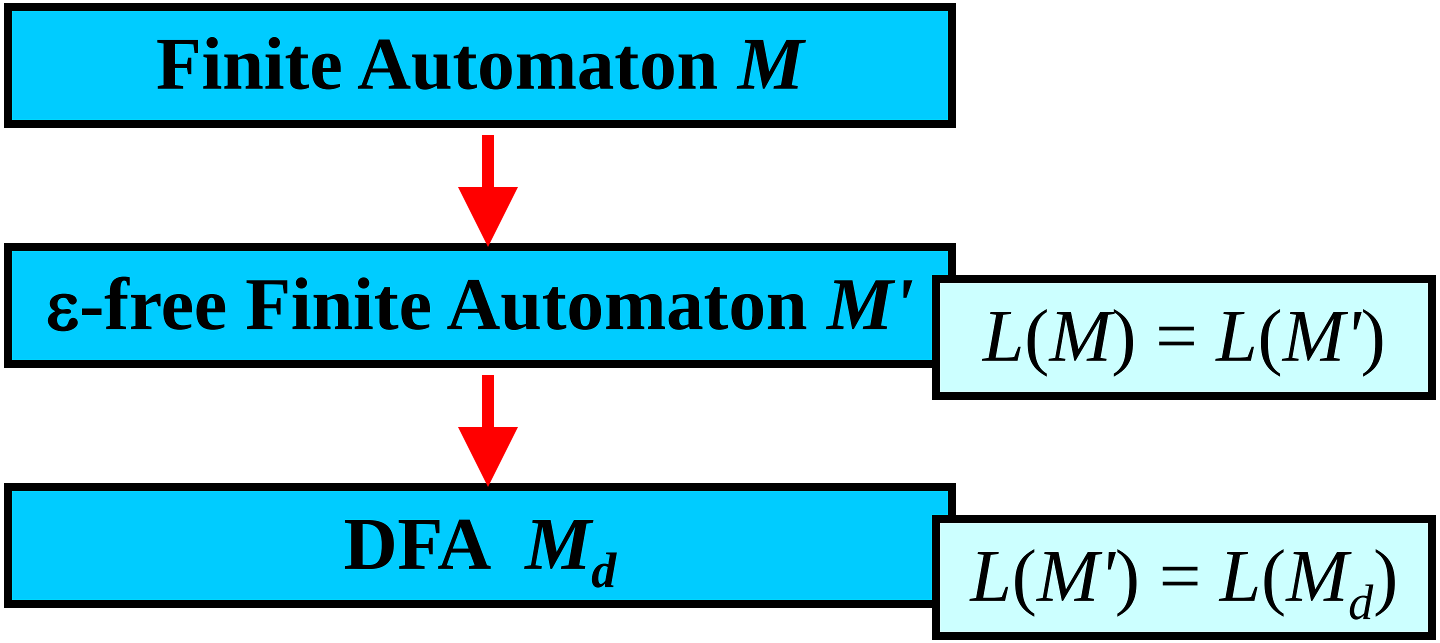


Definition: Let $M = (Q, \Sigma, R, s, F)$ be an **ε-free FA**. M is a ***deterministic finite automaton*** (DFA) if for each rule $pa \rightarrow q \in R$ it holds that $R - \{pa \rightarrow q\}$ contains no rule with the left-hand side equal to pa.

Theorem

- For every FA M, there is an equivalent DFA M_d.

Proof is based on these conversions:



Finite Automaton M

ε-free Finite Automaton M'

$L(M) = L(M')$

DFA M_d

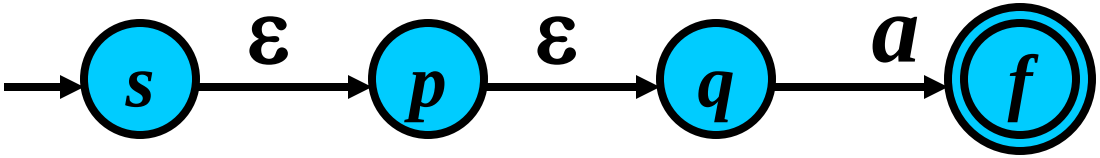
$L(M') = L(M_d)$

ε-closure

Gist: *q* is in ε-closure(*p*) if FA can reach *q* from *p* without reading.

Definition: For every states $p \in Q$, we define a set *ε-closure*(*p*) as ε-closure(*p*) = $\{q: q \in Q, p \vdash^* q\}$

Example:

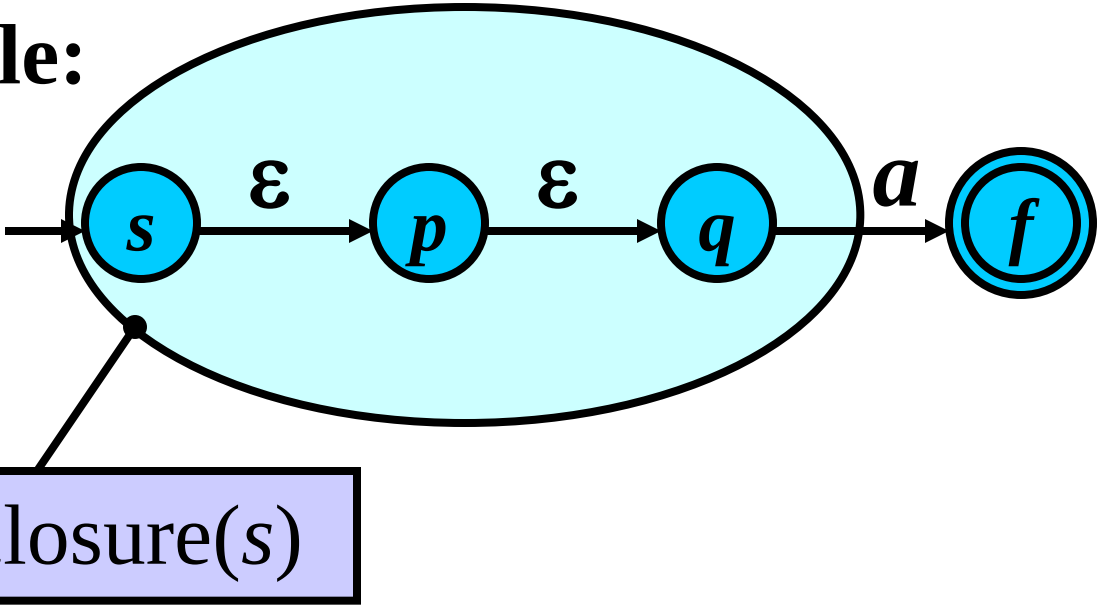


ε-closure

Gist: *q* is in ε-closure(*p*) if FA can reach *q* from *p* without reading.

Definition: For every states $p \in Q$, we define a set *ε-closure*(p) as ε-closure(p) = $\{q: q \in Q, p \vdash^* q\}$

Example:

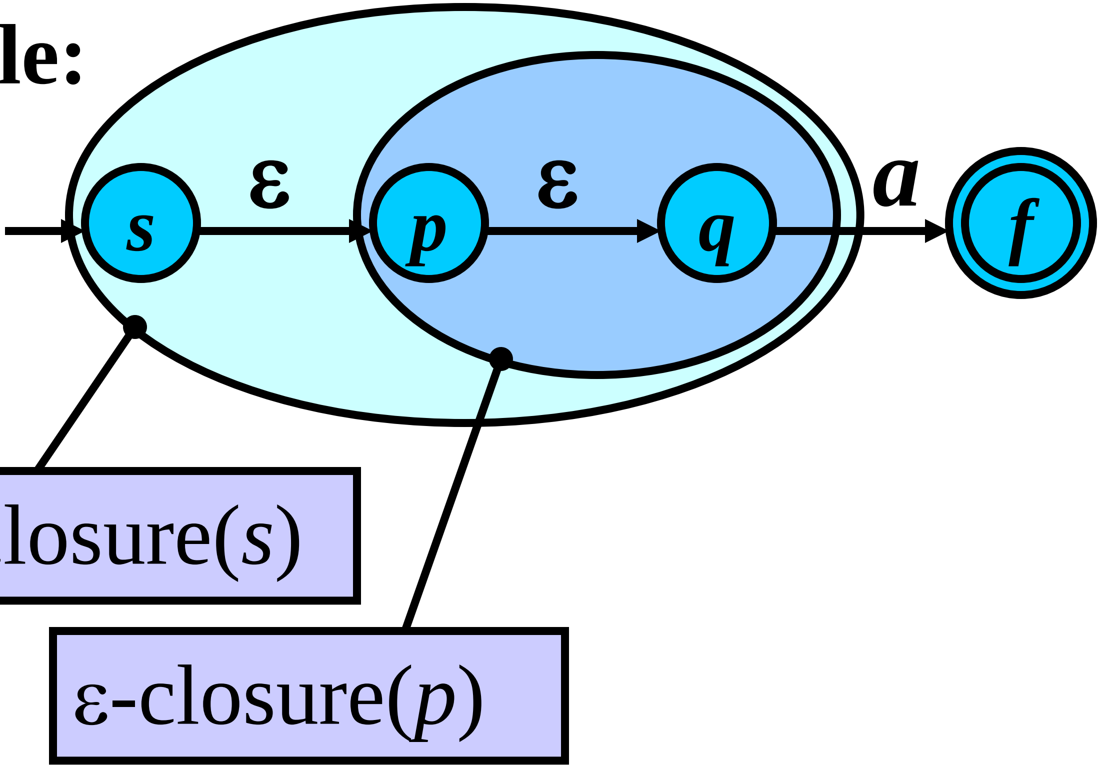


ε-closure

Gist: *q* is in ε-closure(*p*) if FA can reach *q* from *p* without reading.

Definition: For every states $p \in Q$, we define a set *ε-closure*(p) as ε-closure(p) = $\{q: q \in Q, p \vdash^* q\}$

Example:



ε-closure(*s*)

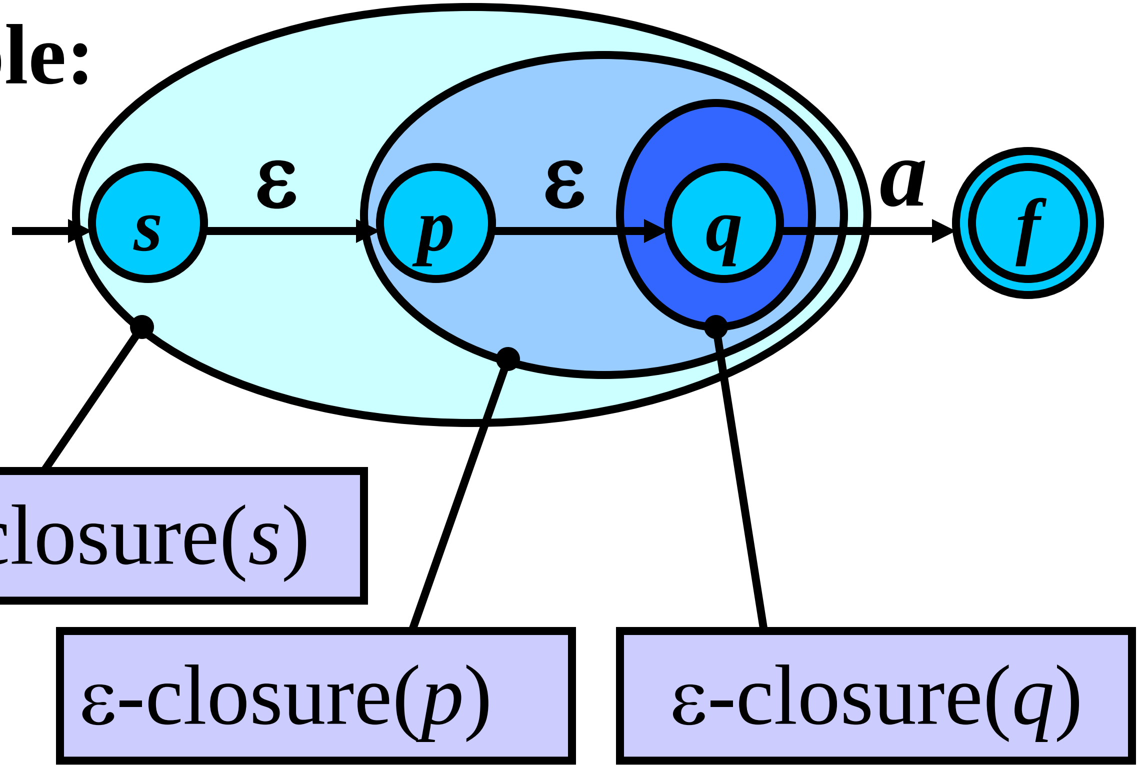
ε-closure(*p*)

ε-closure

Gist: *q* is in ε-closure(*p*) if FA can reach *q* from *p* without reading.

Definition: For every states $p \in Q$, we define a set *ε-closure*(p) as ε-closure(p) = $\{q: q \in Q, p \vdash^* q\}$

Example:



ε-closure(*s*)

ε-closure(*p*)

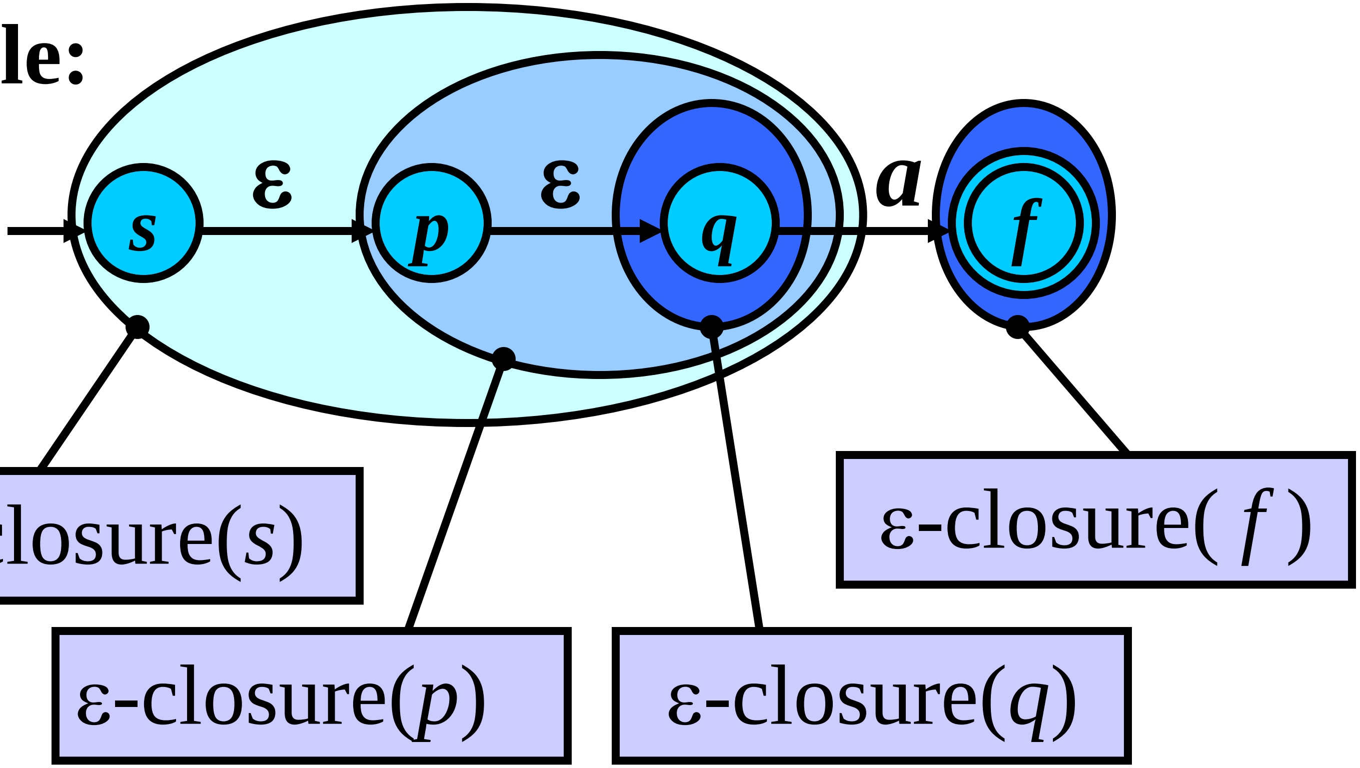
ε-closure(*q*)

ε-closure

Gist: q is in ε-closure(p) if FA can reach q from p without reading.

Definition: For every states $p \in Q$, we define a set *ε-closure*(p) as ε-closure(p) = $\{q: q \in Q, p \vdash^* q\}$

Example:



ε-closure(s)

ε-closure(p)

ε-closure(q)

ε-closure(f)

Algorithm: ε-closure

- **Input:** $M = (Q, \Sigma, R, s, F)$; $p \in Q$
- **Output:** ε-closure(p)

- **Method:**

```
• $i := 0$; $Q_0 := \{p\}$;
• repeat
        $i := i + 1$;
        $Q_i := Q_{i-1} \cup \{ p': p' \in Q, q \rightarrow p' \in R,$
                                  $q \in Q_{i-1} \}$;
until $Q_i = Q_{i-1}$;
• ε-closure($p$) := $Q_i$.
```

ε-closure: Example

$M = (Q, \Sigma, R, s, F)$, where: $Q = \{s, p, q, f\}$, $\Sigma = \{a\}$,
$R = \{s \rightarrow p, p \rightarrow q, qa \rightarrow f\}$, $F = \{f\}$

Task: ε-closure(s)

ε-closure: Example

$M = (Q, \Sigma, R, s, F)$, where: $Q = \{s, p, q, f\}$, $\Sigma = \{a\}$,
$R = \{s \rightarrow p, p \rightarrow q, qa \rightarrow f\}$, $F = \{f\}$

Task: ε-closure(s)

$Q_0 = \{\boldsymbol{s}\}$

ε-closure: Example

$M = (Q, \Sigma, R, s, F)$, where: $Q = \{s, p, q, f\}$, $\Sigma = \{a\}$,
$R = \{s \rightarrow p, p \rightarrow q, qa \rightarrow f\}$, $F = \{f\}$

Task: ε-closure(s)

$Q_0 = \{\mathbf{s}\}$

---

1) $\mathbf{s} \rightarrow p'; p' \in Q$: $\mathbf{s} \rightarrow \boldsymbol{p}$

$Q_1 = \{\mathbf{s}\} \cup \{\boldsymbol{p}\} = \{\mathbf{s}, \boldsymbol{p}\}$

ε-closure: Example

$M = (Q, \Sigma, R, s, F)$, where: $Q = \{s, p, q, f\}$, $\Sigma = \{a\}$,
$R = \{s \rightarrow p, p \rightarrow q, qa \rightarrow f\}$, $F = \{f\}$

Task: ε-closure(s)

$Q_0 = \{\mathbf{s}\}$

---

1) $\mathbf{s} \rightarrow p'; p' \in Q$: $\mathbf{s} \rightarrow \mathbf{p}$

$Q_1 = \{\mathbf{s}\} \cup \{\mathbf{p}\} = \{\mathbf{s}, \mathbf{p}\}$

---

2) $\mathbf{s} \rightarrow p'; p' \in Q$: $\mathbf{s} \rightarrow \mathbf{p}$

$\mathbf{p} \rightarrow p'; p' \in Q$: $\mathbf{p} \rightarrow \mathbf{q}$

$Q_2 = \{\mathbf{s}, \mathbf{p}\} \cup \{\mathbf{p}, \mathbf{q}\} = \{\mathbf{s}, \mathbf{p}, \mathbf{q}\}$

ε-closure: Example

$M = (Q, \Sigma, R, s, F)$, where: $Q = \{s, p, q, f\}$, $\Sigma = \{a\}$,
$R = \{s \rightarrow p, p \rightarrow q, qa \rightarrow f\}$, $F = \{f\}$

Task: ε-closure(s)

$Q_0 = \{\mathbf{s}\}$

---

1) $\mathbf{s} \rightarrow p'; p' \in Q$: $\mathbf{s} \rightarrow \mathbf{p}$

$Q_1 = \{\mathbf{s}\} \cup \{\mathbf{p}\} = \{\mathbf{s}, \mathbf{p}\}$

---

2) $\mathbf{s} \rightarrow p'; p' \in Q$: $\mathbf{s} \rightarrow \mathbf{p}$
$\mathbf{p} \rightarrow p'; p' \in Q$: $\mathbf{p} \rightarrow \mathbf{q}$

$Q_2 = \{\mathbf{s}, \mathbf{p}\} \cup \{\mathbf{p}, \mathbf{q}\} = \{\mathbf{s}, \mathbf{p}, \mathbf{q}\}$

---

3) $\mathbf{s} \rightarrow p'; p' \in Q$: $\mathbf{s} \rightarrow \mathbf{p}$
$\mathbf{p} \rightarrow p'; p' \in Q$: $\mathbf{p} \rightarrow \mathbf{q}$
$\mathbf{q} \rightarrow p'; p' \in Q$: **none**

$Q_3 = \{\mathbf{s}, \mathbf{p}, \mathbf{q}\} \cup \{\mathbf{p}, \mathbf{q}\} = \{\mathbf{s}, \mathbf{p}, \mathbf{q}\} = Q_2 =$ **ε-closure(s)**

Algorithm: FA to ε-free FA

Gist: Skip all ε-moves

- **Input:** FA $M = (Q, \Sigma, R, s, F)$
- **Output:** ε-free FA $M' = (Q, \Sigma, R', s, F')$

- **Method:**

```
• $R' := \emptyset$;
• for all $p \in Q$ do
        $R' := R' \cup \{ pa \rightarrow q: p'a \rightarrow q \in R, a \in \Sigma,$
                $p' \in \varepsilon\text{-closure}(p), q \in Q \}$;
• $F' := \{ p: p \in Q, \varepsilon\text{-closure}(p) \cap F \neq \emptyset \}$.
```

Algorithm: FA to ε-free FA

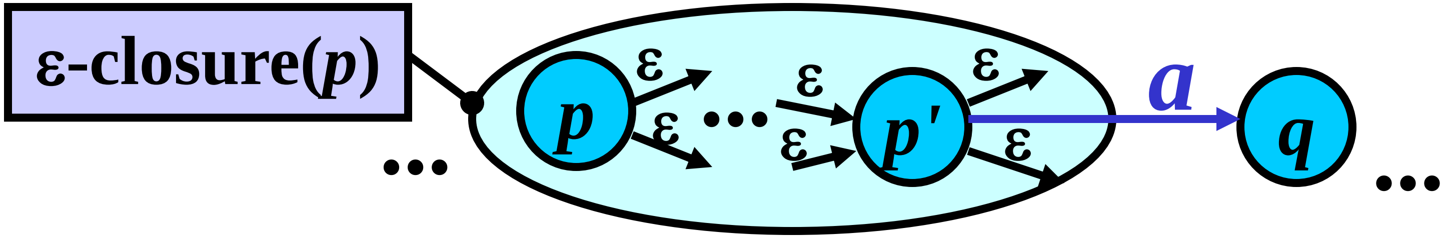
Gist: Skip all ε-moves

- **Input:** FA $M = (Q, \Sigma, R, s, F)$
- **Output:** ε-free FA $M' = (Q, \Sigma, R', s, F')$

- **Method:**
- $R' := \emptyset$;
- **for all** $p \in Q$ **do**

$$R' := R' \cup \{ pa \rightarrow q : p'a \rightarrow q \in R, a \in \Sigma, p' \in \varepsilon\text{-closure}(p), q \in Q \};$$

- $F' := \{ p : p \in Q, \varepsilon\text{-closure}(p) \cap F \neq \emptyset \}$.



Algorithm: FA to ε-free FA

Gist: Skip all ε-moves

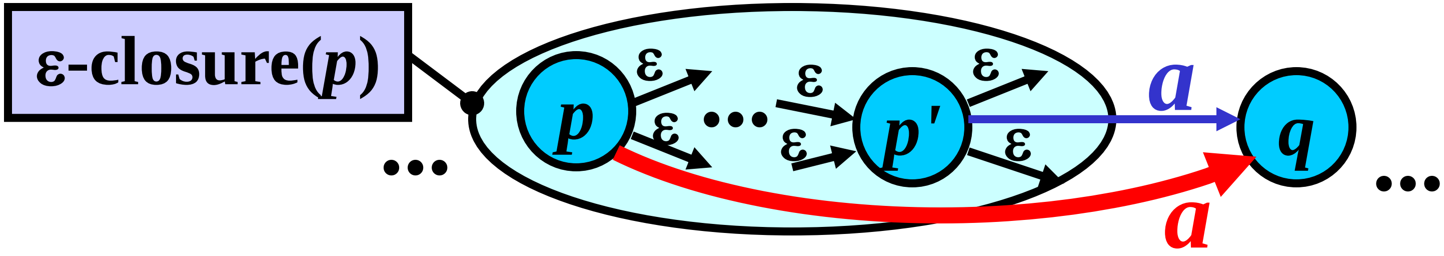
- **Input:** FA $M = (Q, \Sigma, R, s, F)$
- **Output:** ε-free FA $M' = (Q, \Sigma, R', s, F')$

- **Method:**
- $R' := \emptyset$;
- **for all** $p \in Q$ **do**

$$R' := R' \cup \{\, pa \rightarrow q: p'a \rightarrow q \in R,\ a \in \Sigma,\ p' \in \varepsilon\text{-closure}(p),\ q \in Q \,\};$$

- $F' := \{\, p: p \in Q,\ \varepsilon\text{-closure}(p) \cap F \neq \emptyset \,\}$.

ε-closure(*p*)



FA to ε-free FA: Example 1/3

$M = (Q, \Sigma, R, s, F)$, where:

$Q = \{s, q_1, q_2, f\}$; $\Sigma = \{a, b, c\}$;

$R = \{sa \rightarrow s, s \rightarrow q_1, q_1b \rightarrow q_1, q_1b \rightarrow f, s \rightarrow q_2,$
$q_2c \rightarrow q_2, q_2c \rightarrow f, fa \rightarrow f\}$; $F = \{f\}$

FA to ε-free FA: Example 1/3

$M = (Q, \Sigma, R, s, F)$, where:

$Q = \{s, q_1, q_2, f\}$; $\Sigma = \{a, b, c\}$;

$R = \{sa \to s, s \to q_1, q_1b \to q_1, q_1b \to f, s \to q_2,$
$q_2c \to q_2, q_2c \to f, fa \to f\}$; $F = \{f\}$

---

1) for $p = \mathbf{s}$: ε-closure($\mathbf{s}$) = $\{\mathbf{s}, \mathbf{q_1}, \mathbf{q_2}\}$

A. $\mathbf{s}d \to q', d \in \Sigma, q' \in Q$: $\mathbf{sa} \to \mathbf{s}$

B. $\mathbf{q_1}d \to q', d \in \Sigma, q' \in Q$: $\mathbf{q_1b} \to \mathbf{q_1}, \mathbf{q_1b} \to \mathbf{f}$

C. $\mathbf{q_2}d \to q', d \in \Sigma, q' \in Q$: $\mathbf{q_2c} \to \mathbf{q_2}, \mathbf{q_2c} \to \mathbf{f}$

$R' = \varnothing \cup \{\mathbf{sa} \to \mathbf{s}, \mathbf{sb} \to \mathbf{q_1}, \mathbf{sb} \to \mathbf{f}, \mathbf{sc} \to \mathbf{q_2}, \mathbf{sc} \to \mathbf{f}\}$

FA to ε-free FA: Example 2/3

FA to ε-free FA: Example 2/3

2) for p = q_1: ε-closure(q_1) = {q_1}

A. $q_1 d \rightarrow q'; d \in \Sigma; q' \in Q$: $q_1 b \rightarrow q_1$, $q_1 b \rightarrow f$

$R' = R' \cup \{q_1 b \rightarrow q_1, q_1 b \rightarrow f\}$

FA to ε-free FA: Example 2/3

2) for $p = q_1$: ε-closure(q_1) = {q_1}

A. $q_1 d \rightarrow q'; d \in \Sigma; q' \in Q$: $q_1 b \rightarrow q_1$, $q_1 b \rightarrow f$

$R' = R' \cup \{q_1 b \rightarrow q_1, q_1 b \rightarrow f\}$

---

3) for $p = q_2$: ε-closure(q_2) = {q_2}

A. $q_2 d \rightarrow q'; d \in \Sigma; q' \in Q$: $q_2 c \rightarrow q_2$, $q_2 c \rightarrow f$

$R' = R' \cup \{q_2 c \rightarrow q_2, q_2 c \rightarrow f\}$

FA to ε-free FA: Example 2/3

2) for p = $\boldsymbol{q_1}$: ε-closure($\boldsymbol{q_1}$) = {$\boldsymbol{q_1}$}

A. $q_1d \rightarrow q'; d \in \Sigma; q' \in Q$: $\boldsymbol{q_1b \rightarrow q_1}$, $\boldsymbol{q_1b \rightarrow f}$

$R' = R' \cup \{\boldsymbol{q_1b \rightarrow q_1}, \boldsymbol{q_1b \rightarrow f}\}$

---

3) for p = $\boldsymbol{q_2}$: ε-closure($\boldsymbol{q_2}$) = {$\boldsymbol{q_2}$}

A. $q_2d \rightarrow q'; d \in \Sigma; q' \in Q$: $\boldsymbol{q_2c \rightarrow q_2}$, $\boldsymbol{q_2c \rightarrow f}$

$R' = R' \cup \{\boldsymbol{q_2c \rightarrow q_2}, \boldsymbol{q_2c \rightarrow f}\}$

---

4) for p = $\boldsymbol{f}$: ε-closure($\boldsymbol{f}$) = {$\boldsymbol{f}$}

A. $fd \rightarrow q'; d \in \Sigma; q' \in Q$: $\boldsymbol{fa \rightarrow f}$

$R' = R' \cup \{\boldsymbol{fa \rightarrow f}\}$

FA to ε-free FA: Example 2/3

2) for $p = q_1$: ε-closure(q_1) = {q_1}

A. $q_1 d \to q'; d \in \Sigma; q' \in Q$: $q_1 b \to q_1$, $q_1 b \to f$

$R' = R' \cup \{q_1 b \to q_1, q_1 b \to f\}$

---

3) for $p = q_2$: ε-closure(q_2) = {q_2}

A. $q_2 d \to q'; d \in \Sigma; q' \in Q$: $q_2 c \to q_2$, $q_2 c \to f$

$R' = R' \cup \{q_2 c \to q_2, q_2 c \to f\}$

---

4) for $p = f$: ε-closure(f) = {f}

A. $fd \to q'; d \in \Sigma; q' \in Q$: $fa \to f$

$R' = R' \cup \{fa \to f\}$

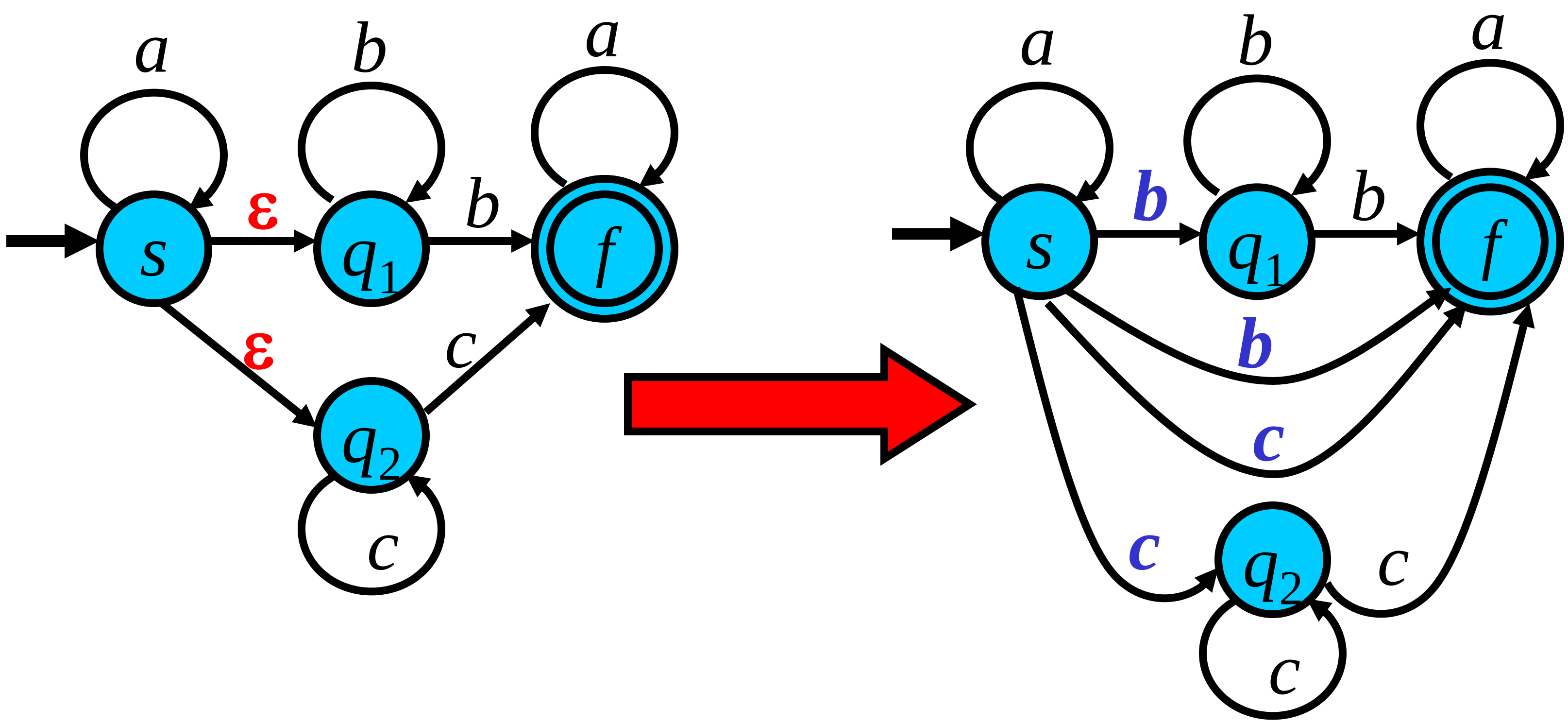
$R' = \{sa \to s, sb \to q_1, sb \to f, sc \to q_2, sc \to f,$
$q_1 b \to q_1, q_1 b \to f, q_2 c \to q_2, q_2 c \to f , fa \to f\}$

FA to ε-free FA: Example 3/3

$$\left.\begin{array}{l}
\varepsilon\text{-closure}(s) \cap F = \{s, q_1, q_2\} \cap \{f\} = \emptyset \\
\varepsilon\text{-closure}(q_1) \cap F = \{q_1\} \cap \{f\} = \emptyset \\
\varepsilon\text{-closure}(q_2) \cap F = \{q_2\} \cap \{f\} = \emptyset \\
\varepsilon\text{-closure}(f) \cap F = \{ f \} \cap \{f\} = \{f\} \neq \emptyset
\end{array}\right\} \boldsymbol{F'} = \{f\}$$

FA to ε-free FA: Example 3/3

$$\left.\begin{array}{ll} \varepsilon\text{-closure}(s) \cap F = \{s, q_1, q_2\} \cap \{f\} & = \emptyset \\ \varepsilon\text{-closure}(q_1) \cap F = \{q_1\} \cap \{f\} & = \emptyset \\ \varepsilon\text{-closure}(q_2) \cap F = \{q_2\} \cap \{f\} & = \emptyset \\ \varepsilon\text{-closure}(f) \cap F = \{f\} \cap \{f\} = \{f\} & \neq \emptyset \end{array}\right\} \boldsymbol{F'} = \{f\}$$



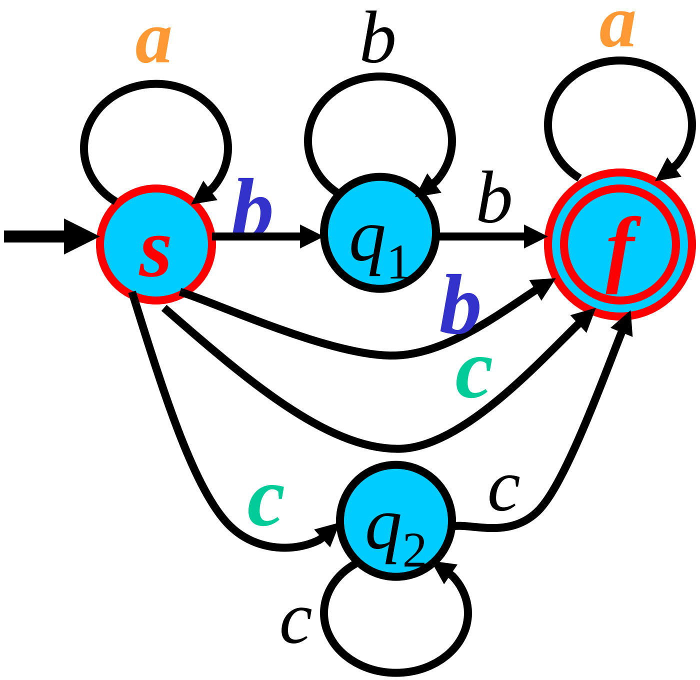
Algorithm: ε-free FA to DFA 1/2

Gist: **In DFA, make states from all subsets of states in ε-free FA and move between them so that all possible states of ε-free FA are simultaneously simulated.**

Algorithm: ε-free FA to DFA 1/2

Gist: In DFA, make states from all subsets of states in ε-free FA and move between them so that all possible states of ε-free FA are <u>simultaneously</u> simulated.

Illustration:

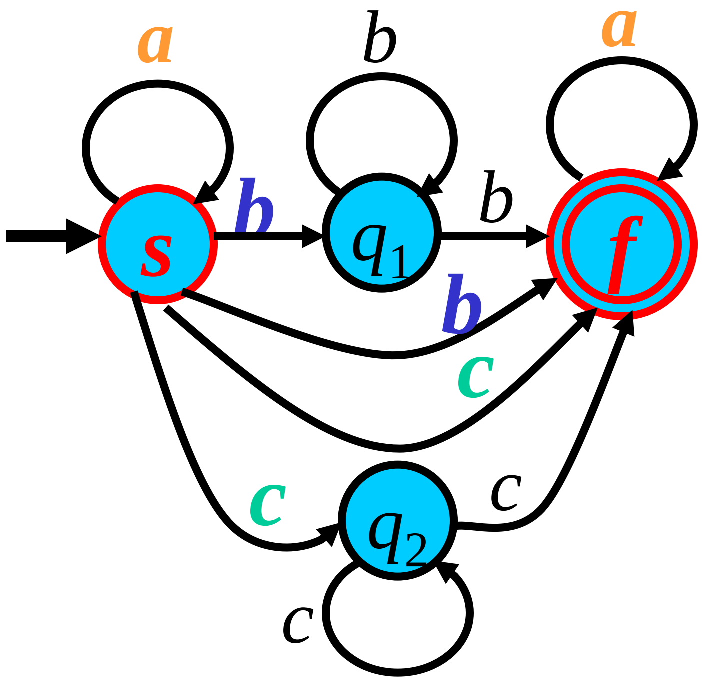


$Q_{DFA} = \{\{s\}, \{q_1\}, \{q_2\}, \{f\}, \{s,q_1\}, \{s,q_2\}, \{s, f\}, \{q_1,q_2\}, \{q_1, f\}, \{q_2, f\}, \{s,q_1,q_2\}, \{s,q_1, f\}, \{s,q_2, f\}, \{q_1,q_2, f\}, \{s,q_1,q_2, f\}\}$

Algorithm: ε-free FA to DFA 1/2

Gist: In DFA, make states from all subsets of states in ε-free FA and move between them so that all possible states of ε-free FA are simultaneously simulated.

Illustration:



$Q_{DFA} = \{\{s\}, \{q_1\}, \{q_2\}, \{f\}, \{s,q_1\}, \{s,q_2\}, \{s, f\}, \{q_1,q_2\}, \{q_1, f\}, \{q_2, f\}, \{s,q_1,q_2\}, \{s,q_1, f\}, \{s,q_2, f\}, \{q_1,q_2, f\}, \{s,q_1,q_2, f\}\}$

For state {*s*}: …

⋮

For state {*s*, *f*}: {*s*, *f*}

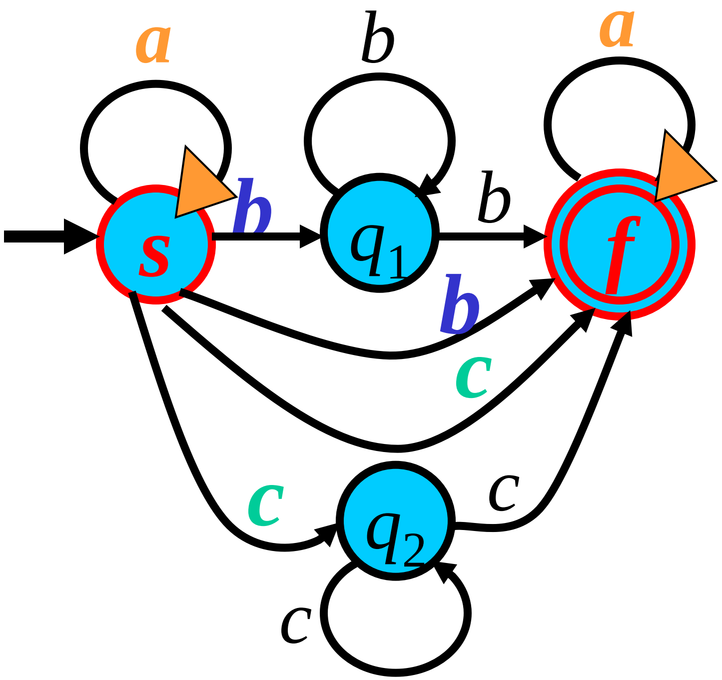
⋮

For state {s,q_1,q_2, f}: …

Algorithm: ε-free FA to DFA 1/2

Gist: In DFA, make states from all subsets of states in ε-free FA and move between them so that all possible states of ε-free FA are simultaneously simulated.

Illustration:

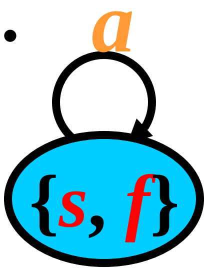


$Q_{DFA} = \{\{s\}, \{q_1\}, \{q_2\}, \{f\}, \{s,q_1\}, \{s,q_2\}, \{s, f\}, \{q_1,q_2\}, \{q_1, f\}, \{q_2, f\}, \{s,q_1,q_2\}, \{s,q_1, f\}, \{s,q_2, f\}, \{q_1,q_2, f\}, \{s,q_1,q_2, f\}\}$

For state {*s*}: …

⋮

For state {*s*, *f*}:



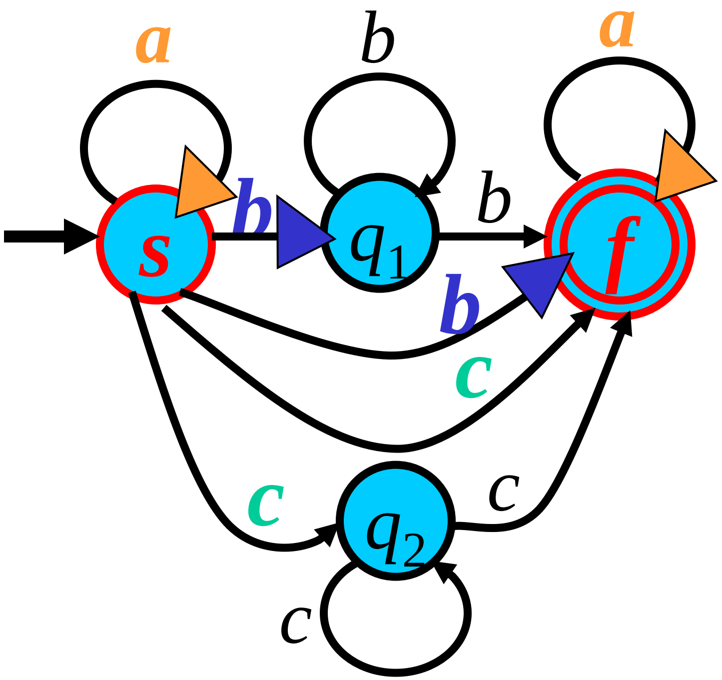
⋮

For state {*s*,*q*$_1$,*q*$_2$, *f*}: …

Algorithm: ε-free FA to DFA 1/2

Gist: In DFA, make states from all subsets of states in ε-free FA and move between them so that all possible states of ε-free FA are simultaneously simulated.

Illustration:

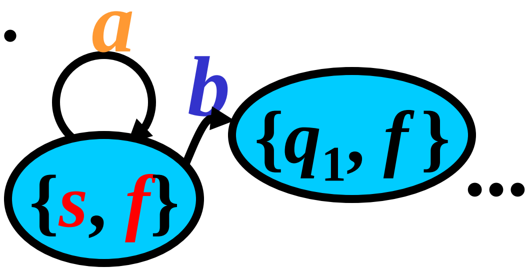


Q_{DFA} = $\{\{s\}, \{q_1\}, \{q_2\}, \{f\}, \{s,q_1\}, \{s,q_2\}, \{s, f\}, \{q_1,q_2\}, \{q_1, f\}, \{q_2, f\}, \{s,q_1,q_2\}, \{s,q_1, f\}, \{s,q_2, f\}, \{q_1,q_2, f\}, \{s,q_1,q_2, f\}\}$

For state {*s*}: …

⋮

For state {*s*, *f*}:



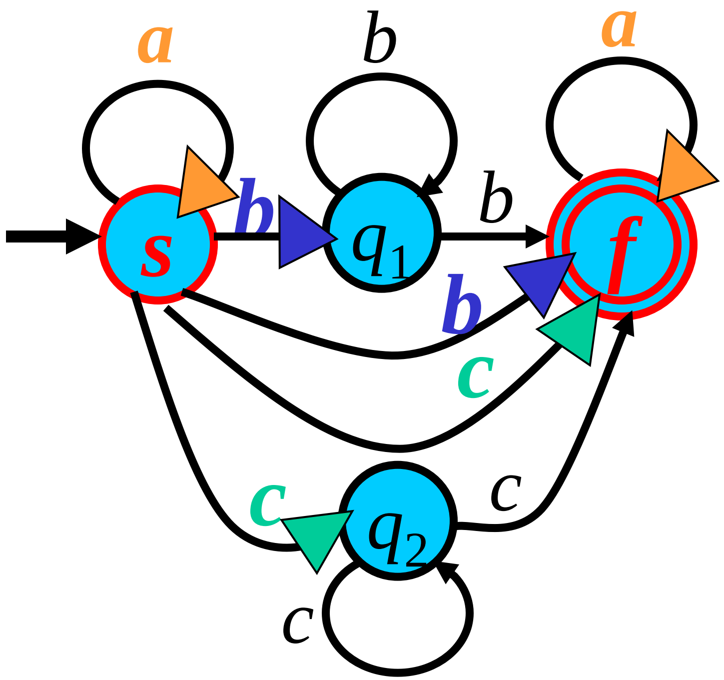
⋮

For state {*s*,*q*$_1$,*q*$_2$, *f*}: …

Algorithm: ε-free FA to DFA 1/2

Gist: **In DFA, make states from all subsets of states in ε-free FA and move between them so that all possible states of ε-free FA are simultaneously simulated.**

Illustration:

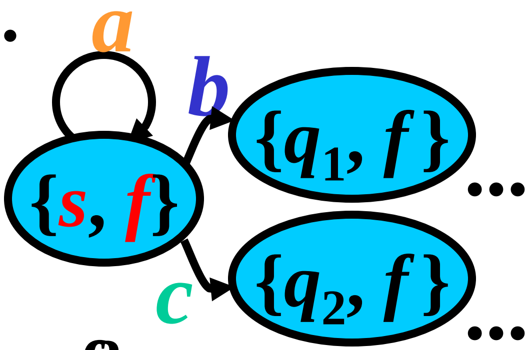


$Q_{DFA} = \{\{s\}, \{q_1\}, \{q_2\}, \{f\}, \{s,q_1\}, \{s,q_2\}, \{s, f\}, \{q_1,q_2\}, \{q_1, f\}, \{q_2, f\}, \{s,q_1,q_2\}, \{s,q_1, f\}, \{s,q_2, f\}, \{q_1,q_2, f\}, \{s,q_1,q_2, f\}\}$

For state {*s*}: …

⋮

For state {*s*, *f*}:



⋮

For state {*s*,q_1,q_2, *f*}: …

Algorithm: ε-free FA to DFA 2/2

- **Input:** ε-free FA: $M = (Q, \Sigma, R, s, F)$
- **Output:** DFA: $M_d = (Q_d, \Sigma, R_d, s_d, F_d)$

- **Method:**

```
• $Q_d := \{Q': Q' \subseteq Q, Q' \neq \emptyset\}; R_d := \emptyset;$
• for each $Q' \in Q_d$, and $a \in \Sigma$ do begin
        $Q'' := \{q: p \in Q', pa \rightarrow q \in R\};$
        if $Q'' \neq \emptyset$ then $R_d := R_d \cup \{Q'a \rightarrow Q''\};$
  end
• $s_d := \{s\};$
• $F_d := \{F': F' \in Q_d, F' \cap F \neq \emptyset\}.$
```

ε-free FA to DFA: Example 1/5

$M = (Q, \Sigma, R, s, F)$, where:

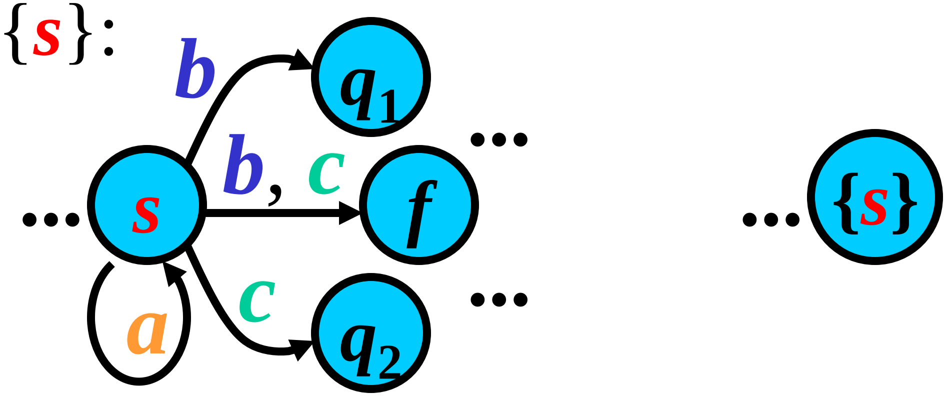
$Q = \{s, q_1, q_2, f\}$; $\Sigma = \{a, b, c\}$; $F = \{f\}$

$R = \{sa \rightarrow s, sb \rightarrow q_1, sb \rightarrow f, sc \rightarrow q_2, sc \rightarrow f,$
$q_1b \rightarrow q_1, q_1b \rightarrow f, q_2c \rightarrow q_2, q_2c \rightarrow f, fa \rightarrow f\}$;

$Q_d = \{\{s\}, \{s,q_1\}, \{s,q_1,q_2\}, \{s,q_1, f\}, \{s,q_1,q_2, f\}, \{s,q_2\}, \{s,q_2, f\},$
$\{s, f\}, \{q_1\}, \{q_1,q_2\}, \{q_1, f\}, \{q_1,q_2, f\}, \{q_2\}, \{q_2, f\}, \{f\}\}$

---

for $Q' = \{s\}$:



ε-free FA to DFA: Example 1/5

$M = (Q, \Sigma, R, s, F)$, where:

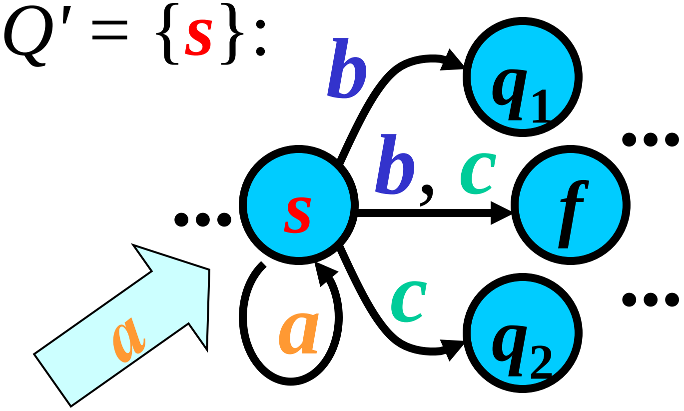
$Q = \{s, q_1, q_2, f\}$; $\Sigma = \{a, b, c\}$; $F = \{f\}$

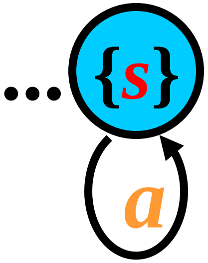
$R = \{sa \to s, sb \to q_1, sb \to f, sc \to q_2, sc \to f,$
$q_1b \to q_1, q_1b \to f, q_2c \to q_2, q_2c \to f, fa \to f\}$;

$Q_d = \{\{s\}, \{s,q_1\}, \{s,q_1,q_2\}, \{s,q_1, f\}, \{s,q_1,q_2, f\}, \{s,q_2\}, \{s,q_2, f\},$
$\{s, f\}, \{q_1\}, \{q_1,q_2\}, \{q_1, f\}, \{q_1,q_2, f\}, \{q_2\}, \{q_2, f\}, \{f\}\}$

---

for $Q' = \{s\}$:





ε-free FA to DFA: Example 1/5

$M = (Q, \Sigma, R, s, F)$, where:

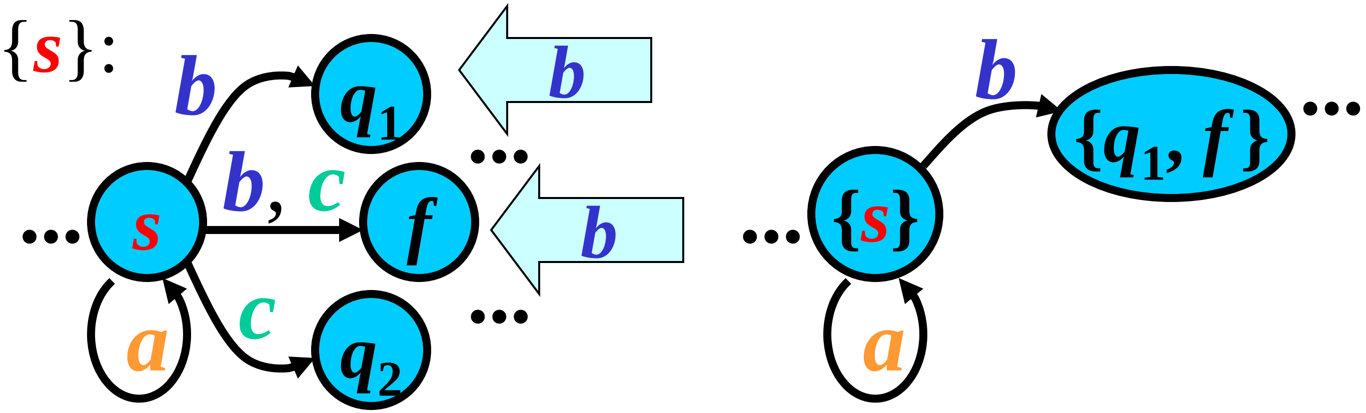
$Q = \{s, q_1, q_2, f\}$; $\Sigma = \{a, b, c\}$; $F = \{f\}$

$R = \{sa \rightarrow s, sb \rightarrow q_1, sb \rightarrow f, sc \rightarrow q_2, sc \rightarrow f,$
$q_1b \rightarrow q_1, q_1b \rightarrow f, q_2c \rightarrow q_2, q_2c \rightarrow f, fa \rightarrow f\};$

$Q_d = \{\{s\}, \{s,q_1\}, \{s,q_1,q_2\}, \{s,q_1, f\}, \{s,q_1,q_2, f\}, \{s,q_2\}, \{s,q_2, f\},$
$\{s, f\}, \{q_1\}, \{q_1,q_2\}, \{q_1, f\}, \{q_1,q_2, f\}, \{q_2\}, \{q_2, f\}, \{f\}\}$

---

for $Q' = \{s\}$:



ε-free FA to DFA: Example 1/5

$M = (Q, \Sigma, R, s, F)$, where:

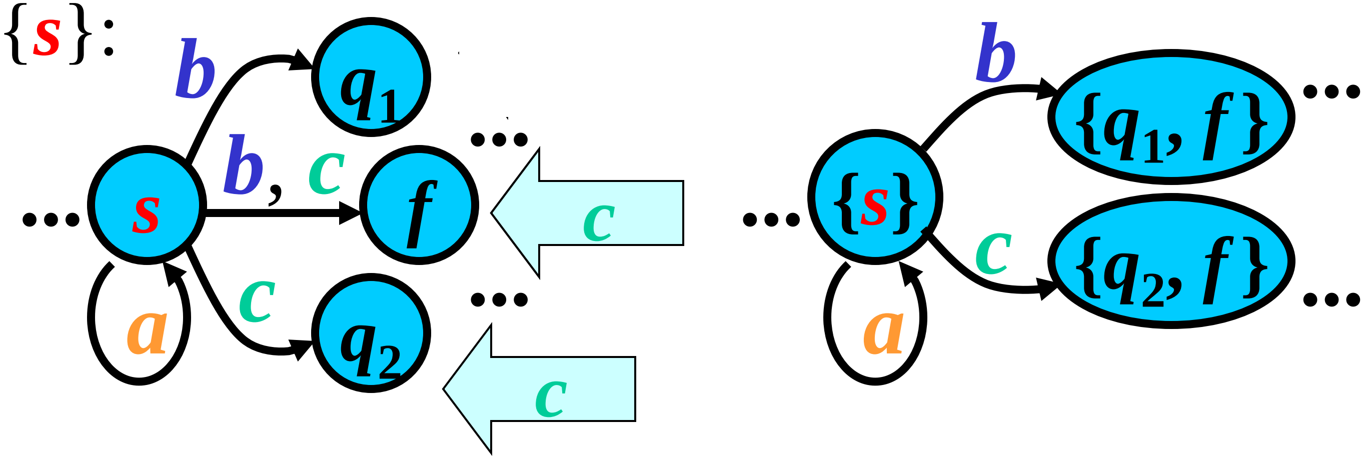
$Q = \{s, q_1, q_2, f\}$; $\Sigma = \{a, b, c\}$; $F = \{f\}$

$R = \{sa \rightarrow s, sb \rightarrow q_1, sb \rightarrow f, sc \rightarrow q_2, sc \rightarrow f,$
$q_1b \rightarrow q_1, q_1b \rightarrow f, q_2c \rightarrow q_2, q_2c \rightarrow f, fa \rightarrow f\}$;

$Q_d =$ **{**$\{s\}, \{s,q_1\}, \{s,q_1,q_2\}, \{s,q_1, f\}, \{s,q_1,q_2, f\}, \{s,q_2\}, \{s,q_2, f\},$
$\{s, f\}, \{q_1\}, \{q_1,q_2\}, \{q_1, f\}, \{q_1,q_2, f\}, \{q_2\}, \{q_2, f\}, \{f\}$**}**

---

for $Q' = \{s\}$:



ε-free FA to DFA: Example 1/5

$M = (Q, \Sigma, R, s, F)$, where:

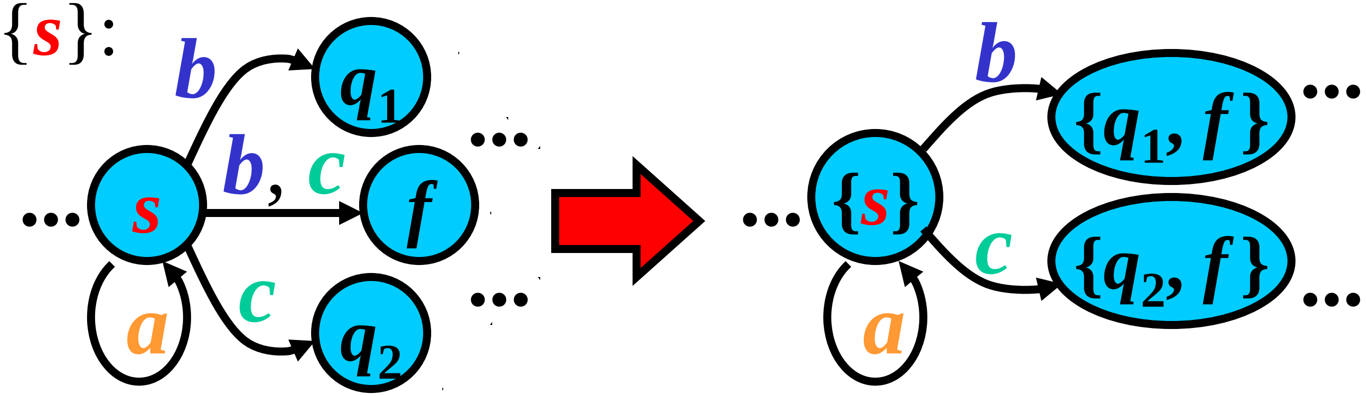
$Q = \{s, q_1, q_2, f\}$; $\Sigma = \{a, b, c\}$; $F = \{f\}$

$R = \{sa \rightarrow s, sb \rightarrow q_1, sb \rightarrow f, sc \rightarrow q_2, sc \rightarrow f,$
$q_1b \rightarrow q_1, q_1b \rightarrow f, q_2c \rightarrow q_2, q_2c \rightarrow f, fa \rightarrow f\}$;

$Q_d = \mathbf{\{}\{s\}, \{s,q_1\}, \{s,q_1,q_2\}, \{s,q_1, f\}, \{s,q_1,q_2, f\}, \{s,q_2\}, \{s,q_2, f\},$
$\{s, f\}, \{q_1\}, \{q_1,q_2\}, \{q_1, f\}, \{q_1,q_2, f\}, \{q_2\}, \{q_2, f\}, \{f\}\mathbf{\}}$

---

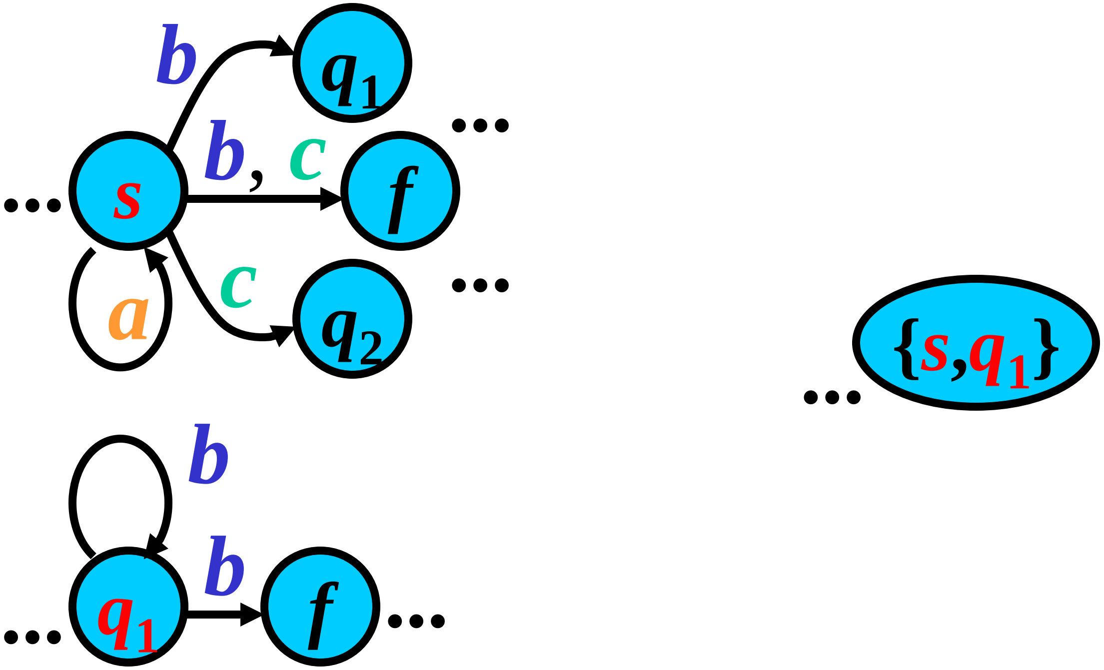
for $Q' = \{\mathbf{s}\}$:



$R_d = \varnothing \cup \mathbf{\{\{s\}a \rightarrow \{s\}, \{s\}b \rightarrow \{q_1, f\}, \{s\}c \rightarrow \{q_2, f\}\}}$

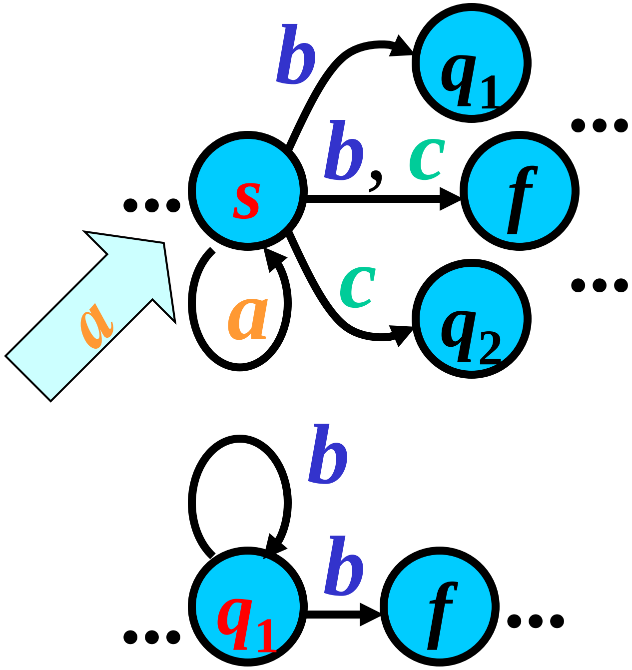
ε-free FA to DFA: Example 2/5

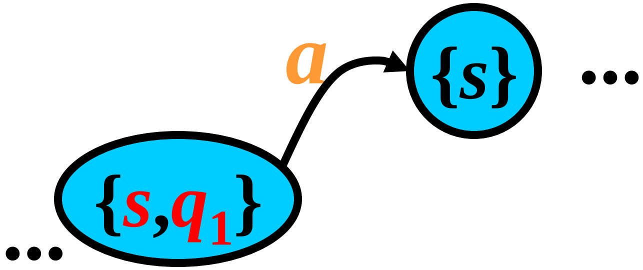
for $Q' = \{s, q_1\}$:



ε-free FA to DFA: Example 2/5

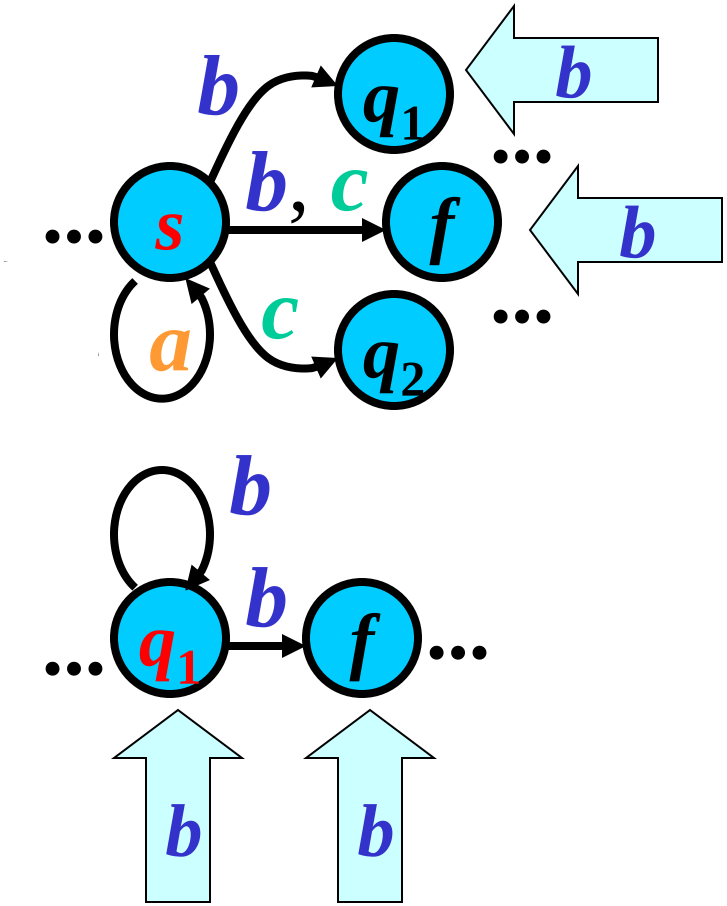
for $Q' = \{s, q_1\}$:

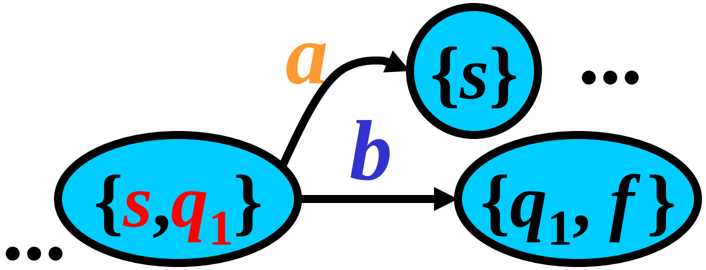




ε-free FA to DFA: Example 2/5

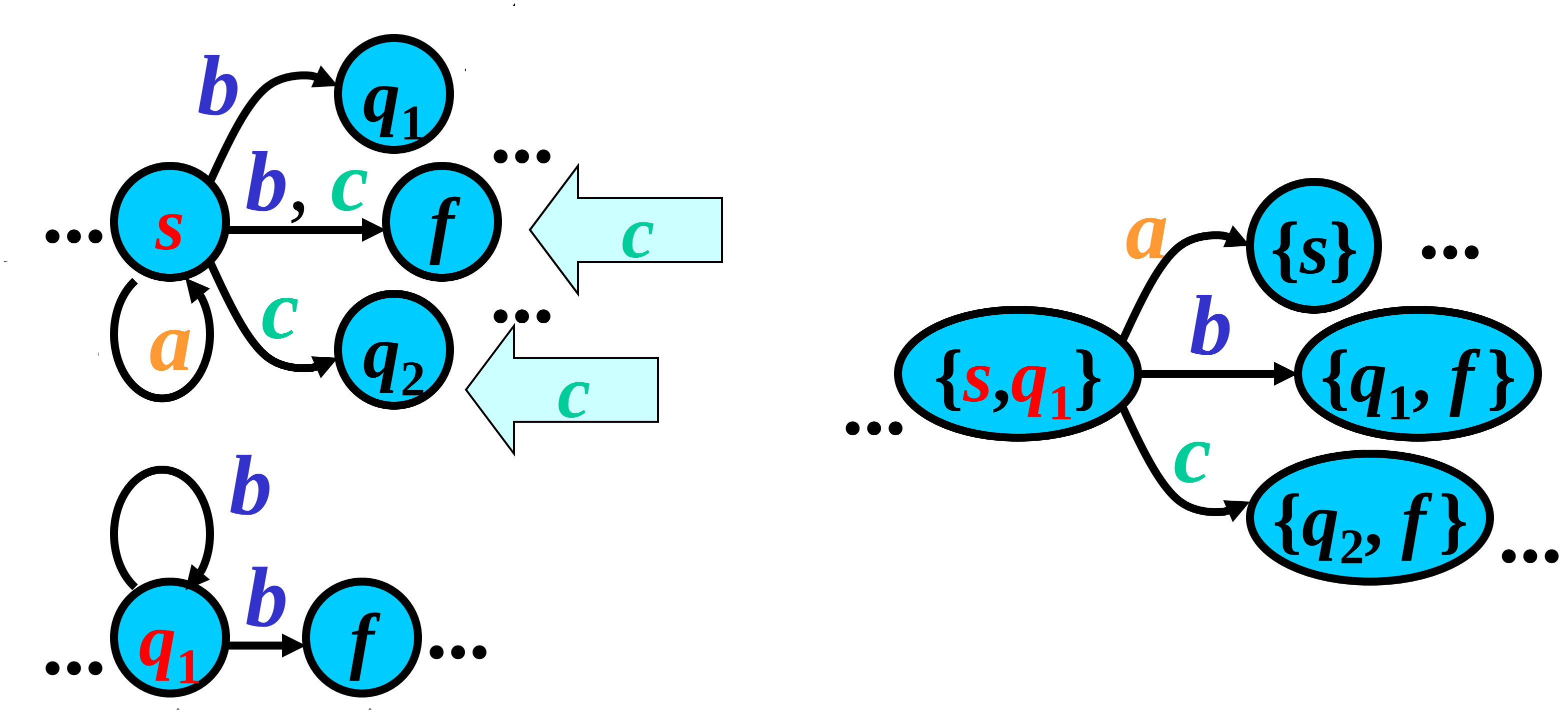
for $Q' = \{s, q_1\}$:





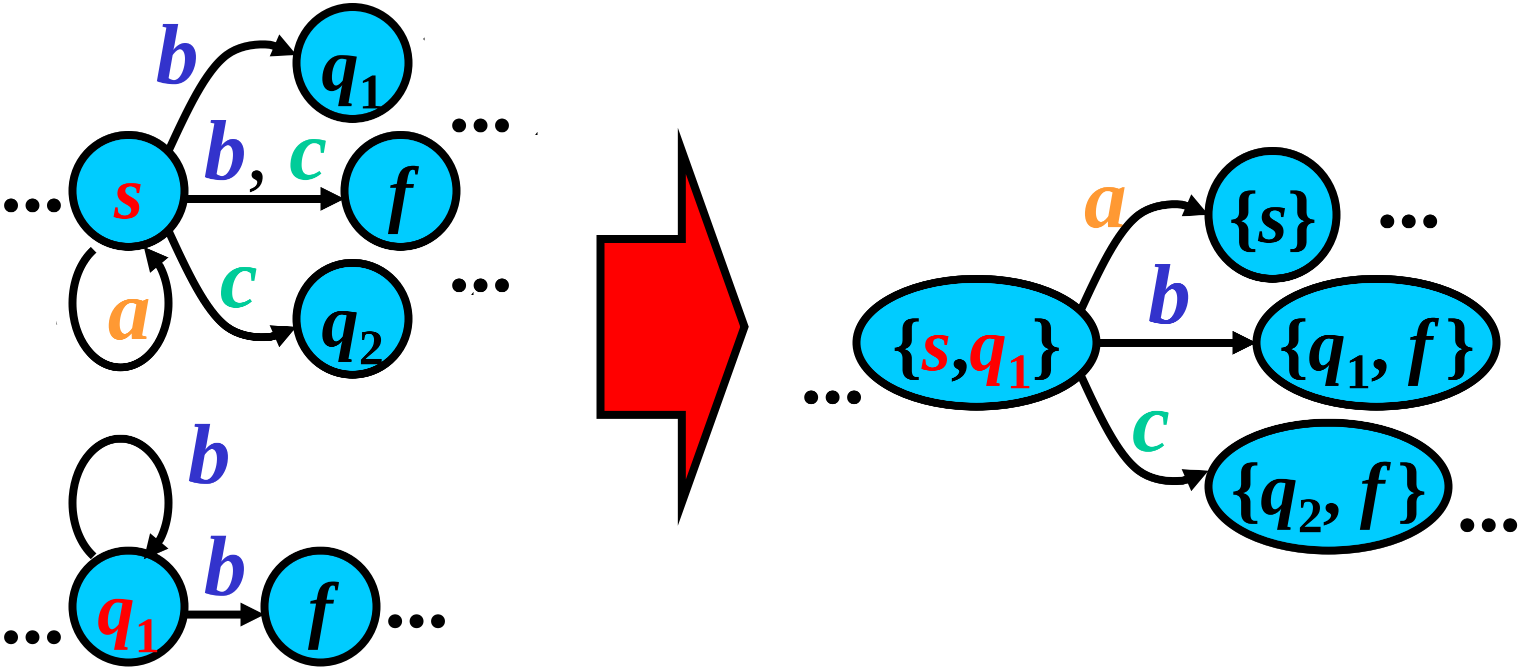
ε-free FA to DFA: Example 2/5

for $Q' = \{s, q_1\}$:



ε-free FA to DFA: Example 2/5

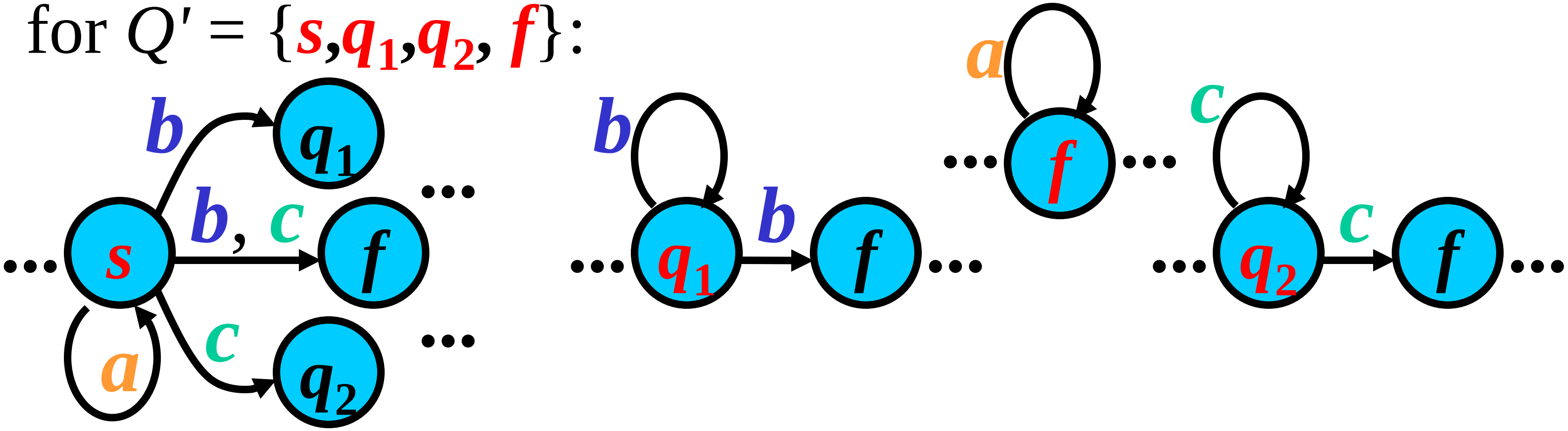
for $Q' = \{s, q_1\}$:



$R_d = R_d \cup \{\{s,q_1\}a \rightarrow \{s\},\ \{s,q_1\}b \rightarrow \{q_1, f\},\ \{s,q_1\}c \rightarrow \{q_2, f\}\}$

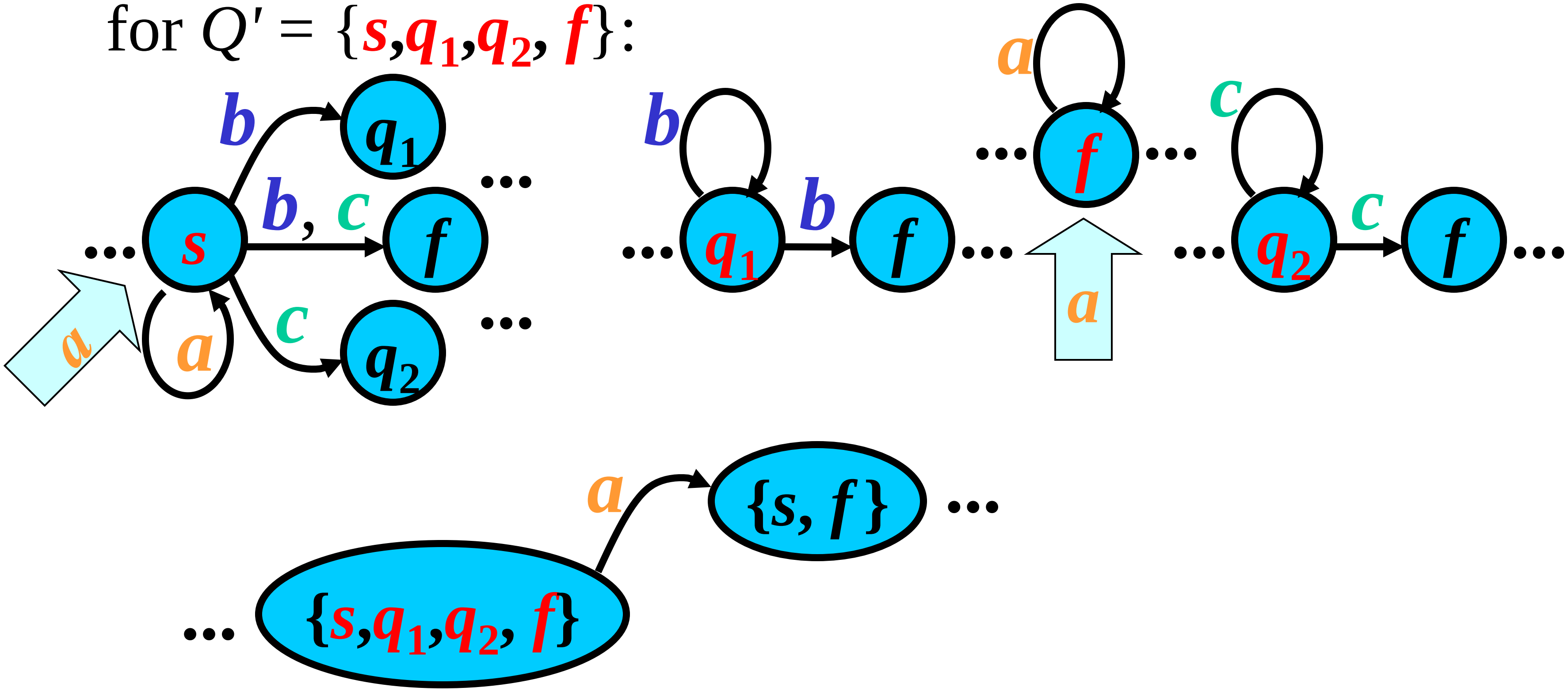
ε-free FA to DFA: Example 3/5

for $Q' = \{s, q_1, q_2, f\}$:



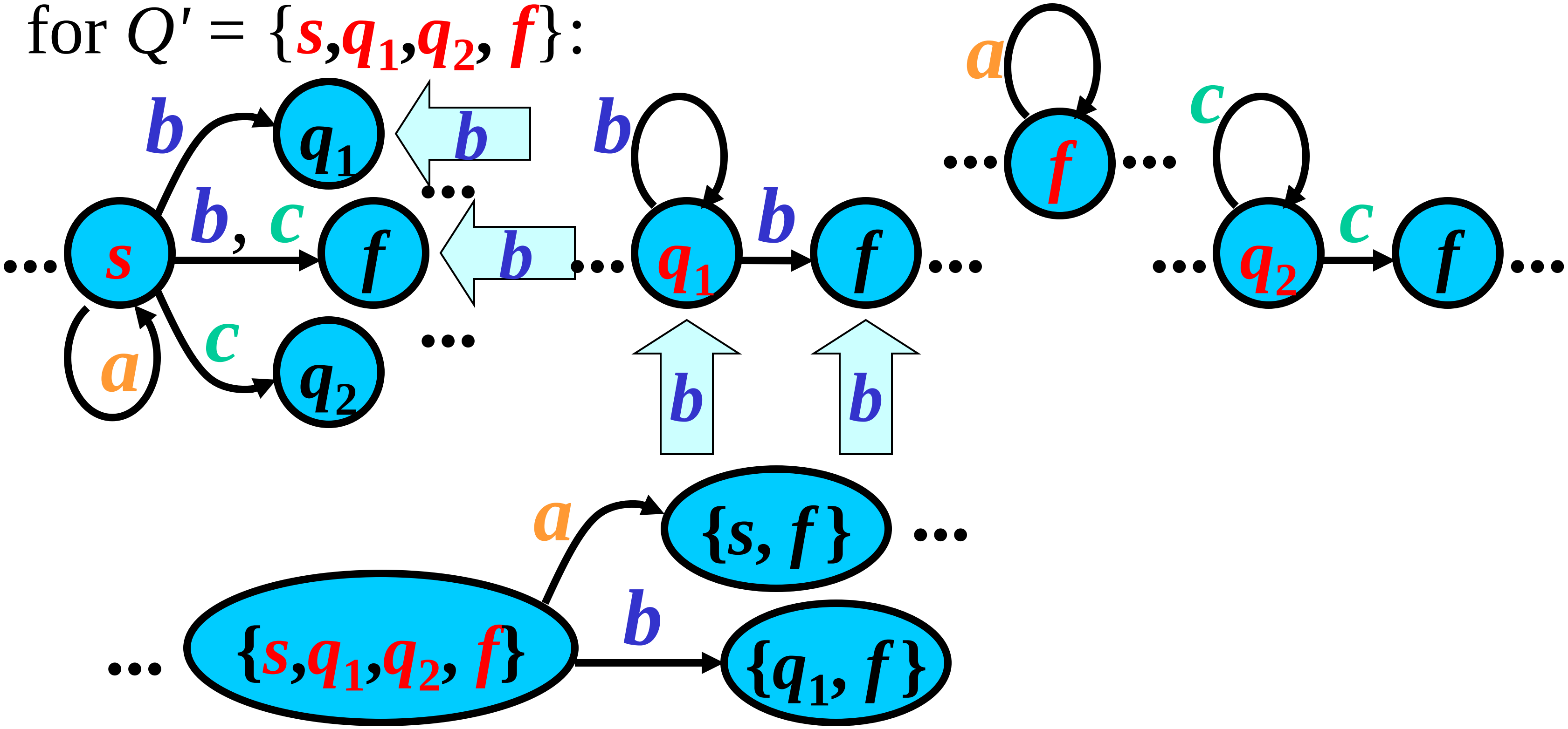
ε-free FA to DFA: Example 3/5

for $Q' = \{s, q_1, q_2, f\}$:



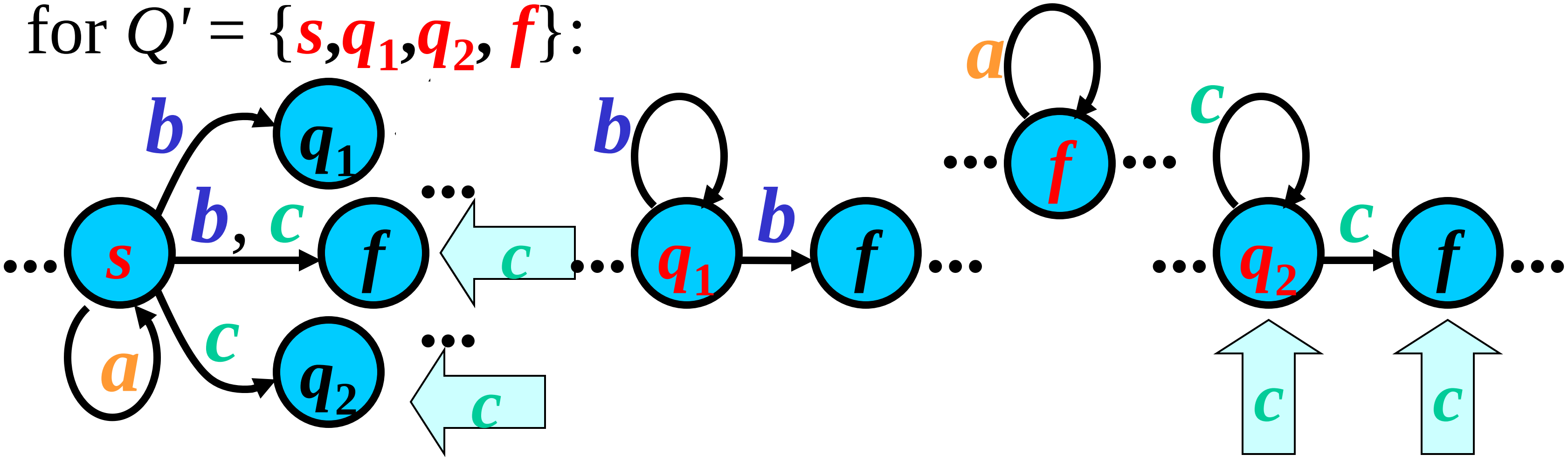
ε-free FA to DFA: Example 3/5

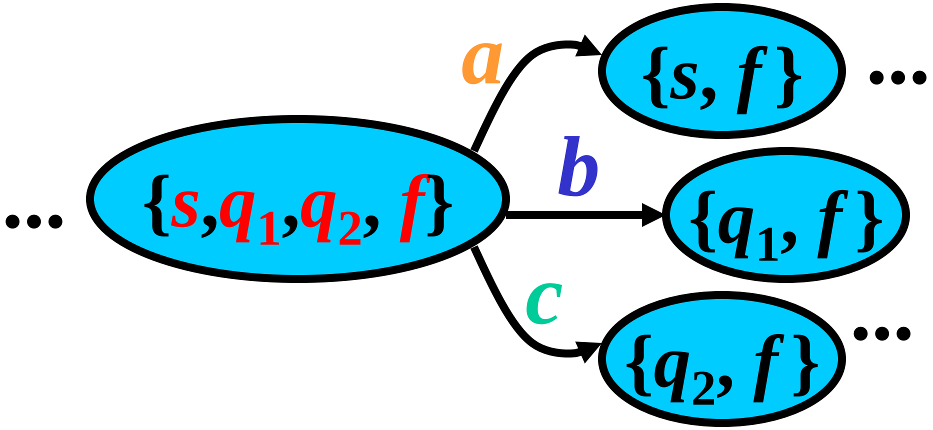
for $Q' = \{s, q_1, q_2, f\}$:



ε-free FA to DFA: Example 3/5

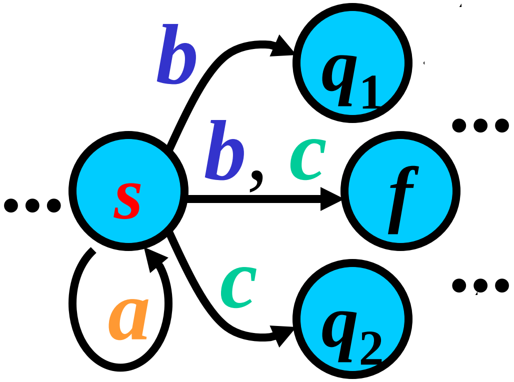
for $Q' = \{s, q_1, q_2, f\}$:

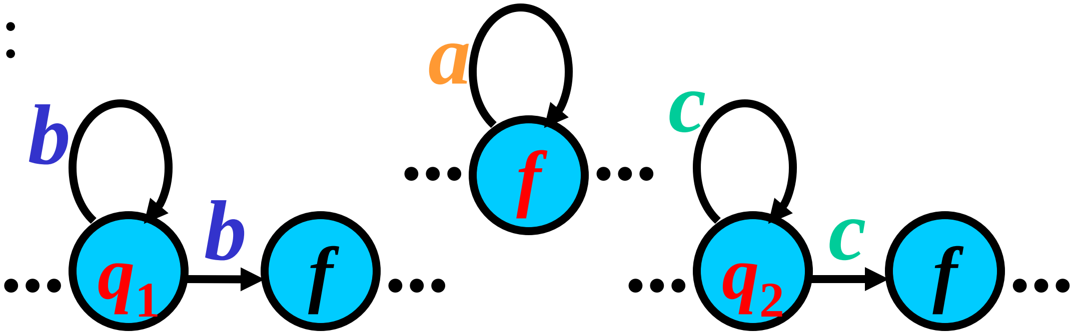


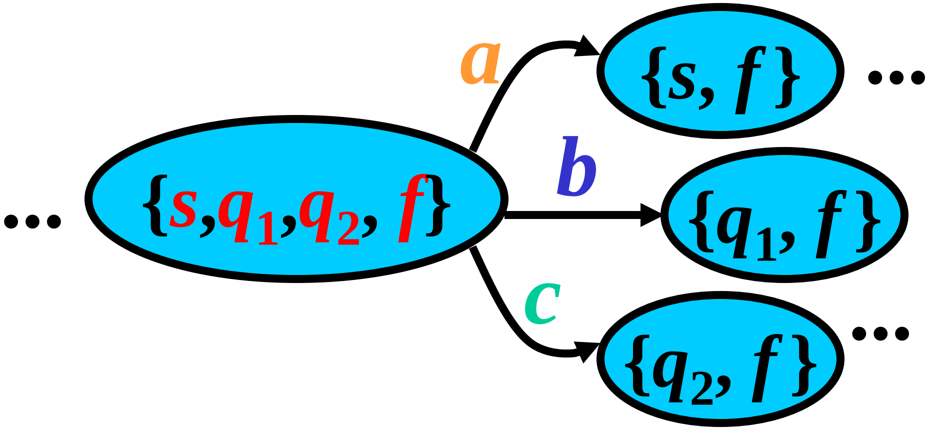


ε-free FA to DFA: Example 3/5

for $Q' = \{s, q_1, q_2, f\}$:







Construct the other states analogically…

$$R_d = R_d \cup \{\{s,q_1,q_2, f\}a \rightarrow \{s, f\}, \{s,q_1,q_2, f\}b \rightarrow \{q_1, f\}, \{s,q_1,q_2, f\}c \rightarrow \{q_2, f\}\}$$

ε-free FA to DFA: Example 4/5

Final states: $F_d := \{F': F' \in Q_d, F' \cap F \neq \emptyset\}$

for $F = \{f\}$:

$\{s\} \cap \{f\} = \emptyset \quad \Rightarrow \quad \{s\} \notin F_d$

$\{s,q_1\} \cap \{f\} = \emptyset \quad \Rightarrow \quad \{s,q_1\} \notin F_d$

$\{s,q_1,q_2\} \cap \{f\} = \emptyset \quad \Rightarrow \quad \{s,q_1,q_2\} \notin F_d$

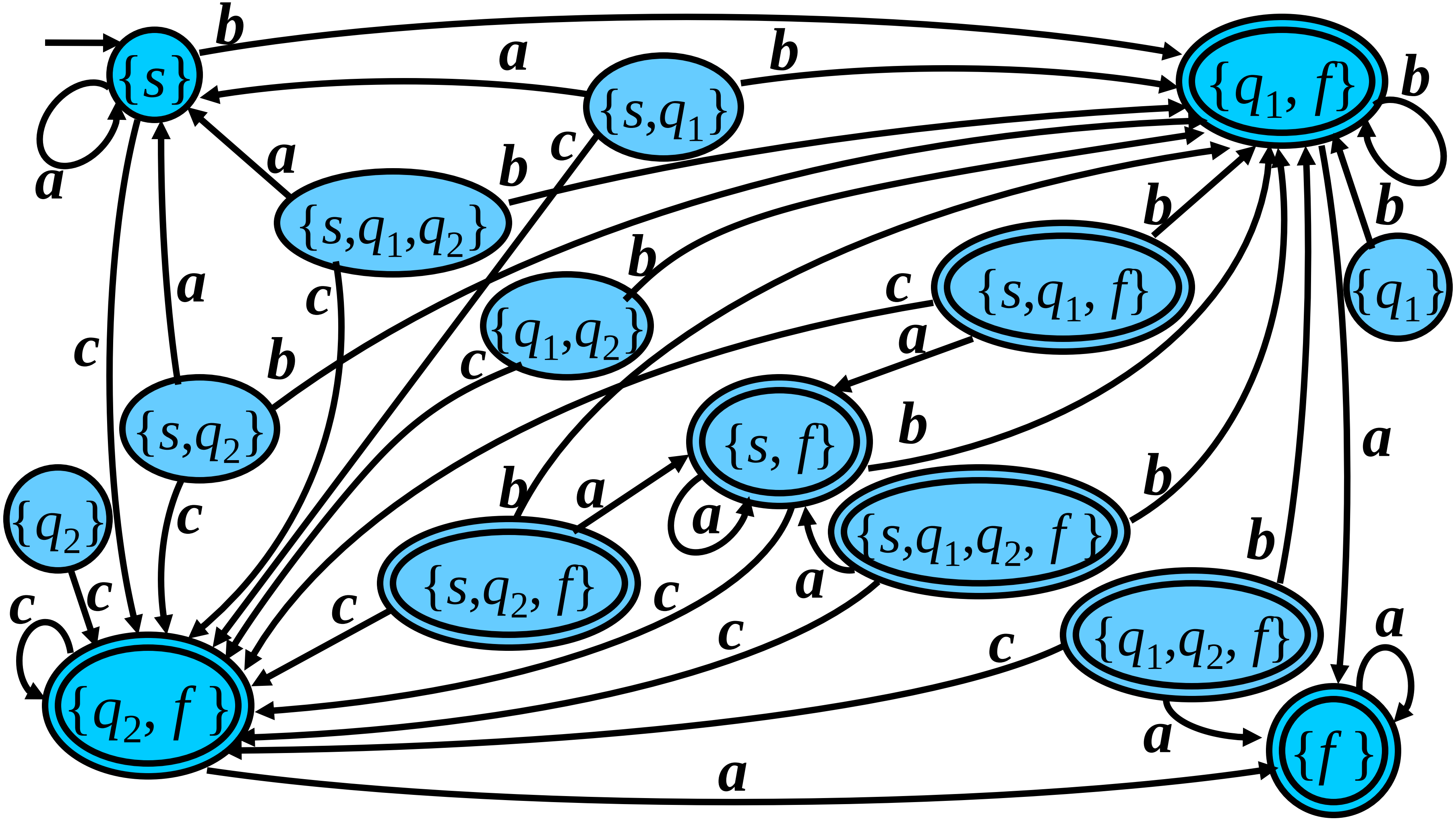
$\{s,q_1,f\} \cap \{f\} = \{f\} \neq \emptyset \quad \Rightarrow \quad \{s,q_1,f\} \in F_d$

$\{s,q_1,q_2,f\} \cap \{f\} = \{f\} \neq \emptyset \quad \Rightarrow \quad \{s,q_1,q_2,f\} \in F_d$

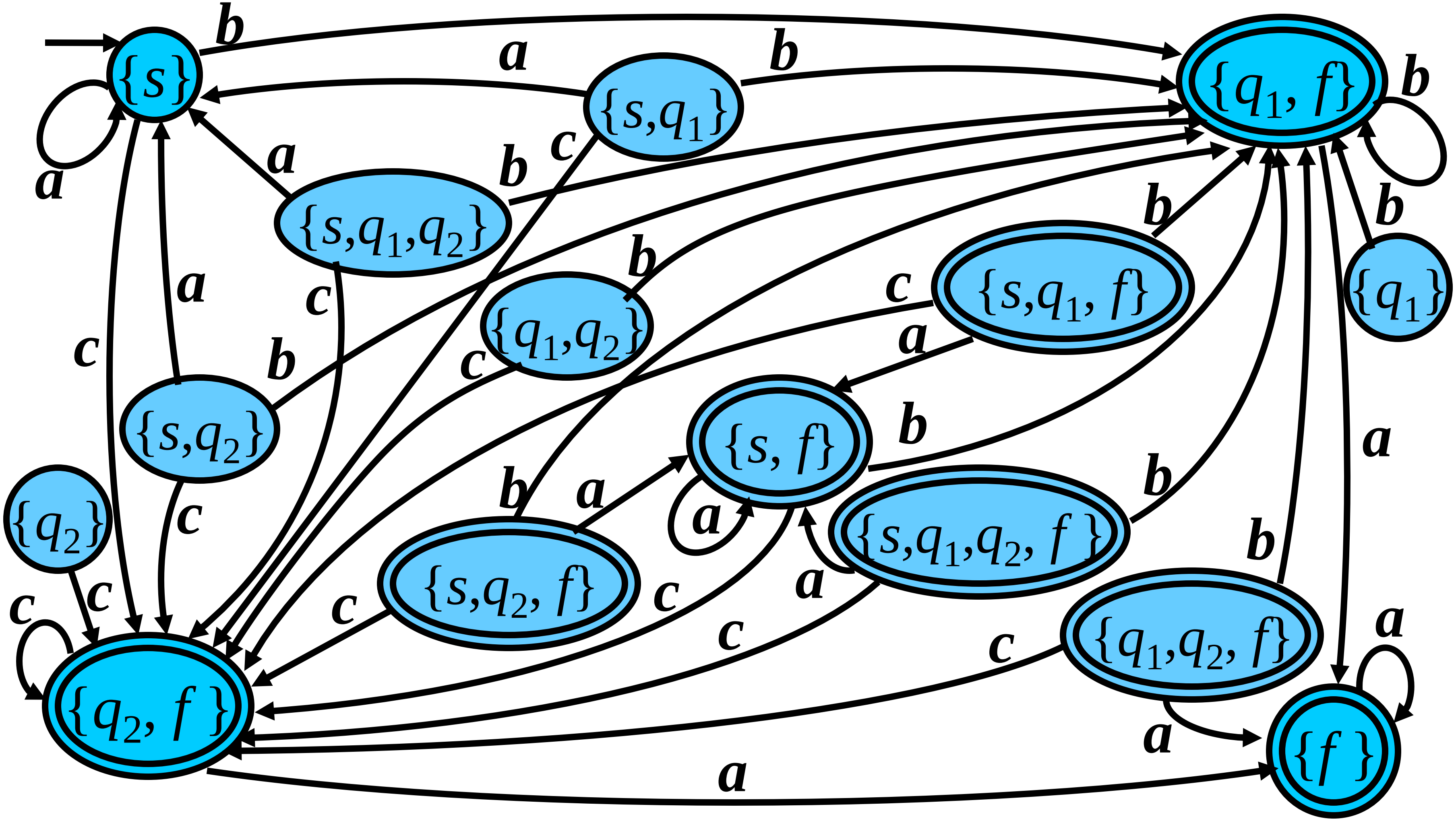
$\vdots$

$$F_d = \{\{s,q_1,f\}, \{s,q_1,q_2,f\}, \{s,q_2,f\}, \{s,f\},$$
$$\{q_1,f\}, \{q_1,q_2,f\}, \{q_2,f\}, \{f\}\}$$

ε-free FA to DFA: Example 5/5

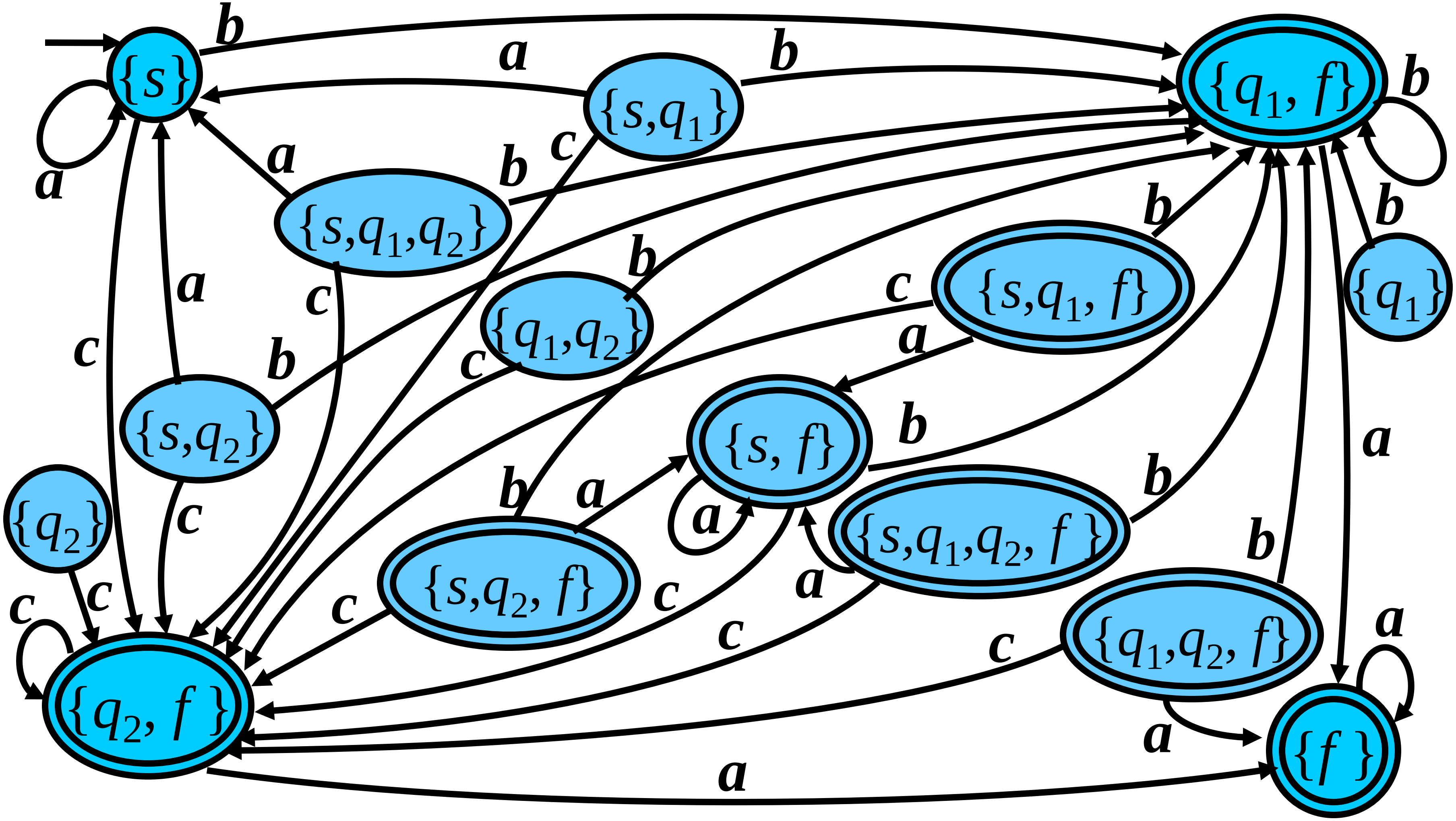


ε-free FA to DFA: Example 5/5



Question: Can we make DFA smaller?

ε-free FA to DFA: Example 5/5



Question: Can we make DFA smaller?

Answer: **YES**

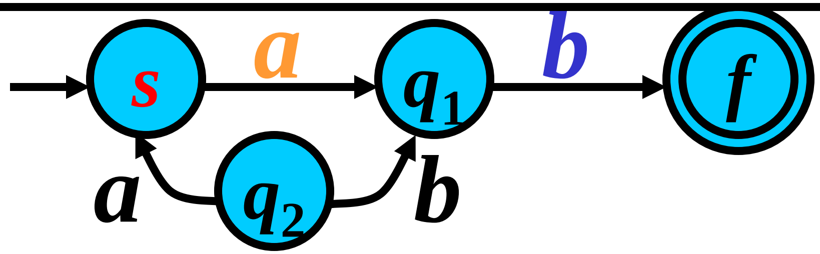
Accessible States

Gist: State q is *accessible* if a string takes DFA from s (the start state) to q.

Definition: Let $M = (Q, \Sigma, R, s, F)$ be an FA.
A state $q \in Q$ is *accessible* if there exists $w \in \Sigma^*$ such that $sw \vdash^* q$; otherwise, q is *inaccessible*.

Note: Each inaccesible state can be removed from FA

Example:



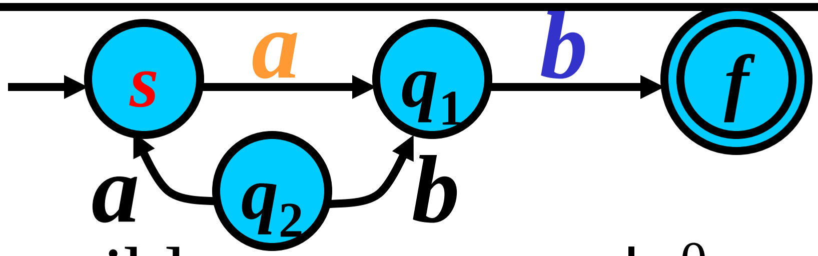
Accessible States

Gist: State q is *accessible* if a string takes DFA from s (the start state) to q.

Definition: Let $M = (Q, \Sigma, R, s, F)$ be an FA.
A state $q \in Q$ is *accessible* if there exists $w \in \Sigma^*$ such that $sw \vdash^* q$; otherwise, q is *inaccessible*.

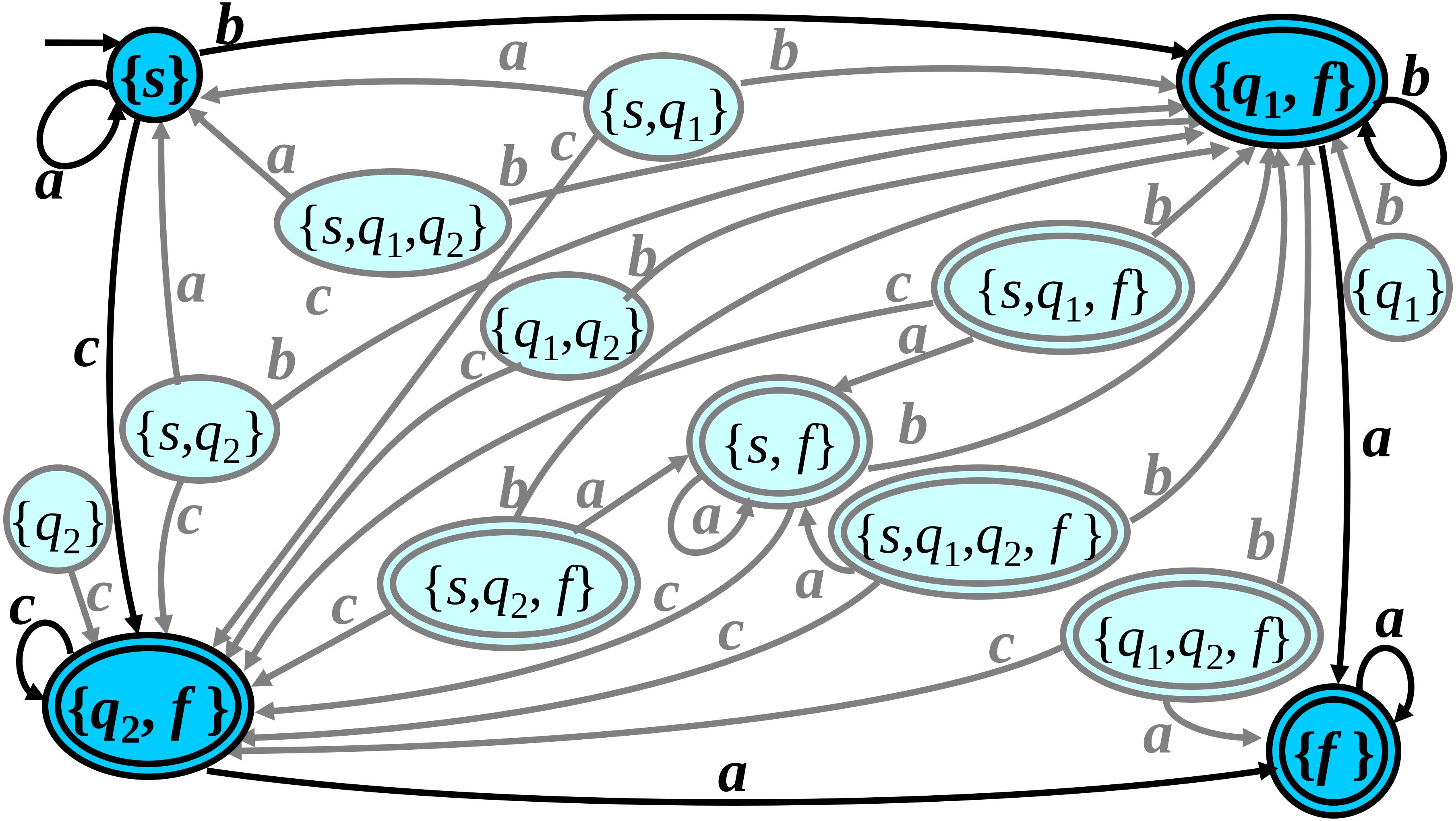
Note: Each inaccesible state can be removed from FA

Example:

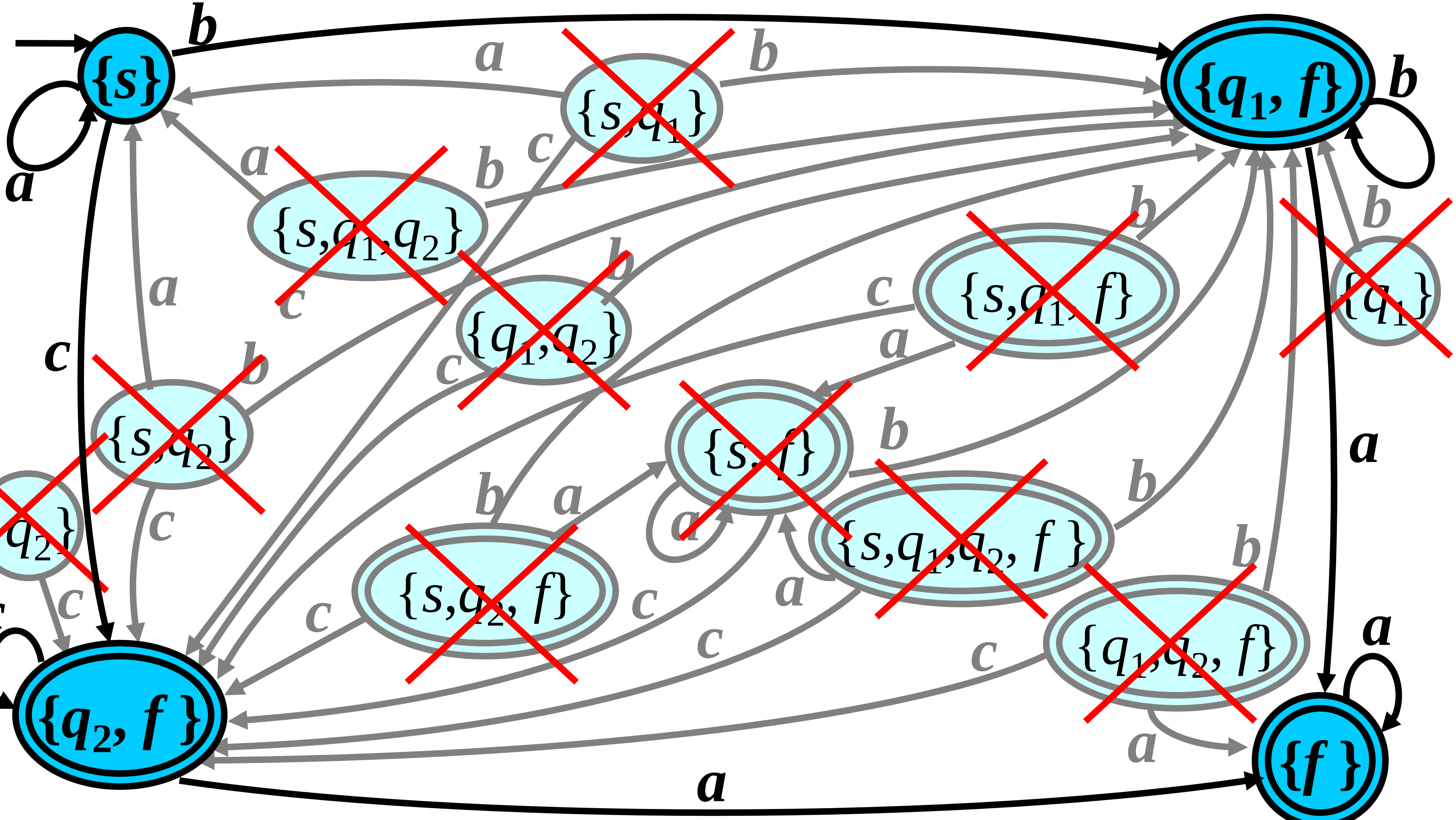


State s - accesible: $w = \varepsilon$: $s \vdash^0 s$
State q_1 - accesible: $w = a$: $sa \vdash q_1$
State f - accesible: $w = ab$: $sab \vdash q_1 b \vdash f$
State q_2 - **inaccessible** (there is no $w \in \Sigma^*$ such that $sw \vdash^* q_2$)

Previous Example



Previous Example



Many inaccessible states

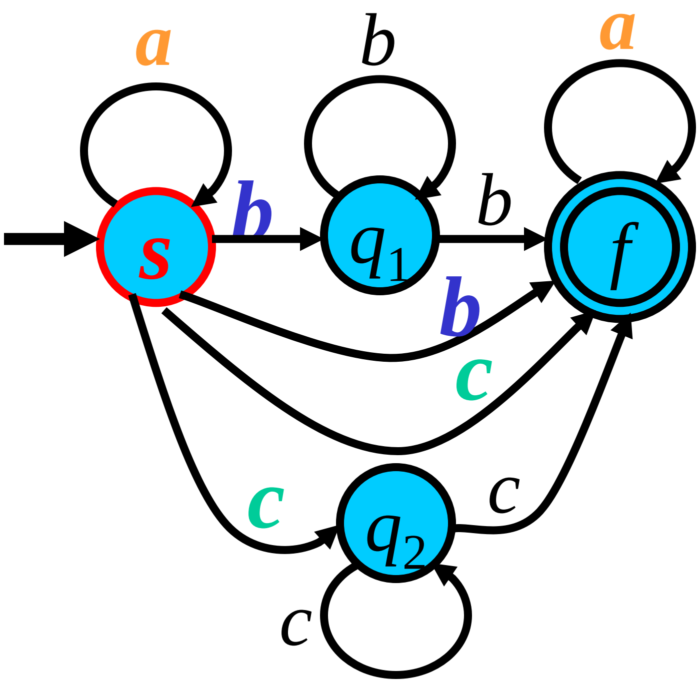
Algorithm II: ε-free FA to DFA 1/2

Gist: Analogy to the previous algorithm except that only sets of accessible states are introduced.

Algorithm II: ε-free FA to DFA 1/2

Gist: **Analogy to the previous algorithm except that only sets of accessible states are introduced.**

Illustration:

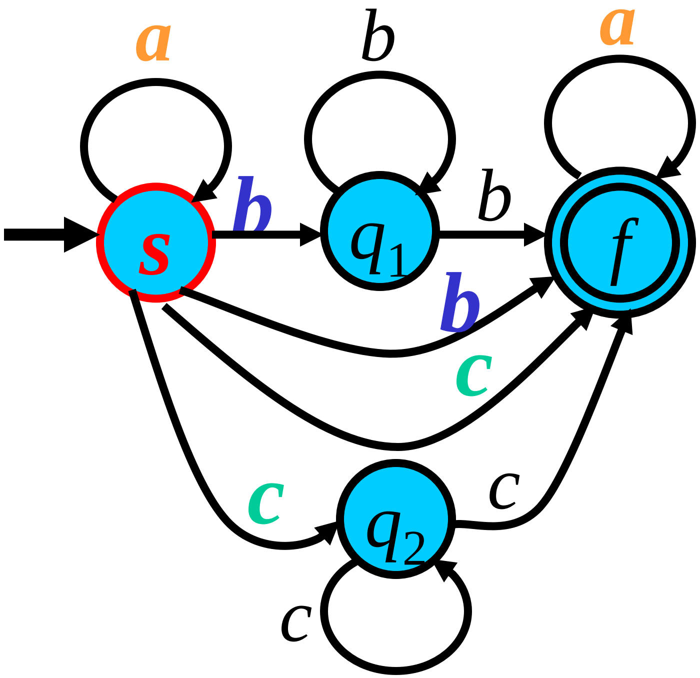


$Q_{DFA} = \{\{s\}\}$

Algorithm II: ε-free FA to DFA 1/2

Gist: Analogy to the previous algorithm except that only sets of accessible states are introduced.

Illustration:



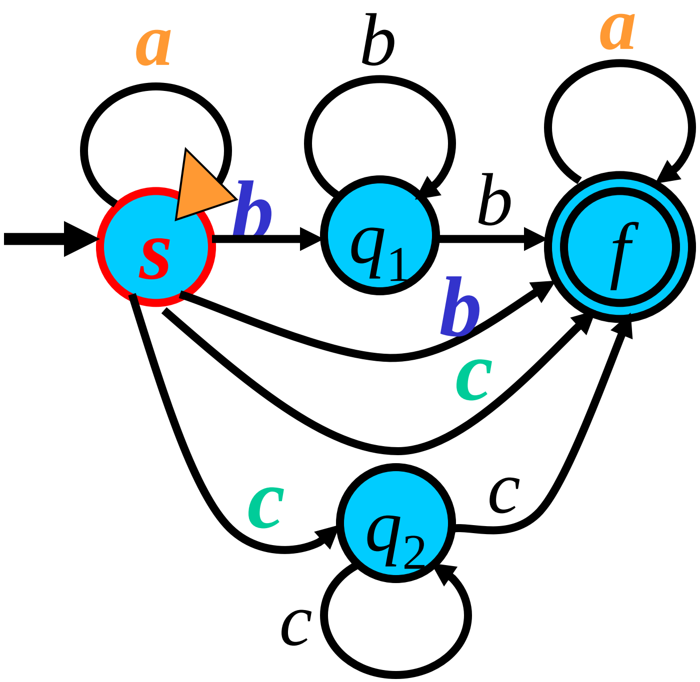
$Q_{DFA} = \{\{s\}\}$

For state {*s*}: 

Algorithm II: ε-free FA to DFA 1/2

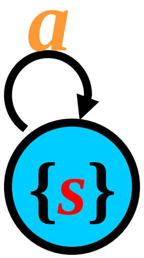
Gist: Analogy to the previous algorithm except that only sets of accessible states are introduced.

Illustration:



Q_{DFA} = {{s}}

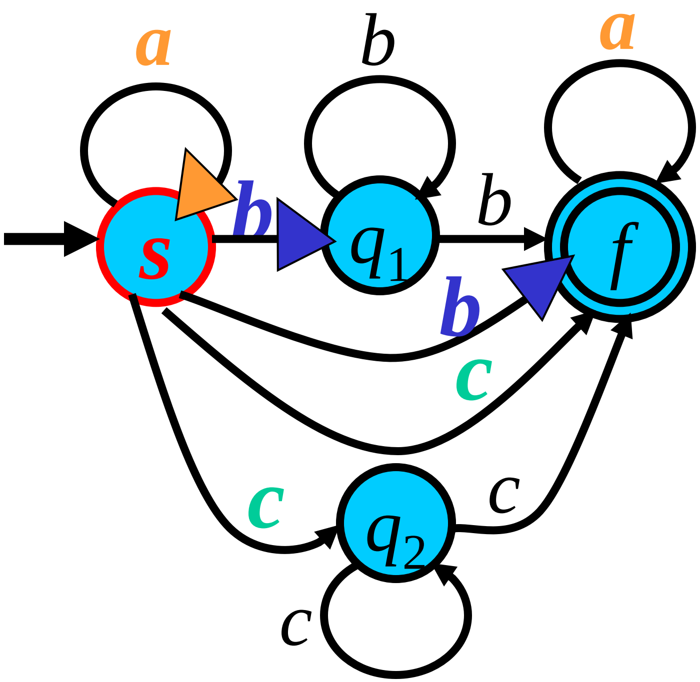
For state {s}:



Algorithm II: ε-free FA to DFA 1/2

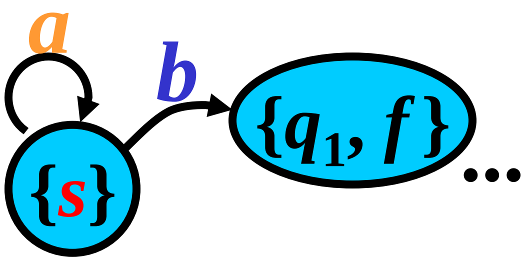
Gist: **Analogy to the previous algorithm except that only sets of accessible states are introduced.**

Illustration:



$Q_{DFA} = \{\{s\}\}$

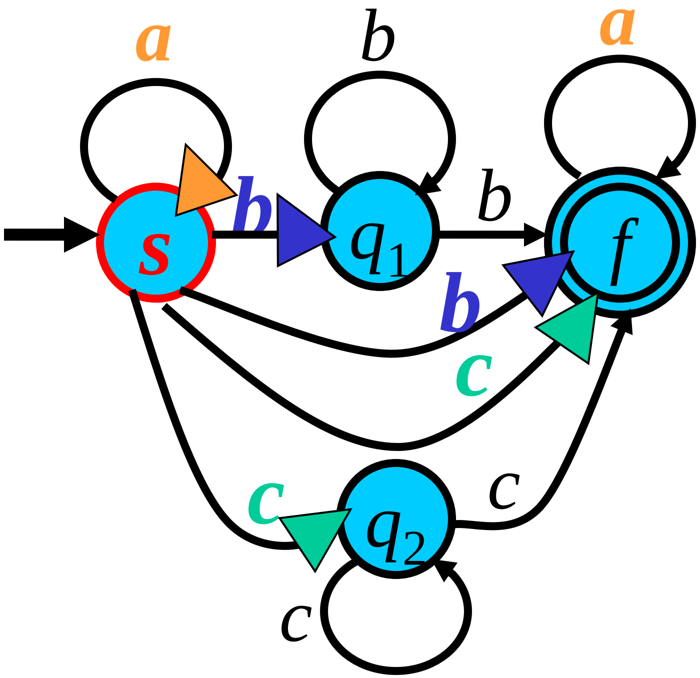
For state {*s*}:



Algorithm II: ε-free FA to DFA 1/2

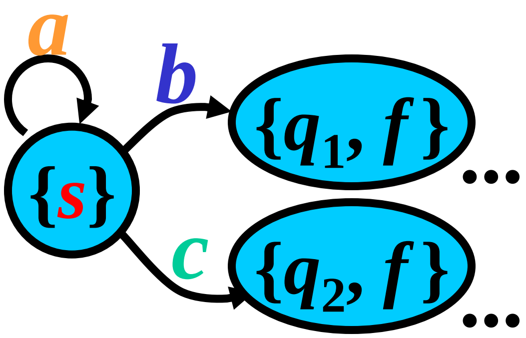
Gist: **Analogy to the previous algorithm except that only sets of accessible states are introduced.**

Illustration:



$Q_{DFA} = \{\{s\}\}$

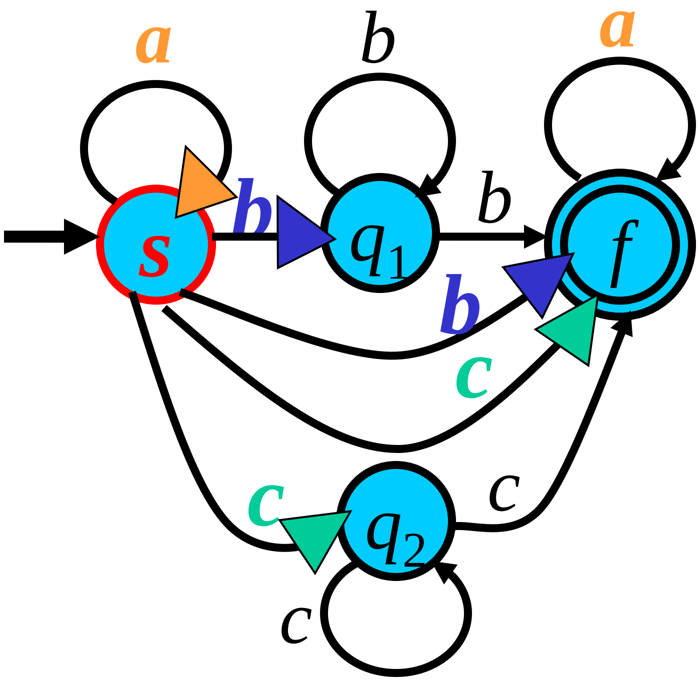
For state {*s*}:



Algorithm II: ε-free FA to DFA 1/2

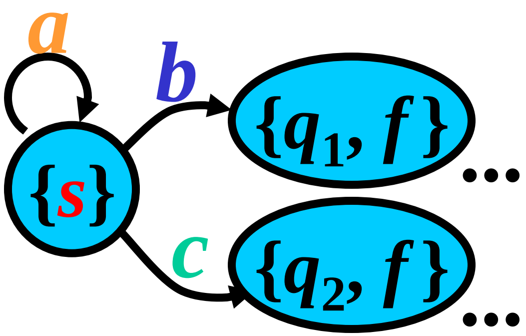
Gist: Analogy to the previous algorithm except that only sets of accessible states are introduced.

Illustration:



$Q_{DFA} = \{\{s\}\}$

For state $\{s\}$:

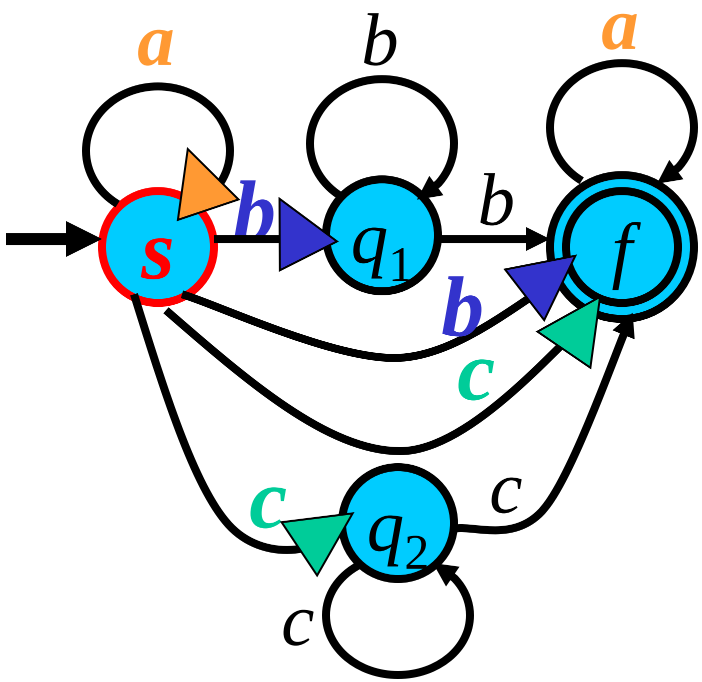


Add new states $\{q_1, f\}$, $\{q_2, f\}$ to Q_{DFA}

Algorithm II: ε-free FA to DFA 1/2

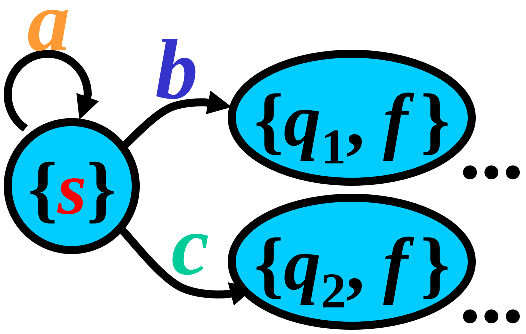
Gist: **Analogy to the previous algorithm except that only sets of accessible states are introduced.**

Illustration:



$Q_{DFA} = \{\{s\}\}$

For state $\{s\}$:



Add new states $\{q_1, f\}$, $\{q_2, f\}$ to Q_{DFA}

For state $\{q_1, f\}$: …

For state $\{q_2, f\}$: …

Add new states …

⋮

Algorithm II: ε-free FA to DFA 2/2

- **Input:** ε-*free* FA: $M = (Q, \Sigma, R, s, F)$
- **Output:** DFA: $M_d = (Q_d, \Sigma, R_d, s_d, F_d)$

  without any inaccessible states

- **Method:**

```
• $s_d := \{s\}$; $Q_{new} := \{s_d\}$; $R_d := \emptyset$; $Q_d := \emptyset$; $F_d := \emptyset$;
• repeat
    let $Q' \in Q_{new}$; $Q_{new} := Q_{new} - \{Q'\}$; $Q_d := Q_d \cup \{Q'\}$;
    for each $a \in \Sigma$ do begin
        $Q'' := \{q: p \in Q', pa \rightarrow q \in R\}$;
        if $Q'' \neq \emptyset$ then $R_d := R_d \cup \{Q'a \rightarrow Q''\}$;
        if $Q'' \notin Q_d \cup \{\emptyset\}$ then $Q_{new} := Q_{new} \cup \{Q''\}$
    end;
    if $Q' \cap F \neq \emptyset$ then $F_d := F_d \cup \{Q'\}$
until $Q_{new} = \emptyset$.
```

ε-free FA to DFA: Example 1/3

$M = (Q, \Sigma, R, s, F)$, where:

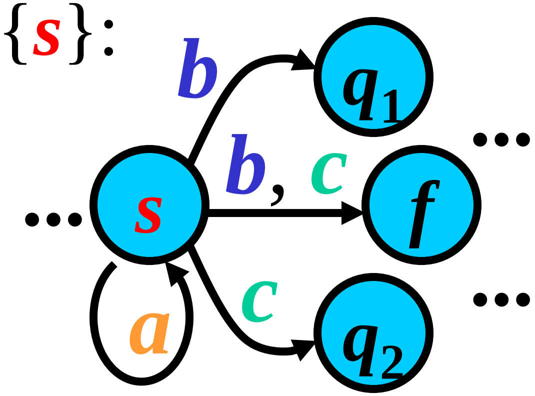
$Q = \{s, q_1, q_2, f\}$; $\Sigma = \{a, b, c\}$; $F = \{f\}$

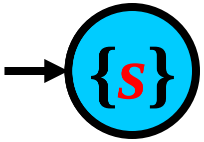
$R = \{sa \rightarrow s, sb \rightarrow q_1, sb \rightarrow f, sc \rightarrow q_2, sc \rightarrow f,$
$q_1b \rightarrow q_1, q_1b \rightarrow f, q_2c \rightarrow q_2, q_2c \rightarrow f, fa \rightarrow f\}$;

$Q_{new} = \{\{s\}\}$; $R_d = \emptyset$; $Q_d = \emptyset$; $F_d = \emptyset$

---

for $Q' = \{s\}$:





ε-free FA to DFA: Example 1/3

$M = (Q, \Sigma, R, s, F)$, where:

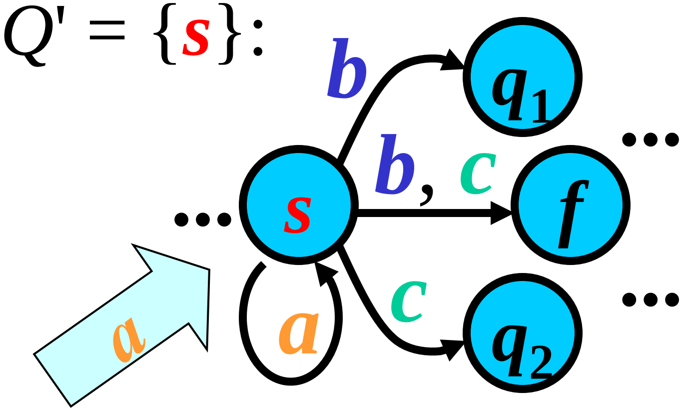
$Q = \{s, q_1, q_2, f\}$; $\Sigma = \{a, b, c\}$; $F = \{f\}$

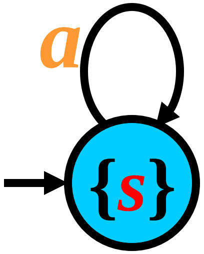
$R = \{sa \rightarrow s, sb \rightarrow q_1, sb \rightarrow f, sc \rightarrow q_2, sc \rightarrow f,$
$q_1b \rightarrow q_1, q_1b \rightarrow f, q_2c \rightarrow q_2, q_2c \rightarrow f, fa \rightarrow f\};$

$Q_{new} = \{\{s\}\}$; $R_d = \emptyset$; $Q_d = \emptyset$; $F_d = \emptyset$

---

for $Q' = \{s\}$:





ε-free FA to DFA: Example 1/3

$M = (Q, \Sigma, R, s, F)$, where:

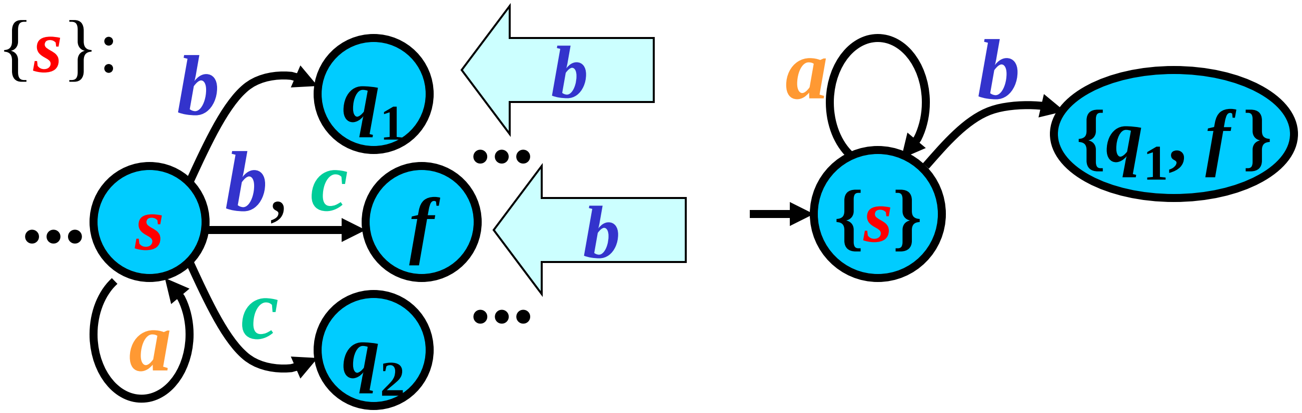
$Q = \{s, q_1, q_2, f\}$; $\Sigma = \{a, b, c\}$; $F = \{f\}$

$R = \{sa \rightarrow s, sb \rightarrow q_1, sb \rightarrow f, sc \rightarrow q_2, sc \rightarrow f,$
$q_1b \rightarrow q_1, q_1b \rightarrow f, q_2c \rightarrow q_2, q_2c \rightarrow f, fa \rightarrow f\};$

$Q_{new} = \{\{s\}\}$; $R_d = \emptyset$; $Q_d = \emptyset$; $F_d = \emptyset$

---

for $Q' = \{s\}$:



ε-free FA to DFA: Example 1/3

$M = (Q, \Sigma, R, s, F)$, where:

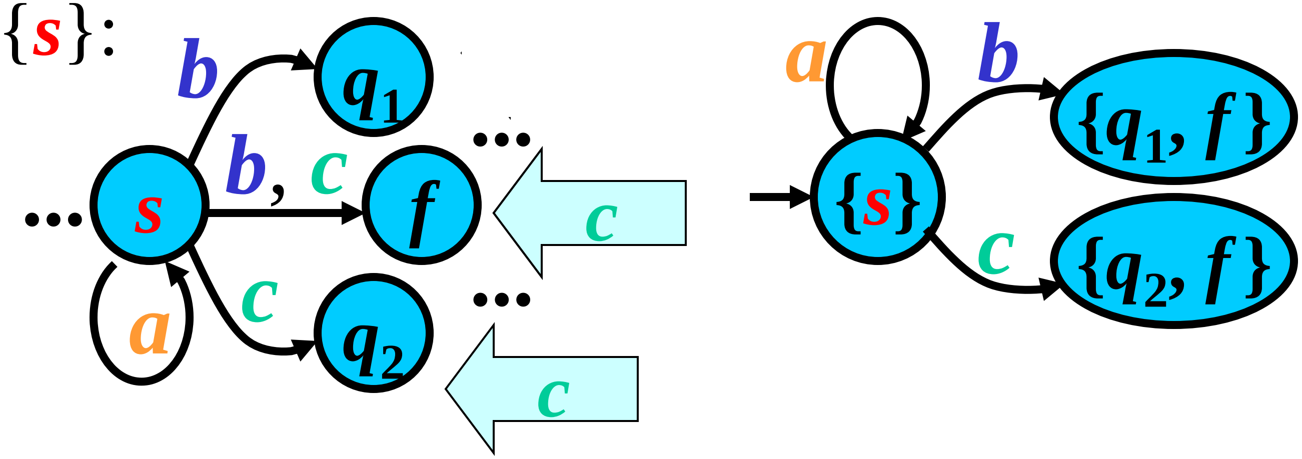
$Q = \{s, q_1, q_2, f\}$; $\Sigma = \{a, b, c\}$; $F = \{f\}$

$R = \{sa \rightarrow s,\ sb \rightarrow q_1,\ sb \rightarrow f,\ sc \rightarrow q_2,\ sc \rightarrow f,$
$\quad q_1b \rightarrow q_1,\ q_1b \rightarrow f,\ q_2c \rightarrow q_2,\ q_2c \rightarrow f,\ fa \rightarrow f\}$;

$Q_{new} = \{\{s\}\}$; $R_d = \emptyset$; $Q_d = \emptyset$; $F_d = \emptyset$

---

for $Q' = \{s\}$:



ε-free FA to DFA: Example 1/3

$M = (Q, \Sigma, R, s, F)$, where:

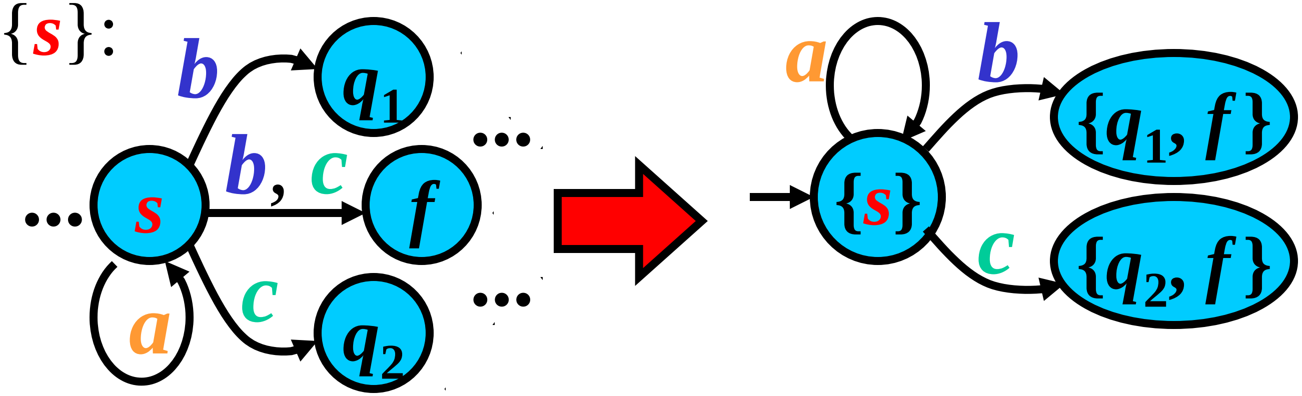
$Q = \{s, q_1, q_2, f\}$; $\Sigma = \{a, b, c\}$; $F = \{f\}$

$R = \{sa \rightarrow s, sb \rightarrow q_1, sb \rightarrow f, sc \rightarrow q_2, sc \rightarrow f,$
$q_1b \rightarrow q_1, q_1b \rightarrow f, q_2c \rightarrow q_2, q_2c \rightarrow f, fa \rightarrow f\}$;

$Q_{new} = \{\{s\}\}$; $R_d = \emptyset$; $Q_d = \emptyset$; $F_d = \emptyset$

---

for $Q' = \{s\}$:

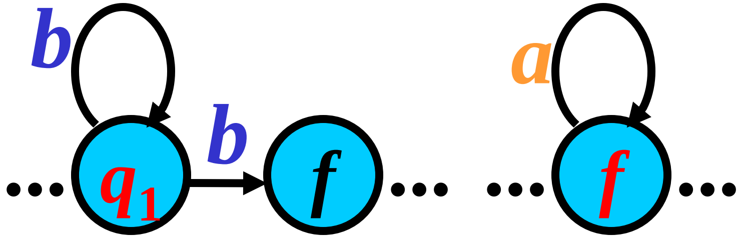


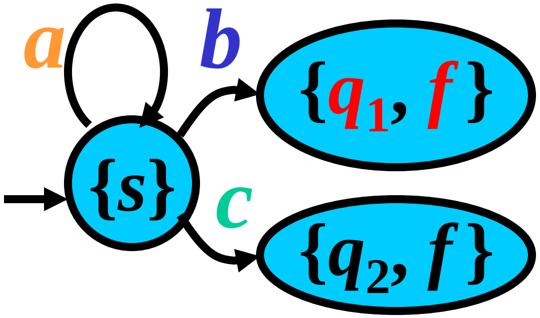
$R_d := \emptyset \cup \{\{s\}a \rightarrow \{s\}, \{s\}b \rightarrow \{q_1, f\}, \{s\}c \rightarrow \{q_2, f\}\}$

$Q_{new} = \{\{q_1, f\}, \{q_2, f\}\}$, $Q_d = \emptyset \cup \{\{s\}\}$, $F_d = \emptyset$

ε-free FA to DFA: Example 2/3

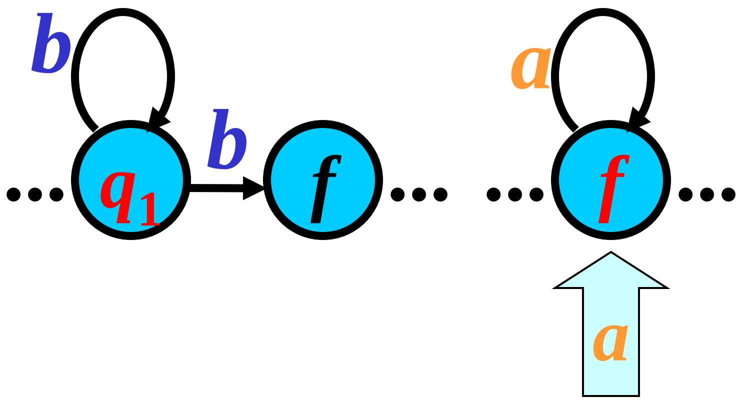
for $Q' = \{q_1, f\}$:

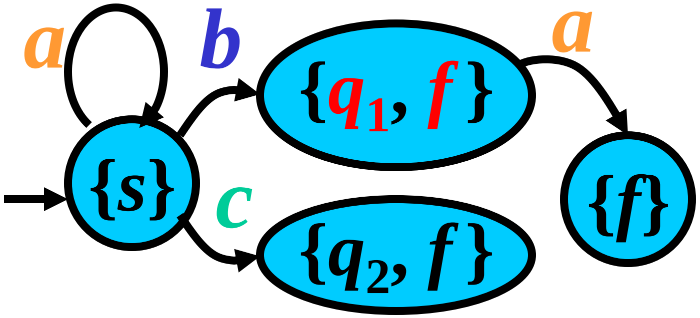




ε-free FA to DFA: Example 2/3

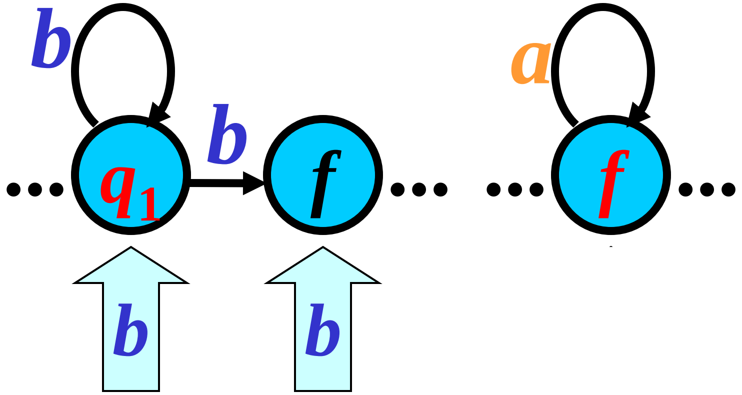
for $Q' = \{q_1, f\}$:

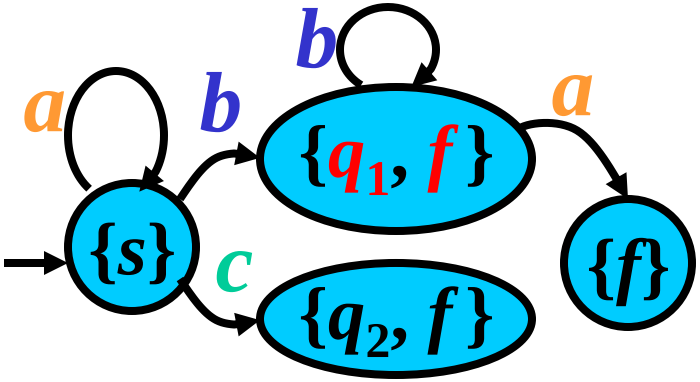




ε-free FA to DFA: Example 2/3

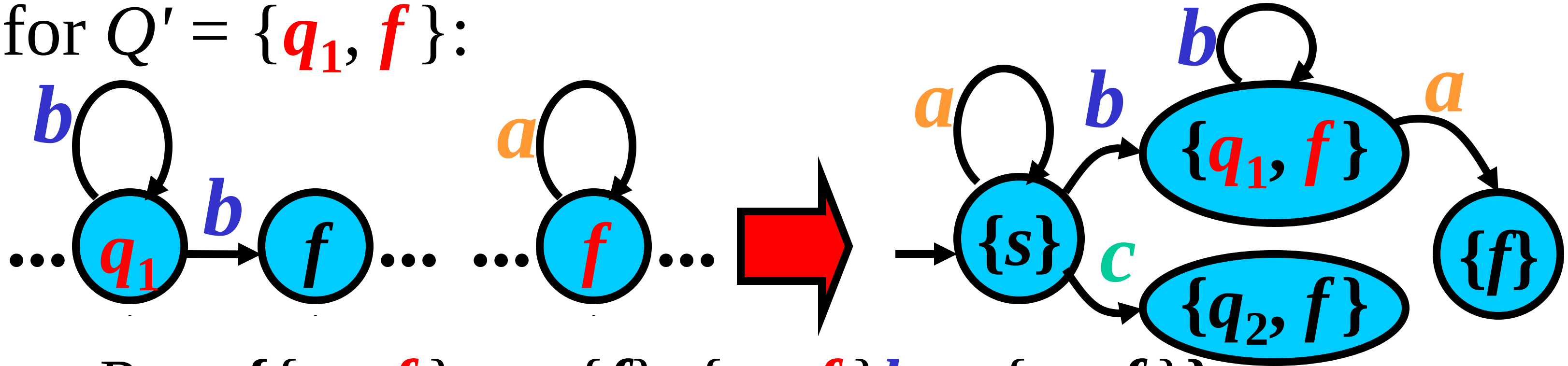
for $Q' = \{q_1, f\}$:





ε-free FA to DFA: Example 2/3

for $Q' = \{q_1, f\}$:

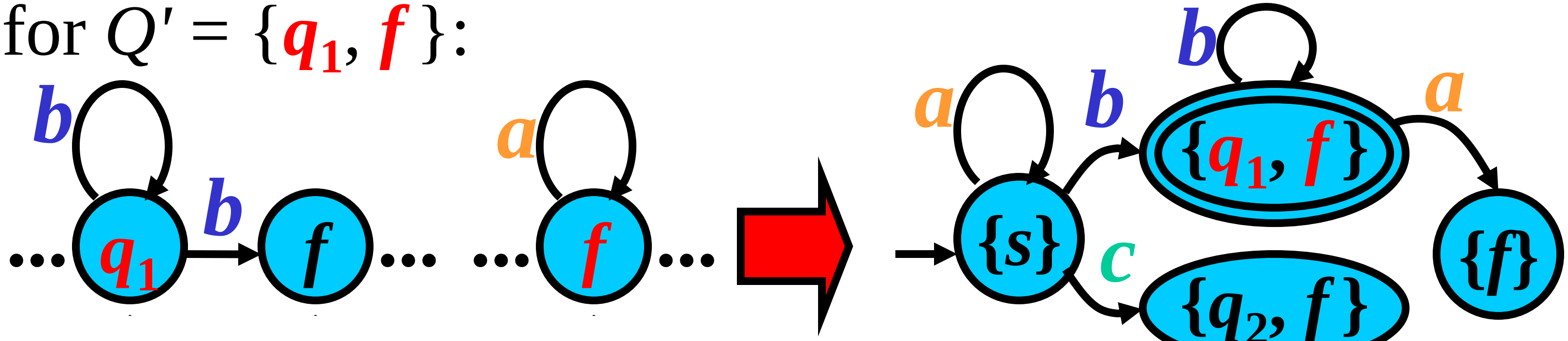


$R_d := R_d \cup \{\{q_1, f\}a \rightarrow \{f\}, \{q_1, f\}b \rightarrow \{q_1, f\}\}$

$Q_{new} = \{\{q_2, f\}, \{f\}\}, Q_d = Q_d \cup \{\{q_1, f\}\},$

ε-free FA to DFA: Example 2/3

for $Q' = \{q_1, f\}$:

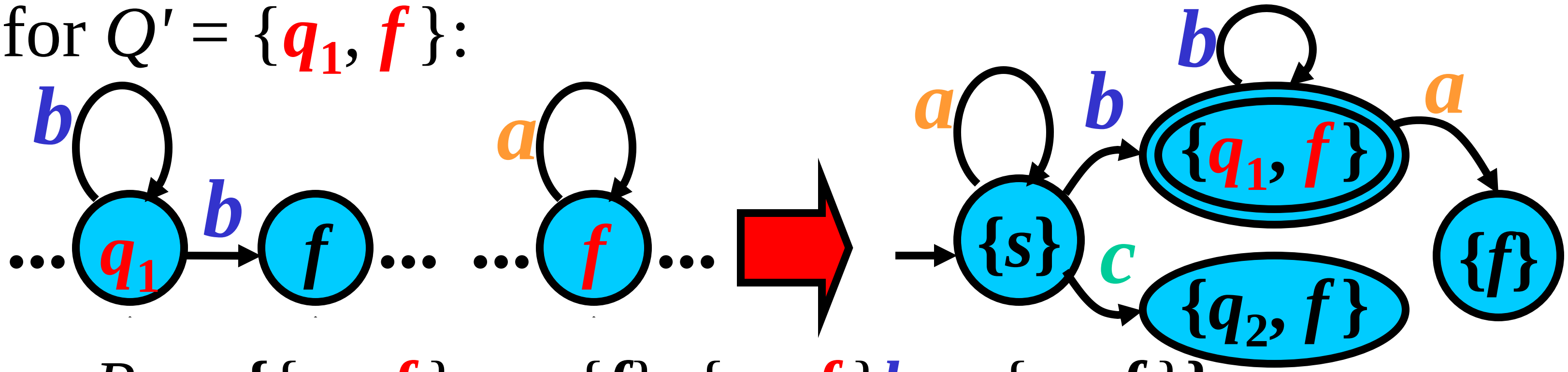


$R_d := R_d \cup \{\{q_1, f\}a \rightarrow \{f\}, \{q_1, f\}b \rightarrow \{q_1, f\}\}$

$Q_{new} = \{\{q_2, f\}, \{f\}\}, Q_d = Q_d \cup \{\{q_1, f\}\}, F_d := \emptyset \cup \{\{q_1, f\}\}$

ε-free FA to DFA: Example 2/3

for $Q' = \{q_1, f\}$:

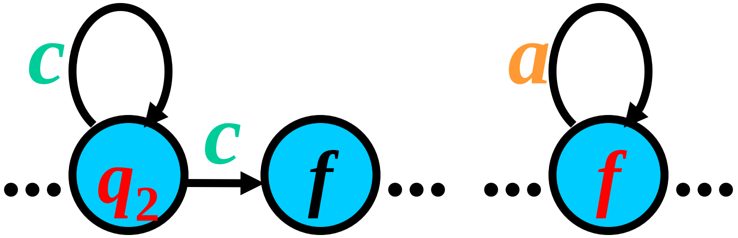


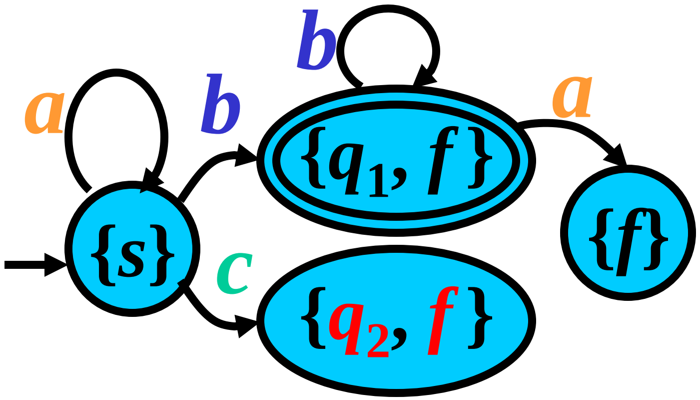
$R_d := R_d \cup \{\{q_1, f\}a \to \{f\}, \{q_1, f\}b \to \{q_1, f\}\}$

$Q_{new} = \{\{q_2, f\}, \{f\}\}, Q_d = Q_d \cup \{\{q_1, f\}\}, F_d := \emptyset \cup \{\{q_1, f\}\}$

---

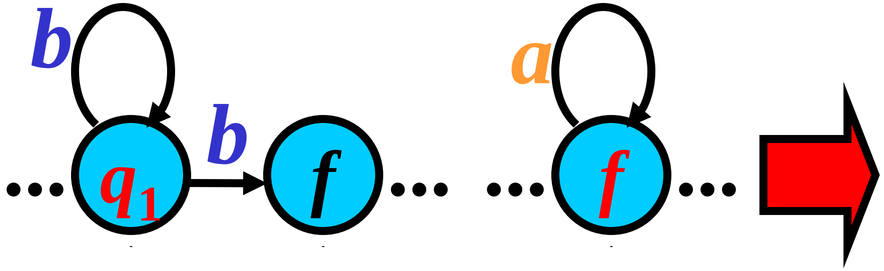
for $Q' = \{q_2, f\}$:

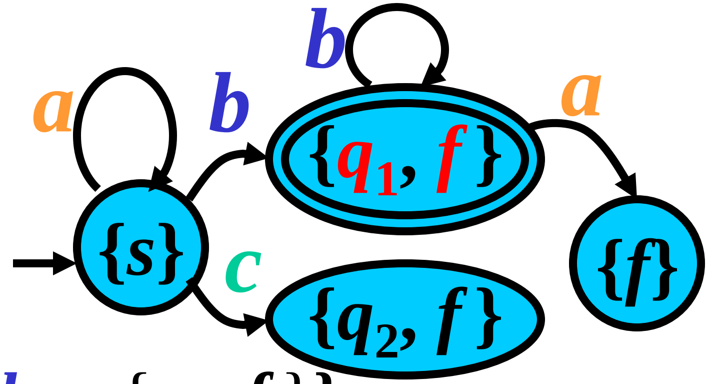




ε-free FA to DFA: Example 2/3

for $Q' = \{q_1, f\}$:

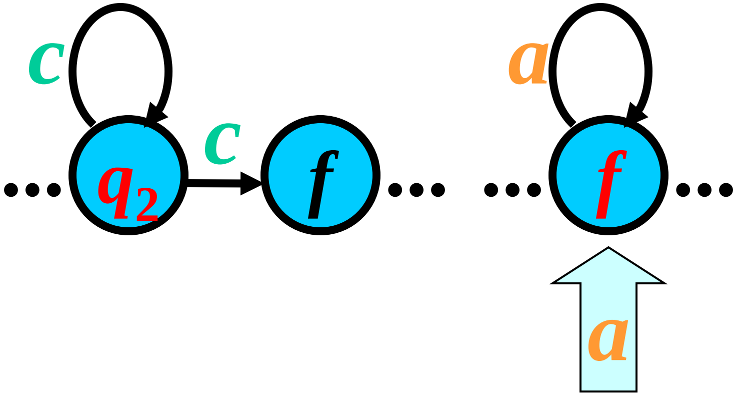


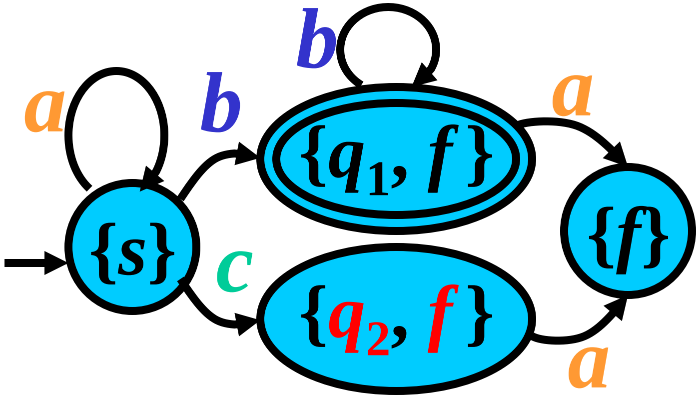


$R_d := R_d \cup \{\{q_1, f\}a \rightarrow \{f\}, \{q_1, f\}b \rightarrow \{q_1, f\}\}$

$Q_{new} = \{\{q_2, f\}, \{f\}\}, Q_d = Q_d \cup \{\{q_1, f\}\}, F_d := \emptyset \cup \{\{q_1, f\}\}$

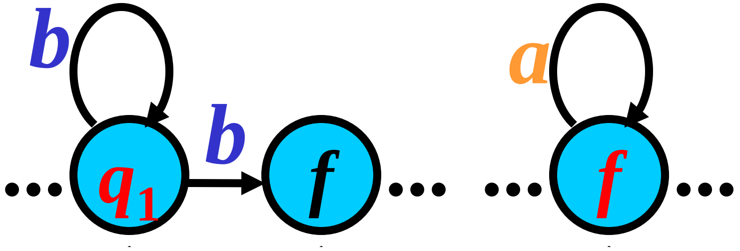
for $Q' = \{q_2, f\}$:

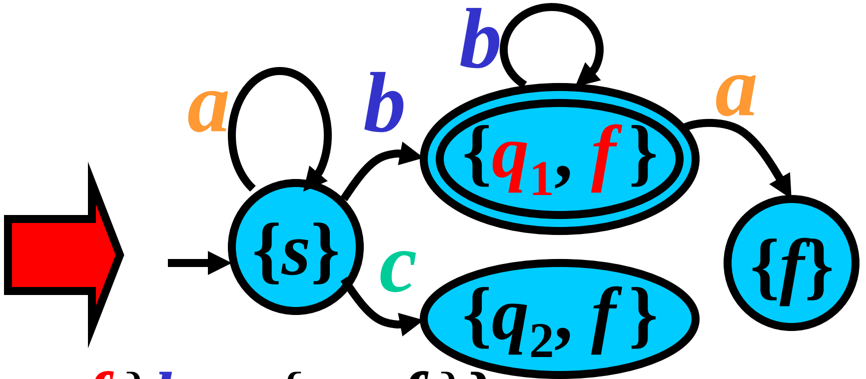




ε-free FA to DFA: Example 2/3

for $Q' = \{q_1, f\}$:



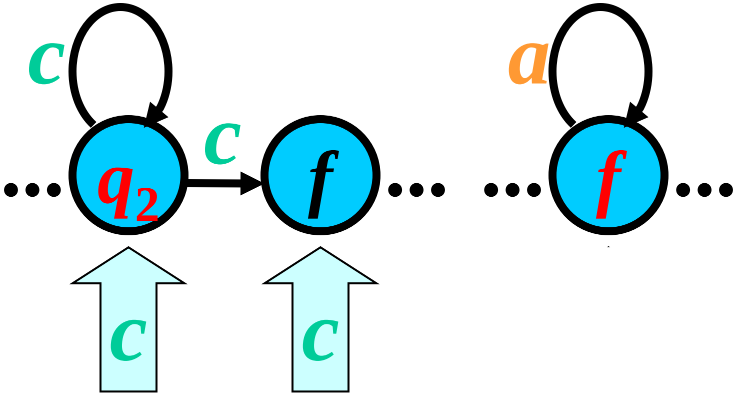


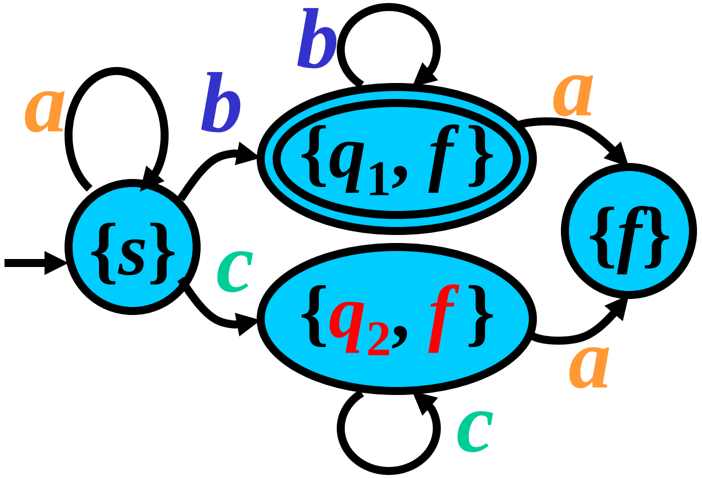
$R_d := R_d \cup \{\{q_1, f\}a \rightarrow \{f\}, \{q_1, f\}b \rightarrow \{q_1, f\}\}$

$Q_{new} = \{\{q_2, f\}, \{f\}\}, Q_d = Q_d \cup \{\{q_1, f\}\}, F_d := \emptyset \cup \{\{q_1, f\}\}$

---

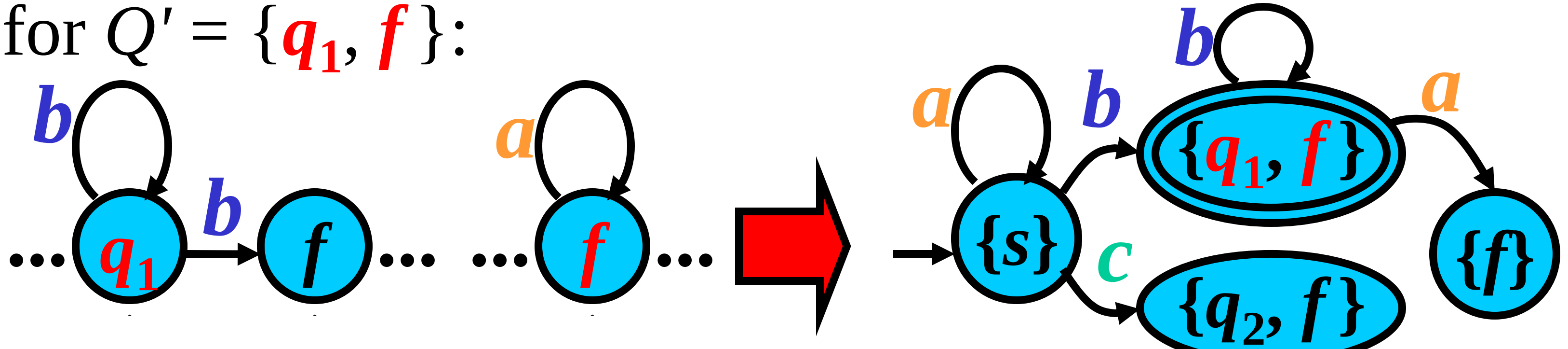
for $Q' = \{q_2, f\}$:





ε-free FA to DFA: Example 2/3

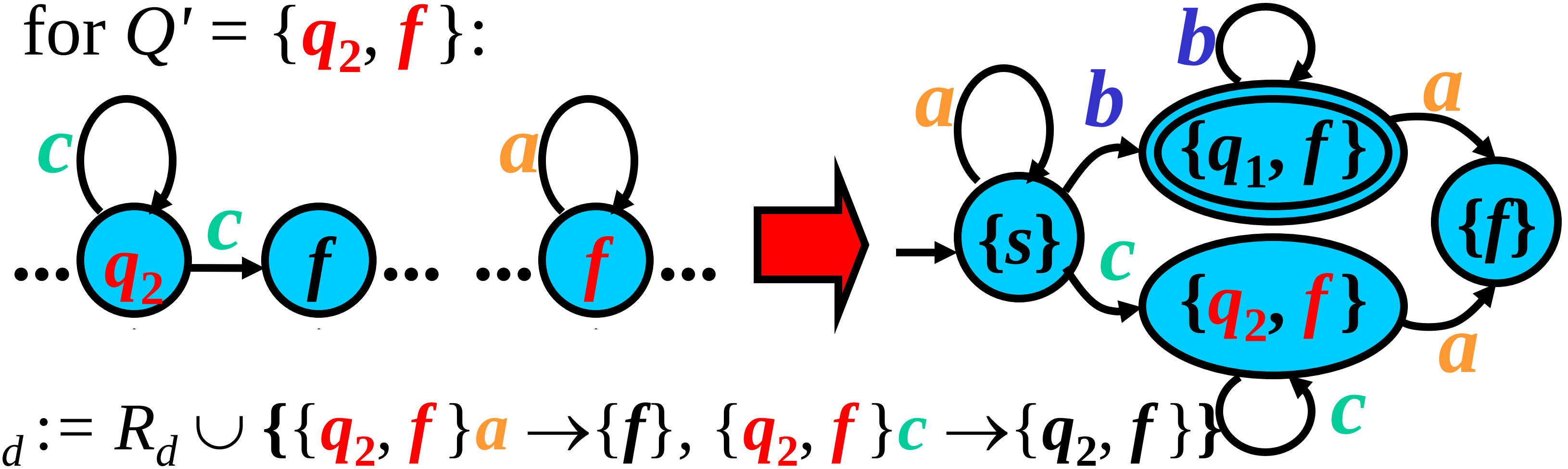
for $Q' = \{q_1, f\}$:



$R_d := R_d \cup \{\{q_1, f\}a \rightarrow \{f\}, \{q_1, f\}b \rightarrow \{q_1, f\}\}$

$Q_{new} = \{\{q_2, f\}, \{f\}\}, Q_d = Q_d \cup \{\{q_1, f\}\}, F_d := \emptyset \cup \{\{q_1, f\}\}$

for $Q' = \{q_2, f\}$:

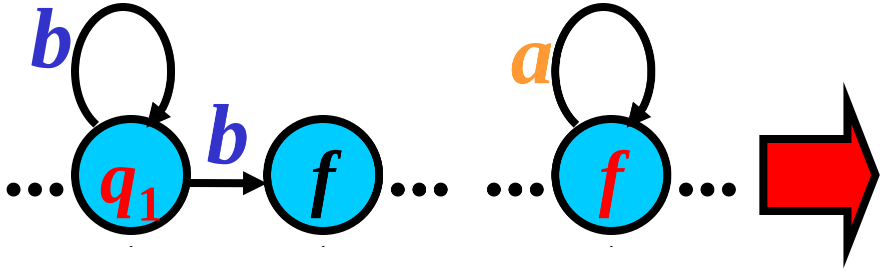


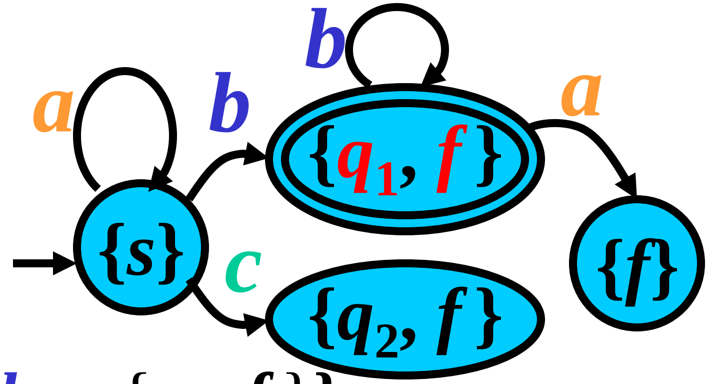
$R_d := R_d \cup \{\{q_2, f\}a \rightarrow \{f\}, \{q_2, f\}c \rightarrow \{q_2, f\}\}$

$Q_{new} = \{\{f\}\}, Q_d = Q_d \cup \{\{q_2, f\}\},$

ε-free FA to DFA: Example 2/3

for $Q' = \{q_1, f\}$:



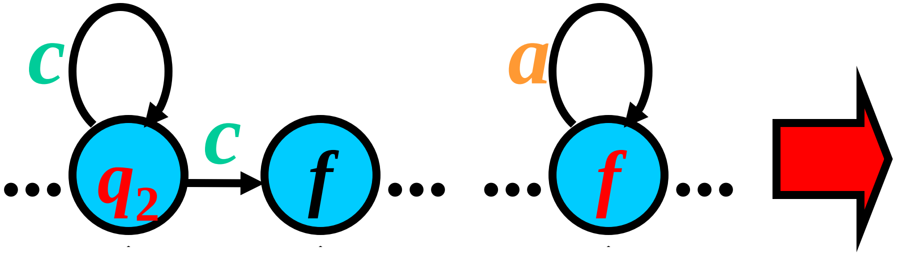


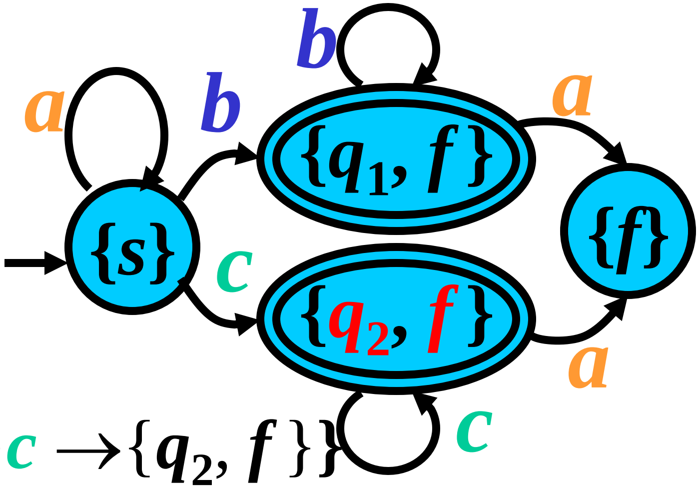
$R_d := R_d \cup \{\{q_1, f\}a \rightarrow \{f\}, \{q_1, f\}b \rightarrow \{q_1, f\}\}$

$Q_{new} = \{\{q_2, f\}, \{f\}\}, Q_d = Q_d \cup \{\{q_1, f\}\}, F_d := \emptyset \cup \{\{q_1, f\}\}$

---

for $Q' = \{q_2, f\}$:



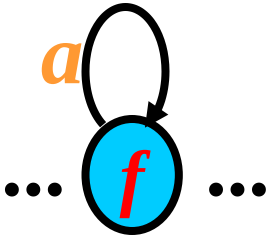


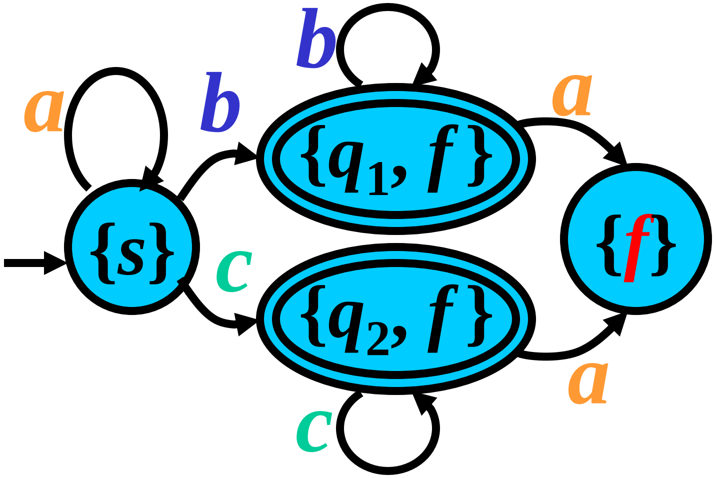
$R_d := R_d \cup \{\{q_2, f\}a \rightarrow \{f\}, \{q_2, f\}c \rightarrow \{q_2, f\}\}$

$Q_{new} = \{\{f\}\}, Q_d = Q_d \cup \{\{q_2, f\}\}, F_d := F_d \cup \{\{q_2, f\}\}$

ε-free FA to DFA: Example 3/3

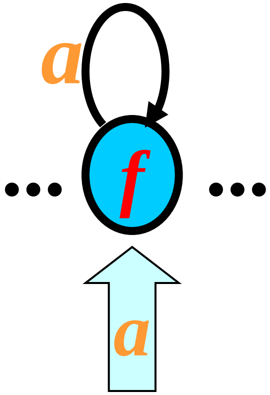
for $Q' = \{f\}$:

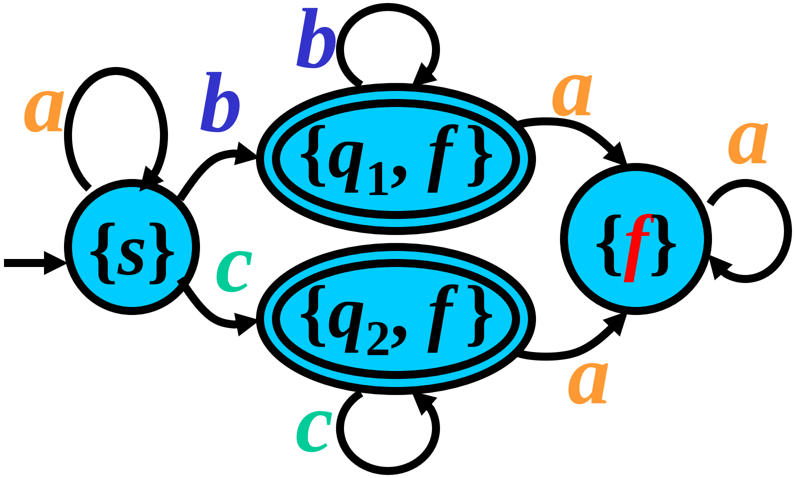




ε-free FA to DFA: Example 3/3

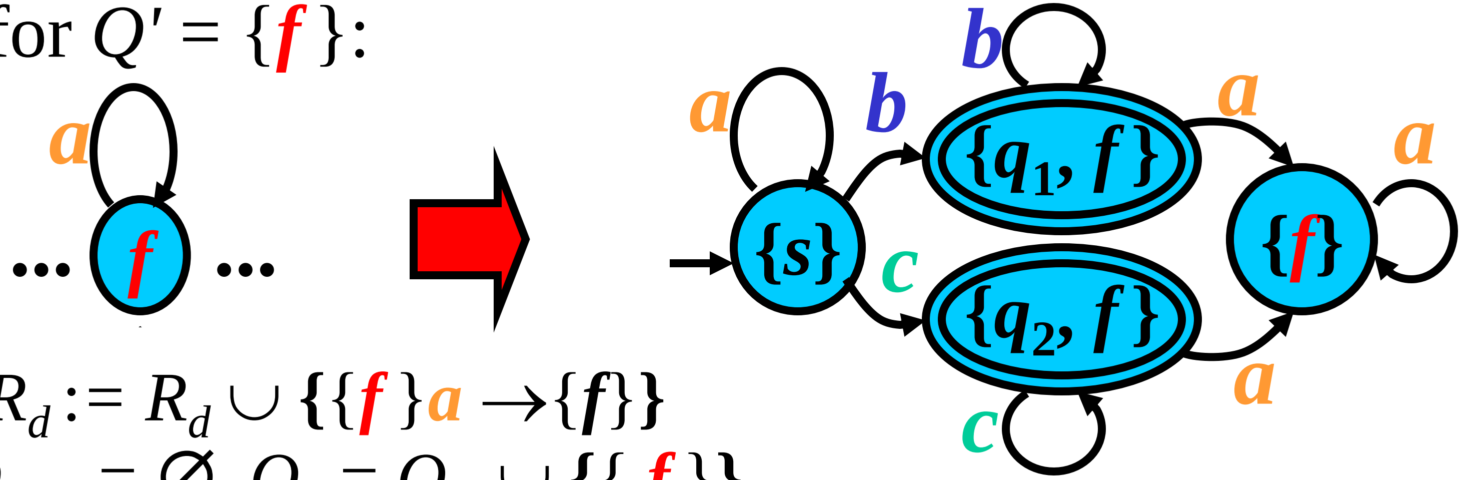
for $Q' = \{f\}$:





ε-free FA to DFA: Example 3/3

for $Q' = \{f\}$:

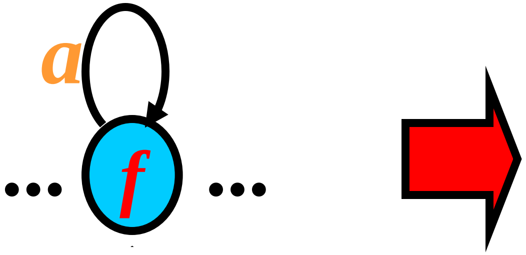


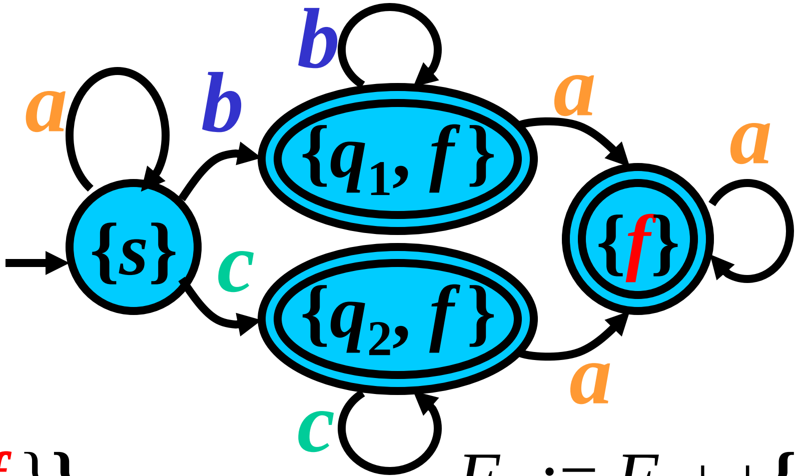
$R_d := R_d \cup \{\{f\}a \rightarrow \{f\}\}$

$Q_{new} = \emptyset$, $Q_d = Q_d \cup \{\{f\}\}$,

ε-free FA to DFA: Example 3/3

for $Q' = \{f\}$:





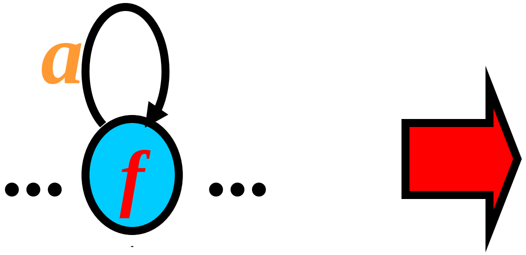
$R_d := R_d \cup \{\{f\}a \rightarrow \{f\}\}$

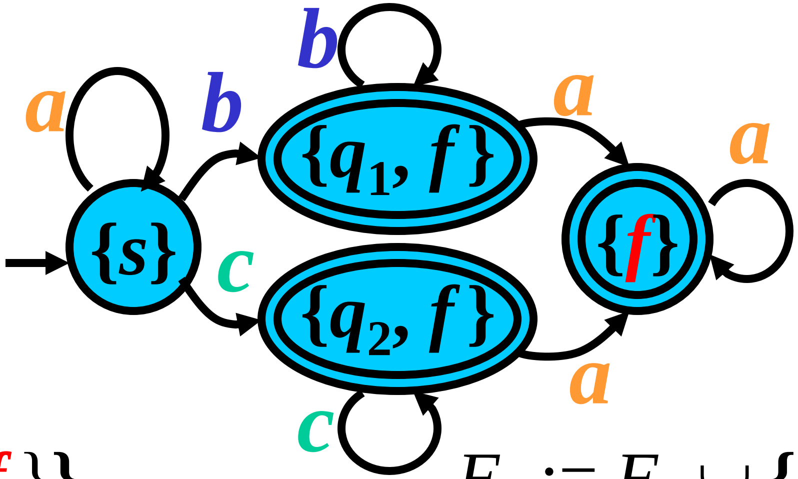
$Q_{new} = \emptyset$, $Q_d = Q_d \cup \{\{f\}\}$,

$F_d := F_d \cup \{\{f\}\}$

ε-free FA to DFA: Example 3/3

for $Q' = \{f\}$:

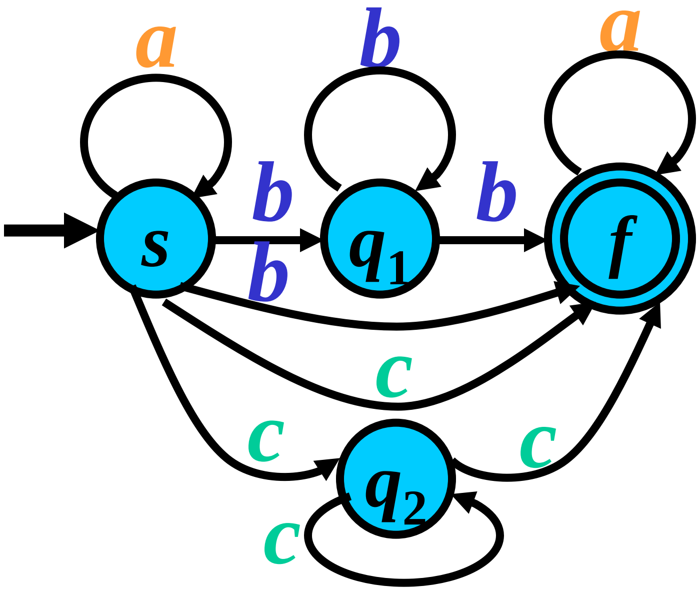




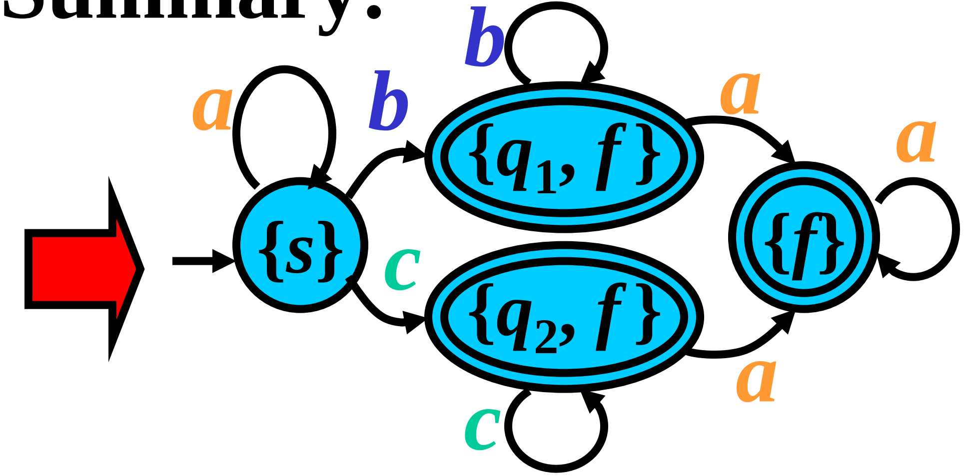
$R_d := R_d \cup \{\{f\}a \rightarrow \{f\}\}$

$Q_{new} = \emptyset, Q_d = Q_d \cup \{\{f\}\}$,

$F_d := F_d \cup \{\{f\}\}$



Summary:



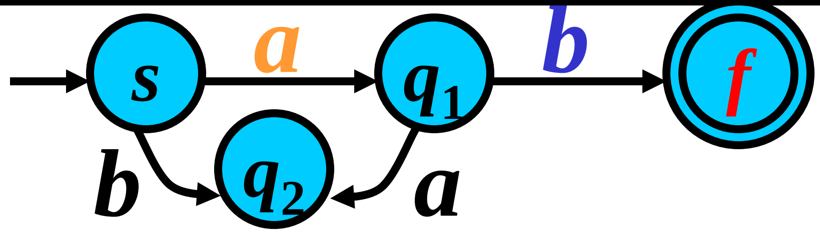
Terminating States

Gist: **State q is *terminating* if a string takes DFA from q to a final state.**

Definition: Let $M = (Q, \Sigma, R, s, F)$ be a DFA. A state $q \in Q$ is *terminating* if there exists $w \in \Sigma^*$ such that $qw \vdash^* f$ with $f \in F$; otherwise, q is *nonterminating*.

Note: Each nonterminating state can be removed from DFA

Example:



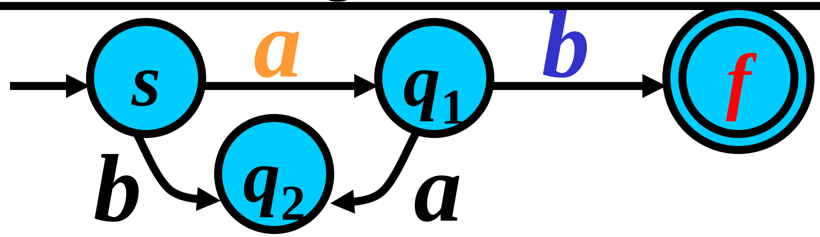
Terminating States

Gist: State q is *terminating* if a string takes DFA from q to a final state.

Definition: Let $M = (Q, \Sigma, R, s, F)$ be a DFA. A state $q \in Q$ is *terminating* if there exists $w \in \Sigma^*$ such that $qw \vdash^* f$ with $f \in F$; otherwise, q is *nonterminating*.

Note: Each nonterminating state can be removed from DFA

Example:



State s - terminating: $w = ab$: $sab \vdash q_1b \vdash f$

State q_1 - terminating: $w = b$: $q_1b \vdash f$

State f - terminating: $w = \varepsilon$: $f \vdash^0 f$

State q_2 - **nonterminating** (there is no $w \in \Sigma^*$
such that $q_2w \vdash^* q$, $q \in F$)

Algorithm: Removal of nont. states

- **Input:** DFA: $M = (Q, \Sigma, R, s, F)$
- **Output:** DFA: $M_t = (Q_t, \Sigma, R_t, s, F)$

- **Method:**

```
• $Q_0 := F; i := 0;$
• repeat
      $i := i + 1;$
      $Q_i := Q_{i-1} \cup \{q: qa \rightarrow p \in R, a \in \Sigma, p \in Q_{i-1}\};$
  until $Q_i = Q_{i-1};$
• $Q_t := Q_i;$
• $R_t := \{qa \rightarrow p: qa \rightarrow p \in R,\ p, q \in Q_t, a \in \Sigma\}.$
```

Nonterminating States: Example

$M = (Q, \Sigma, R, s, F)$, where: $Q = \{s, q_1, q_2, f\}$, $\Sigma = \{a, b\}$,
$R = \{sa \rightarrow q_1, sb \rightarrow q_2, q_1a \rightarrow q_2, q_1b \rightarrow f\}$, $F = \{f\}$

Nonterminating States: Example

$M = (Q, \Sigma, R, s, F)$, where: $Q = \{s, q_1, q_2, f\}$, $\Sigma = \{a, b\}$,
$R = \{sa \rightarrow q_1, sb \rightarrow q_2, q_1a \rightarrow q_2, q_1b \rightarrow f\}$, $F = \{f\}$

$Q_0 = \{\boldsymbol{f}\}$

Nonterminating States: Example

$M = (Q, \Sigma, R, s, F)$, where: $Q = \{s, q_1, q_2, f\}$, $\Sigma = \{a, b\}$,
$R = \{sa \rightarrow q_1, sb \rightarrow q_2, q_1a \rightarrow q_2, q_1b \rightarrow f\}$, $F = \{f\}$

$Q_0 = \{\boldsymbol{f}\}$

1) $qd \rightarrow \boldsymbol{f}$; $q \in Q$; $d \in \Sigma$: $\boldsymbol{q_1}b \rightarrow \boldsymbol{f}$

$Q_1 = \{\boldsymbol{f}\} \cup \{\boldsymbol{q_1}\} = \{\boldsymbol{f}, \boldsymbol{q_1}\}$

Nonterminating States: Example

$M = (Q, \Sigma, R, s, F)$, where: $Q = \{s, q_1, q_2, f\}$, $\Sigma = \{a, b\}$,
$R = \{sa \rightarrow q_1, sb \rightarrow q_2, q_1a \rightarrow q_2, q_1b \rightarrow f\}$, $F = \{f\}$

$Q_0 = \{\boldsymbol{f}\}$

---

1) $qd \rightarrow \boldsymbol{f}$; $q \in Q$; $d \in \Sigma$: $\boldsymbol{q_1}b \rightarrow \boldsymbol{f}$

$Q_1 = \{\boldsymbol{f}\} \cup \{\boldsymbol{q_1}\} = \{\boldsymbol{f}, \boldsymbol{q_1}\}$

---

2) $qd \rightarrow \boldsymbol{f}$; $q \in Q$; $d \in \Sigma$: $\boldsymbol{q_1}b \rightarrow \boldsymbol{f}$

$qd \rightarrow \boldsymbol{q_1}$; $q \in Q$; $d \in \Sigma$: $\boldsymbol{s}a \rightarrow \boldsymbol{q_1}$

$Q_2 = \{\boldsymbol{f}, \boldsymbol{q_1}\} \cup \{\boldsymbol{q_1}, \boldsymbol{s}\} = \{\boldsymbol{f}, \boldsymbol{q_1}, \boldsymbol{s}\}$

Nonterminating States: Example

$M = (Q, \Sigma, R, s, F)$, where: $Q = \{s, q_1, q_2, f\}$, $\Sigma = \{a, b\}$, $R = \{sa \rightarrow q_1, sb \rightarrow q_2, q_1a \rightarrow q_2, q_1b \rightarrow f\}$, $F = \{f\}$

$Q_0 = \{f\}$

---

1) $qd \rightarrow f$; $q \in Q$; $d \in \Sigma$: $\mathbf{q_1}b \rightarrow \mathbf{f}$

$Q_1 = \{f\} \cup \{\mathbf{q_1}\} = \{\mathbf{f}, \mathbf{q_1}\}$

---

2) $qd \rightarrow f$; $q \in Q$; $d \in \Sigma$: $\mathbf{q_1}b \rightarrow \mathbf{f}$

$qd \rightarrow \mathbf{q_1}$; $q \in Q$; $d \in \Sigma$: $\mathbf{s}a \rightarrow \mathbf{q_1}$

$Q_2 = \{f, \mathbf{q_1}\} \cup \{\mathbf{q_1}, \mathbf{s}\} = \{f, \mathbf{q_1}, \mathbf{s}\}$

---

3) $qd \rightarrow f$; $q \in Q$; $d \in \Sigma$: $\mathbf{q_1}b \rightarrow \mathbf{f}$

$qd \rightarrow \mathbf{q_1}$; $q \in Q$; $d \in \Sigma$: $\mathbf{s}a \rightarrow \mathbf{q_1}$

$qd \rightarrow \mathbf{s}$; $q \in Q$; $d \in \Sigma$: **none**

$Q_3 = \{f, \mathbf{q_1}, \mathbf{s}\} \cup \{\mathbf{q_1}, \mathbf{s}\} = \{f, \mathbf{q_1}, \mathbf{s}\} = Q_2 = Q_t$

Nonterminating States: Example

$M = (Q, \Sigma, R, s, F)$, where: $Q = \{s, q_1, q_2, f\}$, $\Sigma = \{a, b\}$,
$R = \{sa \rightarrow q_1, sb \rightarrow q_2, q_1a \rightarrow q_2, q_1b \rightarrow f\}$, $F = \{f\}$

$Q_0 = \{f\}$

---

1) $qd \rightarrow f$; $q \in Q$; $d \in \Sigma$: $\quad \mathbf{q_1}b \rightarrow \mathbf{f}$

$Q_1 = \{f\} \cup \{\mathbf{q_1}\} = \{f, \mathbf{q_1}\}$

---

2) $qd \rightarrow f$; $q \in Q$; $d \in \Sigma$: $\quad \mathbf{q_1}b \rightarrow \mathbf{f}$
$qd \rightarrow \mathbf{q_1}$; $q \in Q$; $d \in \Sigma$: $\quad sa \rightarrow \mathbf{q_1}$

$Q_2 = \{f, \mathbf{q_1}\} \cup \{\mathbf{q_1}, \mathbf{s}\} = \{f, \mathbf{q_1}, \mathbf{s}\}$

---

3) $qd \rightarrow f$; $q \in Q$; $d \in \Sigma$: $\quad \mathbf{q_1}b \rightarrow \mathbf{f}$
$qd \rightarrow \mathbf{q_1}$; $q \in Q$; $d \in \Sigma$: $\quad sa \rightarrow \mathbf{q_1}$
$qd \rightarrow \mathbf{s}$; $q \in Q$; $d \in \Sigma$: $\quad$ **none**

$Q_3 = \{f, \mathbf{q_1}, \mathbf{s}\} \cup \{\mathbf{q_1}, \mathbf{s}\} = \{f, \mathbf{q_1}, \mathbf{s}\} = Q_2 = Q_t$

$R_t = \{\mathbf{sa} \rightarrow \mathbf{q_1}, \mathbf{sb} \rightarrow \mathbf{q_2}, \mathbf{q_1a} \rightarrow \mathbf{q_2}, \mathbf{q_1b} \rightarrow \mathbf{f}\}$

Nonterminating States: Example

$M = (Q, \Sigma, R, s, F)$, where: $Q = \{s, q_1, q_2, f\}$, $\Sigma = \{a, b\}$,
$R = \{sa \rightarrow q_1, sb \rightarrow q_2, q_1a \rightarrow q_2, q_1b \rightarrow f\}$, $F = \{f\}$

$Q_0 = \{f\}$

---

1) $qd \rightarrow f$; $q \in Q$; $d \in \Sigma$: $\boldsymbol{q_1}b \rightarrow \boldsymbol{f}$
$Q_1 = \{f\} \cup \{\boldsymbol{q_1}\} = \{f, \boldsymbol{q_1}\}$

---

2) $qd \rightarrow f$; $q \in Q$; $d \in \Sigma$: $\boldsymbol{q_1}b \rightarrow \boldsymbol{f}$
$qd \rightarrow \boldsymbol{q_1}$; $q \in Q$; $d \in \Sigma$: $\boldsymbol{s}a \rightarrow \boldsymbol{q_1}$
$Q_2 = \{f, \boldsymbol{q_1}\} \cup \{\boldsymbol{q_1}, \boldsymbol{s}\} = \{f, \boldsymbol{q_1}, \boldsymbol{s}\}$

---

3) $qd \rightarrow f$; $q \in Q$; $d \in \Sigma$: $\boldsymbol{q_1}b \rightarrow \boldsymbol{f}$
$qd \rightarrow \boldsymbol{q_1}$; $q \in Q$; $d \in \Sigma$: $\boldsymbol{s}a \rightarrow \boldsymbol{q_1}$
$qd \rightarrow \boldsymbol{s}$; $q \in Q$; $d \in \Sigma$: **none**
$Q_3 = \{f, \boldsymbol{q_1}, \boldsymbol{s}\} \cup \{\boldsymbol{q_1}, \boldsymbol{s}\} = \{f, \boldsymbol{q_1}, \boldsymbol{s}\} = Q_2 = Q_t$

$R_t = \{\boldsymbol{sa} \rightarrow \boldsymbol{q_1}, \boldsymbol{sb} \cancel{\rightarrow} q_2, \boldsymbol{q_1a} \rightarrow q_2, \boldsymbol{q_1b} \rightarrow \boldsymbol{f}\}$

Nonterminating States: Example

$M = (Q, \Sigma, R, s, F)$, where: $Q = \{s, q_1, q_2, f\}$, $\Sigma = \{a, b\}$,
$R = \{sa \rightarrow q_1, sb \rightarrow q_2, q_1a \rightarrow q_2, q_1b \rightarrow f\}$, $F = \{f\}$

$Q_0 = \{\boldsymbol{f}\}$

---

1) $qd \rightarrow \boldsymbol{f}$; $q \in Q$; $d \in \Sigma$: $\boldsymbol{q_1}b \rightarrow \boldsymbol{f}$

$Q_1 = \{\boldsymbol{f}\} \cup \{\boldsymbol{q_1}\} = \{\boldsymbol{f}, \boldsymbol{q_1}\}$

---

2) $qd \rightarrow \boldsymbol{f}$; $q \in Q$; $d \in \Sigma$: $\boldsymbol{q_1}b \rightarrow \boldsymbol{f}$
$qd \rightarrow \boldsymbol{q_1}$; $q \in Q$; $d \in \Sigma$: $\boldsymbol{s}a \rightarrow \boldsymbol{q_1}$

$Q_2 = \{\boldsymbol{f}, \boldsymbol{q_1}\} \cup \{\boldsymbol{q_1}, \boldsymbol{s}\} = \{\boldsymbol{f}, \boldsymbol{q_1}, \boldsymbol{s}\}$

---

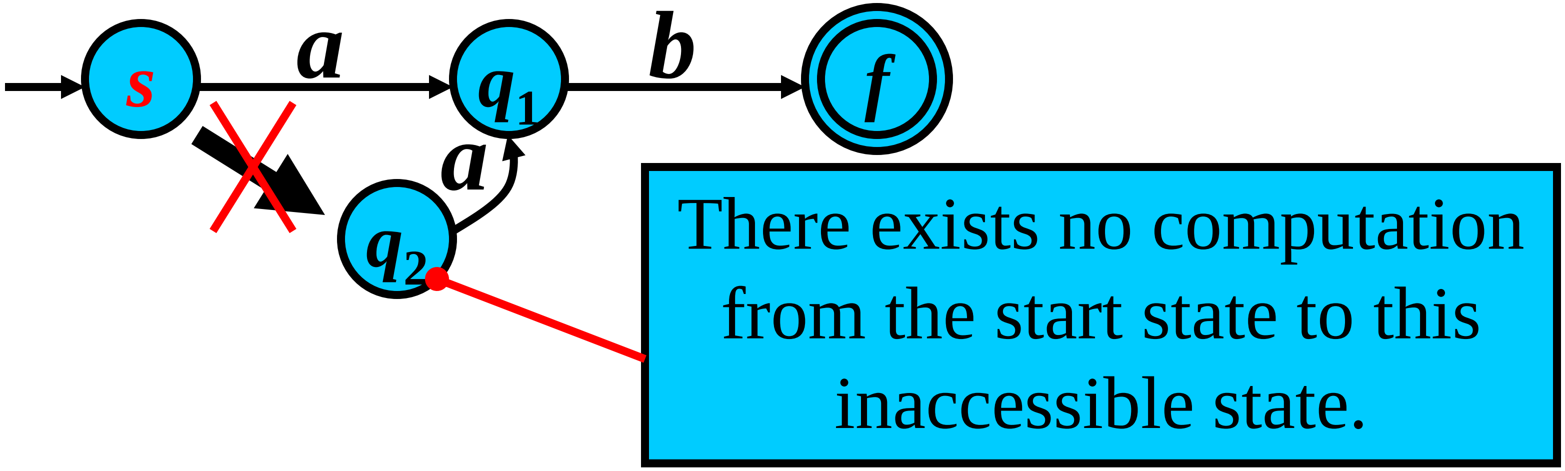
3) $qd \rightarrow \boldsymbol{f}$; $q \in Q$; $d \in \Sigma$: $\boldsymbol{q_1}b \rightarrow \boldsymbol{f}$
$qd \rightarrow \boldsymbol{q_1}$; $q \in Q$; $d \in \Sigma$: $\boldsymbol{s}a \rightarrow \boldsymbol{q_1}$
$qd \rightarrow \boldsymbol{s}$; $q \in Q$; $d \in \Sigma$: **none**

$Q_3 = \{\boldsymbol{f}, \boldsymbol{q_1}, \boldsymbol{s}\} \cup \{\boldsymbol{q_1}, \boldsymbol{s}\} = \{\boldsymbol{f}, \boldsymbol{q_1}, \boldsymbol{s}\} = Q_2 = Q_t$

$R_t = \{\boldsymbol{sa} \rightarrow \boldsymbol{q_1}, \boldsymbol{sb} \cancel{\rightarrow} \boldsymbol{q_2}, \boldsymbol{q_1a} \cancel{\rightarrow} \boldsymbol{q_2}, \boldsymbol{q_1b} \rightarrow \boldsymbol{f}\}$

Summary: States to Remove

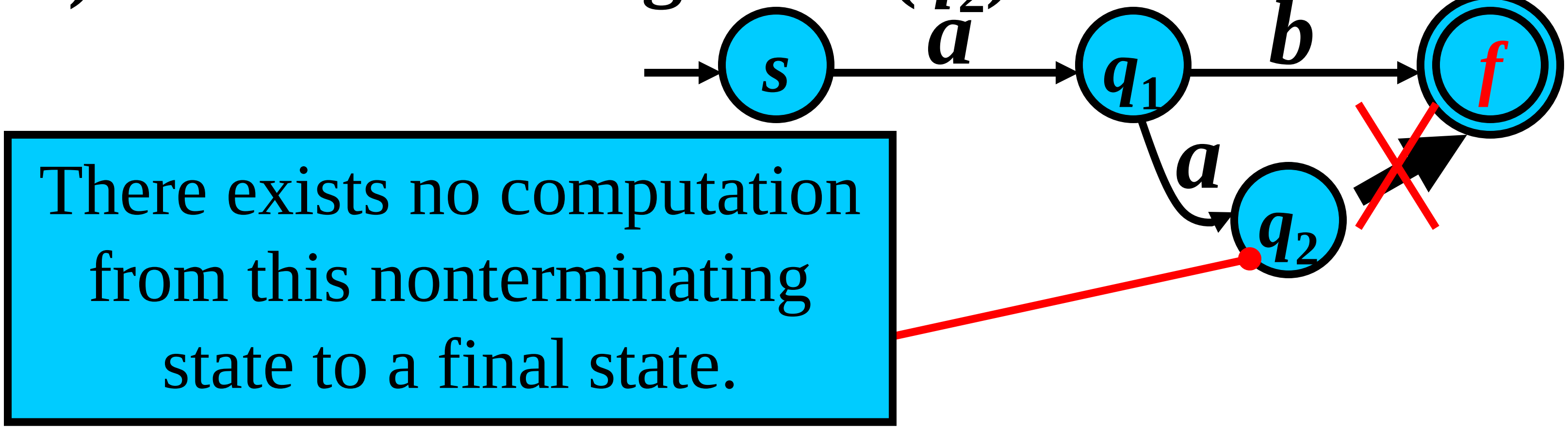
1) Inaccessible state (q_2):



There exists no computation from the start state to this inaccessible state.

---

2) Nonterminating state (q_2):



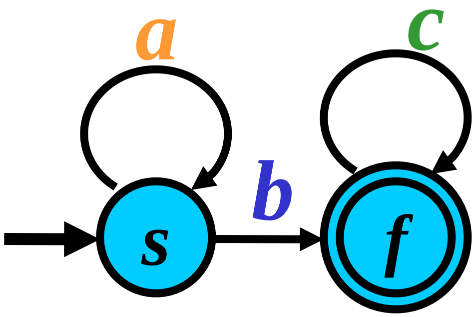
There exists no computation from this nonterminating state to a final state.

Complete DFA

Gist: Complete DFA cannot get stuck.

Definition: Let $M = (Q, \Sigma, R, s, F)$ be a **DFA**. M is ***complete***, if for any $p \in Q$, $a \in \Sigma$ there is exactly one rule of the form $pa \rightarrow q \in R$ for some $q \in Q$; otherwise, M is ***incomplete***

Conversion: Incomplete DFA



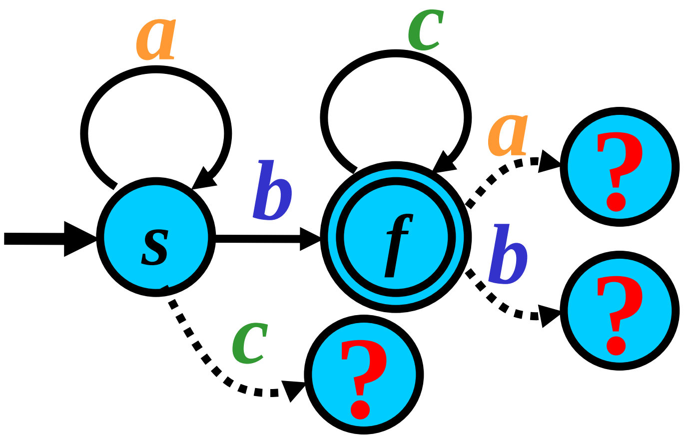
$\Sigma = \{a, b, c\}$

Complete DFA

Gist: Complete DFA cannot get stuck.

Definition: Let $M = (Q, \Sigma, R, s, F)$ be a **DFA**. M is ***complete***, if for any $p \in Q$, $a \in \Sigma$ there is exactly one rule of the form $pa \rightarrow q \in R$ for some $q \in Q$; otherwise, M is ***incomplete***

Conversion: Incomplete DFA



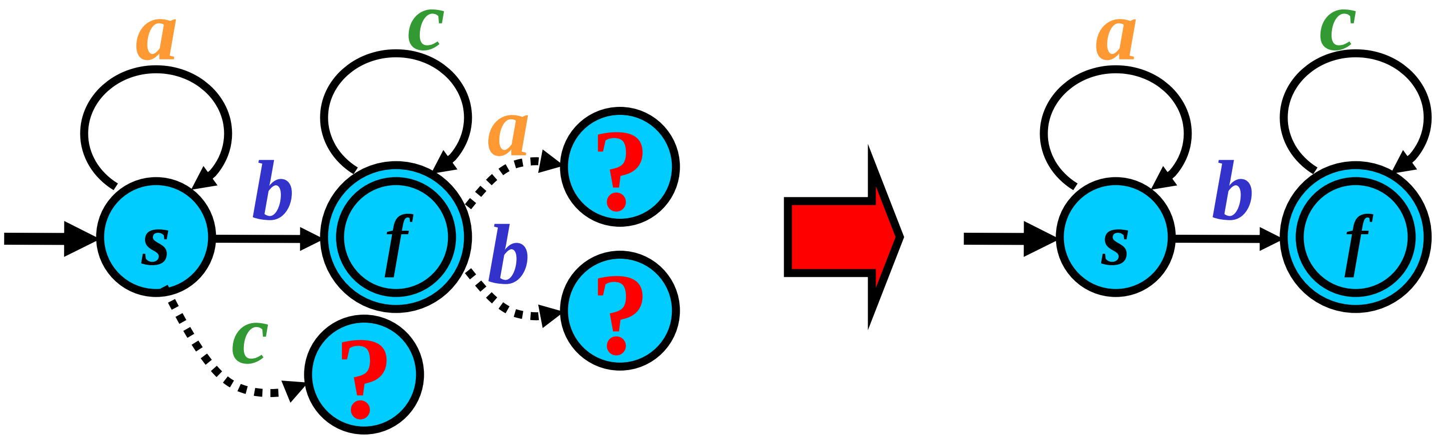
$\Sigma = \{a, b, c\}$

Complete DFA

Gist: Complete DFA cannot get stuck.

Definition: Let $M = (Q, \Sigma, R, s, F)$ be a **DFA**. M is ***complete***, if for any $p \in Q$, $a \in \Sigma$ there is exactly one rule of the form $pa \to q \in R$ for some $q \in Q$; otherwise, M is ***incomplete***

Conversion: Incomplete DFA **to Complete DFA**



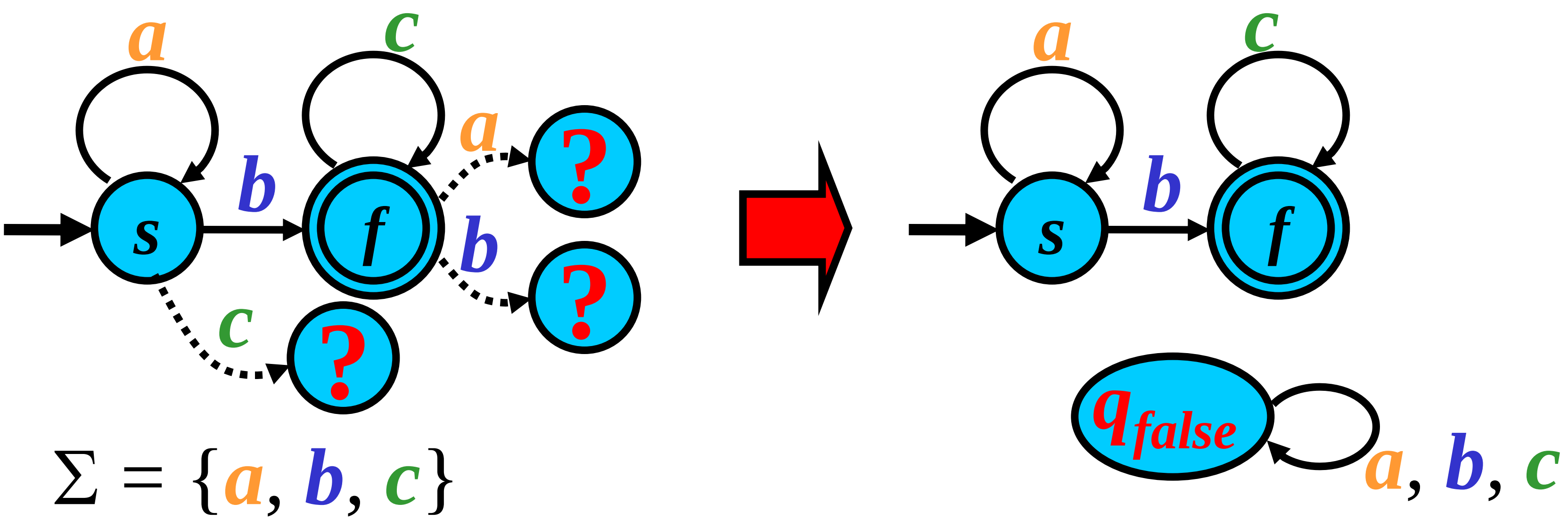
$\Sigma = \{a, b, c\}$

Complete DFA

Gist: Complete DFA cannot get stuck.

Definition: Let $M = (Q, \Sigma, R, s, F)$ be a **DFA**. M is ***complete***, if for any $p \in Q$, $a \in \Sigma$ there is exactly one rule of the form $pa \rightarrow q \in R$ for some $q \in Q$; otherwise, M is ***incomplete***

Conversion: **Incomplete DFA** **to Complete DFA**



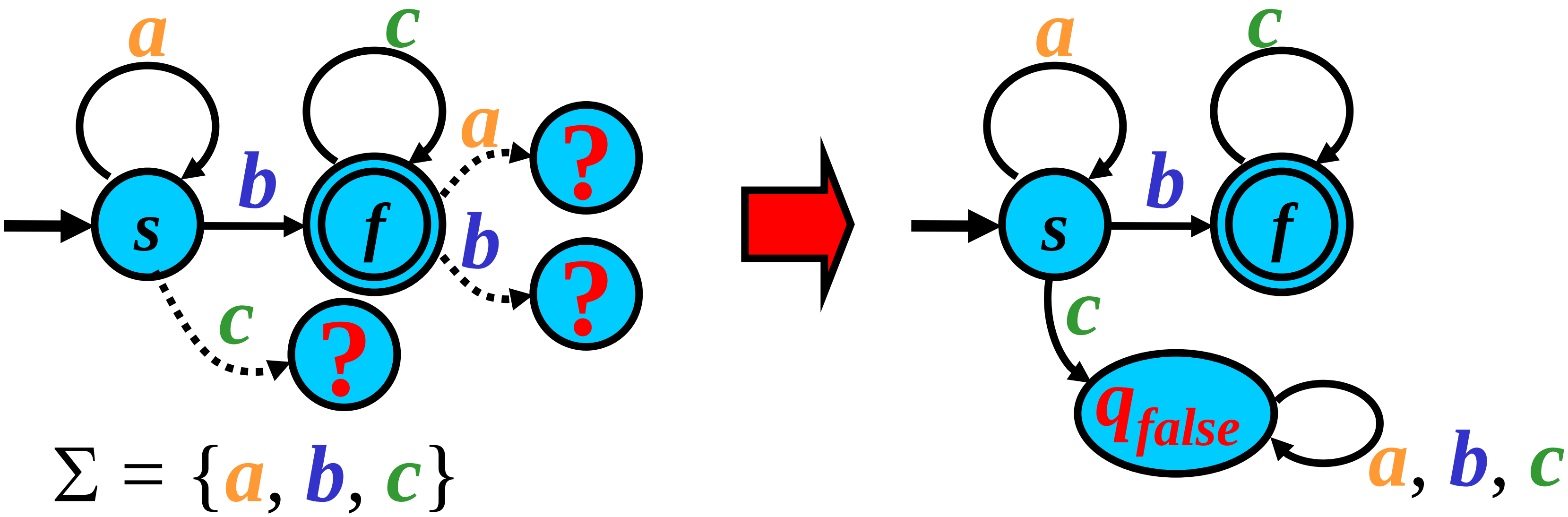
$\Sigma = \{a, b, c\}$

Complete DFA

Gist: Complete DFA cannot get stuck.

Definition: Let $M = (Q, \Sigma, R, s, F)$ be a **DFA**. M is ***complete***, if for any $p \in Q$, $a \in \Sigma$ there is exactly one rule of the form $pa \rightarrow q \in R$ for some $q \in Q$; otherwise, M is ***incomplete***

Conversion: Incomplete DFA **to Complete DFA**

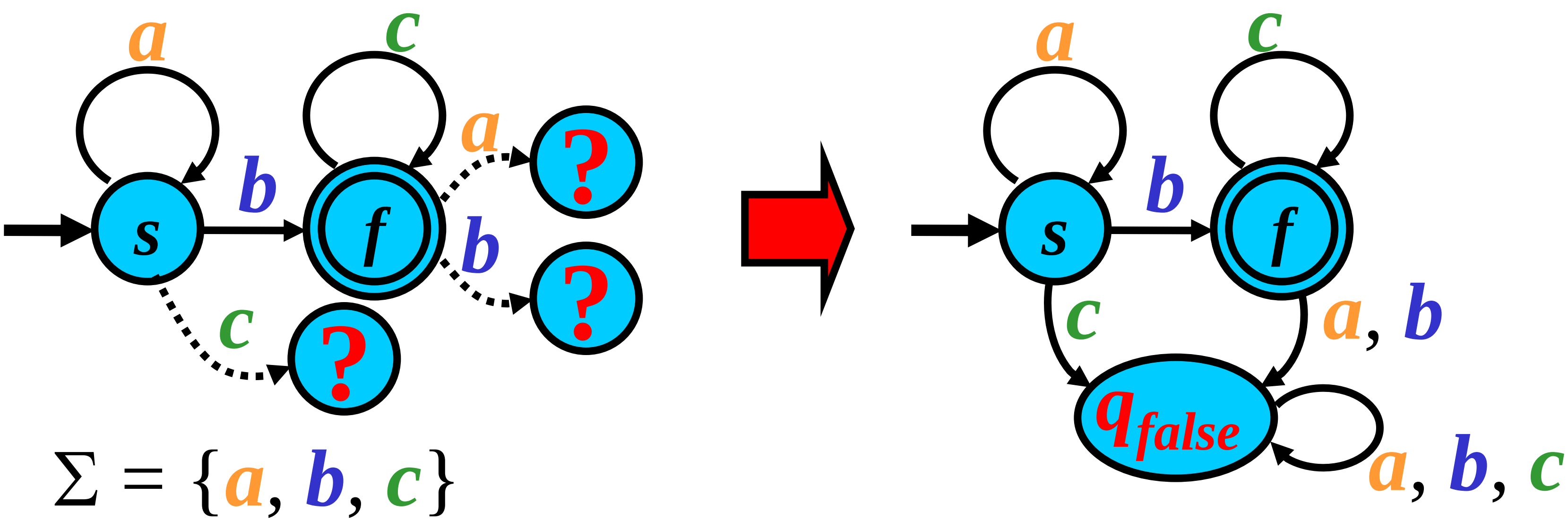


Complete DFA

Gist: Complete DFA cannot get stuck.

Definition: Let $M = (Q, \Sigma, R, s, F)$ be a **DFA**. M is ***complete***, if for any $p \in Q$, $a \in \Sigma$ there is exactly one rule of the form $pa \rightarrow q \in R$ for some $q \in Q$; otherwise, M is ***incomplete***

Conversion: **Incomplete DFA** **to Complete DFA**



$\Sigma = \{a, b, c\}$

Algorithm: DFA to Complete DFA

Gist: Add a “trap” state

- **Input:** Incomplete DFA $M = (Q, \Sigma, R, s, F)$
- **Output:** Complete DFA $M_c = (Q_c, \Sigma, R_c, s, F)$

- **Method:**
- $Q_c := Q \cup \{q_{false}\};$
- $R_c := R \cup \{qa \rightarrow q_{false}: a \in \Sigma, q \in Q_c,$
  $qa \rightarrow p \notin R,\ \ p \in Q\}.$

Well-Specified FA

Definition: Let $M = (Q, \Sigma, R, s, F)$ be a **complete DFA**. Then, M is ***well-specified FA*** (WSFA) if:

1) Q has no inaccessible state

2) Q has no more than one nonterminating state

Note: If well-specified FA has one nonterminating state, then it is q_{false} from the previous algorithm.

Theorem: For every FA M, there is an equivalent WSFA M_{ws}.

Proof: Use the next algorithm.

Algorithm: FA to WSFA

- **Input:** FA M
- **Output:** WSFA M_{ws}

- **Method:**
- convert a FA M to an equivalent ε-free FA M'
- convert a M' to an equivalent DFA M_d without any inaccessible state
- convert M_d to an equivalent DFA M_t without any nonterminating state
- convert M_t to an equivalent complete FA M_c
- $M_{ws} := M_c$

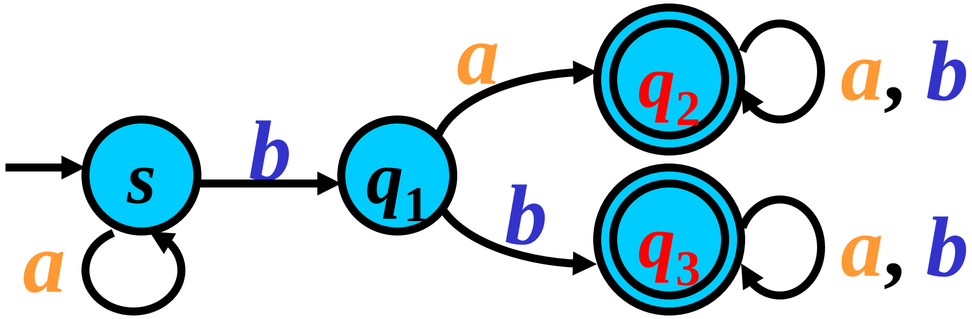
Note: No more than one nonterminating state in M_{ws}—q_{false}

Distinguishable States

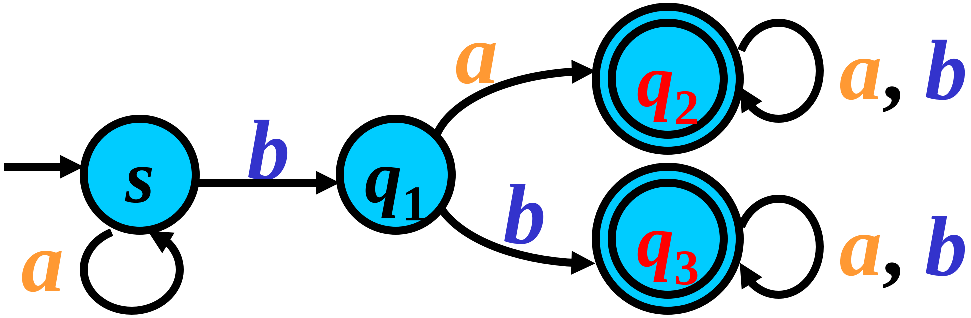
Gist: String *w distinguishes* states *p* and *q* if WSFA reaches a final state from precisely one of configurations *pw* and *qw*.

Definition: Let $M = (Q, \Sigma, R, s, F)$ be a WSFA, and let $p, q \in Q$, $p \neq q$. States p and q are *distinguishable* if there exists $w \in \Sigma^*$ such that: $pw \vdash^* p'$ and $qw \vdash^* q'$, where $p', q' \in Q$ and $((p' \in F$ and $q' \notin F)$ or $(p' \notin F$ and $q' \in F))$; otherwise, states p and q are *indistinguishable*

Distinguishable States: Example



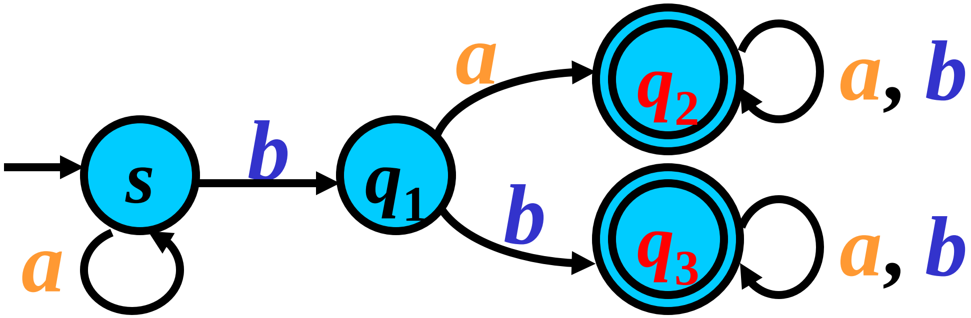
Distinguishable States: Example



- s and q_1 are **distinguishable**, because for $w = a$:

$$sa \vdash s \;,\; s \notin F$$
$$q_1 a \vdash q_2 \;,\; q_2 \in F$$

Distinguishable States: Example



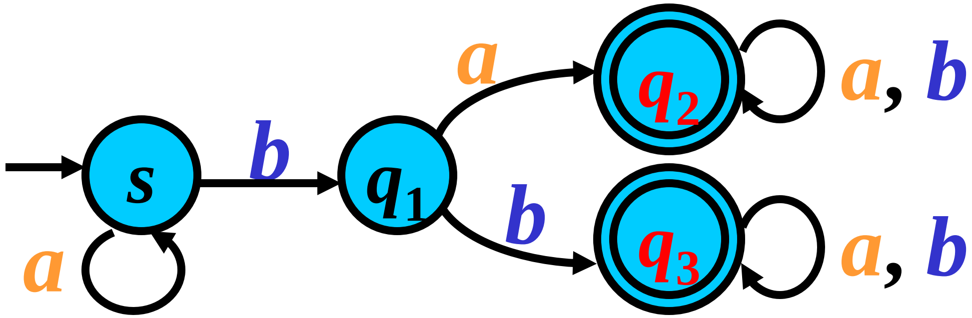
- s and q_1 are **distinguishable**, because for $w = a$:

$$sa \vdash s\ ,\ s \notin F$$
$$q_1a \vdash q_2\ ,\ q_2 \in F$$

- q_2 and q_3 are **indistinguishable**, because for each $w \in \Sigma^*$:

$$q_2w \vdash^* q_2,\ q_2 \in F$$
$$q_3w \vdash^* q_3,\ q_3 \in F$$

Distinguishable States: Example



- s and q_1 are **distinguishable**, because for $w = a$:

$$sa \vdash s\ ,\ s \notin F$$
$$q_1 a \vdash q_2\ ,\ q_2 \in F$$

- q_2 and q_3 are **indistinguishable**, because for each $w \in \Sigma^*$:

$$q_2 w \vdash^* q_2,\ q_2 \in F$$
$$q_3 w \vdash^* q_3,\ q_3 \in F$$

- Other pairs of states are trivially **distinguishable** for $w = \varepsilon$.

Minimum-State FA

Definition: Let M be a **WSFA**. Then, M is ***minimum-state FA*** if M contains only distinguishable states.

Theorem: For every WSFA M, there is an equivalent minimum-state FA M_m

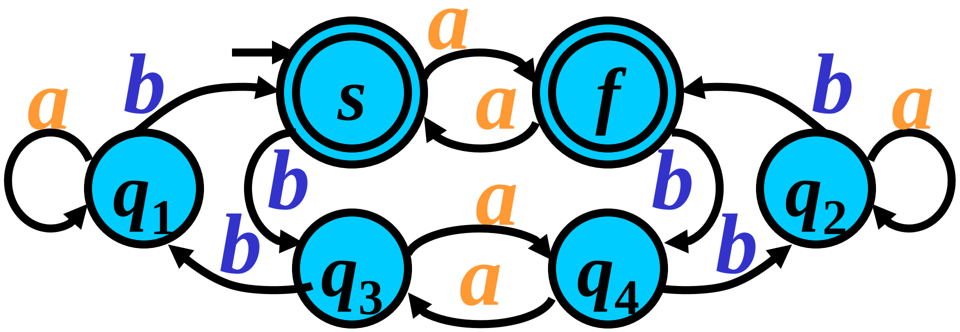
Proof: Use the next algorithm.

Algorithm: WSFA to Min-State FA

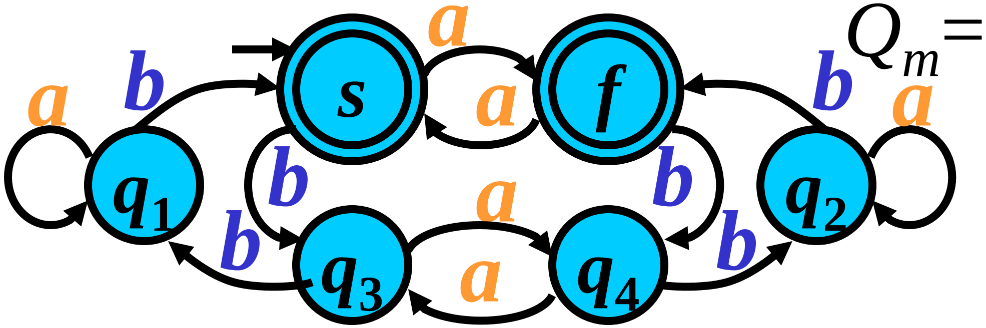
- **Input:** WSFA $M = (Q, \Sigma, R, s, F)$
- **Output:** Minimum-State FA $M_m = (Q_m, \Sigma, R_m, s_m, F_m)$
- **Method:**

```
• $Q_m = \{\{p: p \in F\}, \{q: q \in Q - F\}\};$
• repeat
     if there exist $X \in Q_m$, $d \in \Sigma$, $X_1, X_2 \subset X$ such that
         $X = X_1 \cup X_2$, $X_1 \cap X_2 = \emptyset$ and
         $\{q_1: p_1 \in X_1, p_1d \rightarrow q_1 \in R\} \subseteq Q_1, Q_1 \in Q_m,$
         $\{q_2: p_2 \in X_2, p_2d \rightarrow q_2 \in R\} \cap Q_1 = \emptyset$
     then divide $X$ into $X_1$ and $X_2$ in $Q_m$
  until no division is possible;
• $R_m = \{ Xa \rightarrow Y: X, Y \in Q_m, pa \rightarrow q \in R, p \in X, q \in Y, a \in \Sigma\};$
• $s_m = X$ with $s \in X$;  $F_m := \{X: X \in Q_m, X \cap F \neq \emptyset\}.$
```

Minimization: Example 1/4

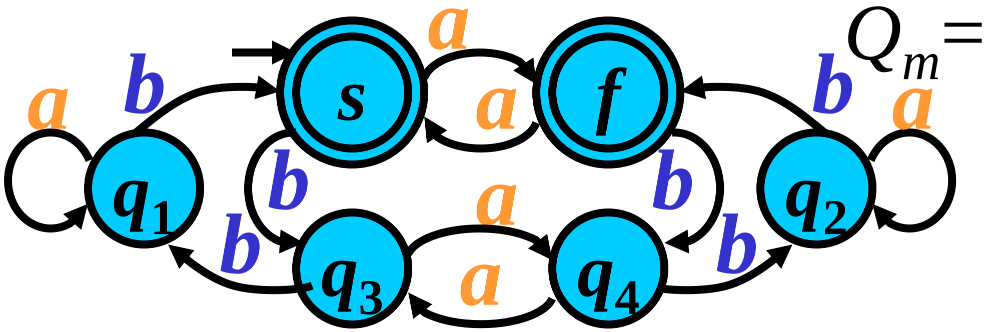


Minimization: Example 1/4



$Q_m = \{\underbrace{\{s, f\}}_{\boxed{\text{Final States}}}, \underbrace{\{q_1, q_2, q_3, q_4\}}_{\boxed{\text{Other States}}}\}$

Minimization: Example 1/4



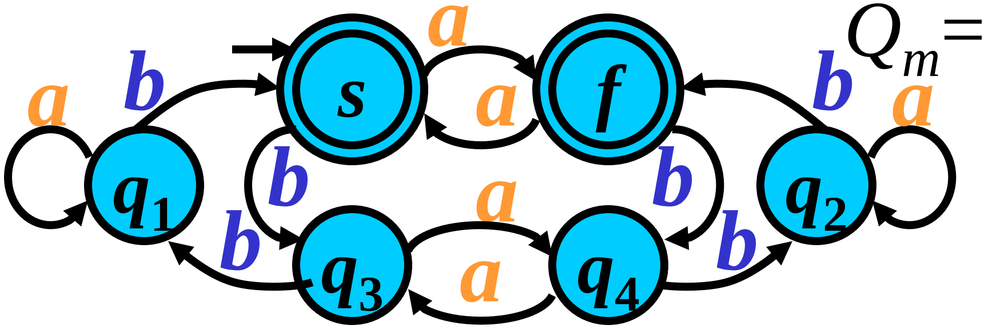
$$Q_m = \{\underbrace{\{s,f\}}_{\text{Final States}}, \underbrace{\{q_1,q_2,q_3,q_4\}}_{\text{Other States}}\}$$

1) $X = \{s,f\}$:

$d = a$: $sa \rightarrow f$

$fa \rightarrow s$

Minimization: Example 1/4



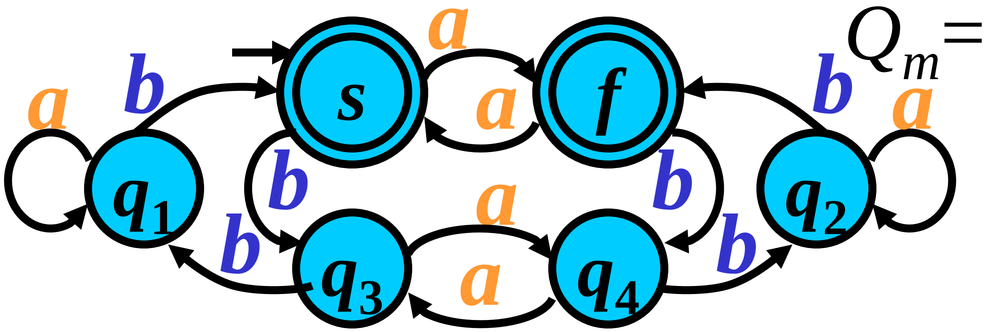
$$Q_m = \{\underbrace{\{s,f\}}_{\boxed{\text{Final States}}}, \underbrace{\{q_1,q_2,q_3,q_4\}}_{\boxed{\text{Other States}}}\}$$

---

1) $X = \{s,f\}$: **From one set**

$d = a$: $\begin{array}{l} sa \rightarrow \\ fa \rightarrow \end{array} \boxed{\begin{array}{c} f \\ s \end{array}}$

Minimization: Example 1/4



$$Q_m = \{\underbrace{\{s,f\}}_{\boxed{\text{Final States}}}, \underbrace{\{q_1,q_2,q_3,q_4\}}_{\boxed{\text{Other States}}}\}$$

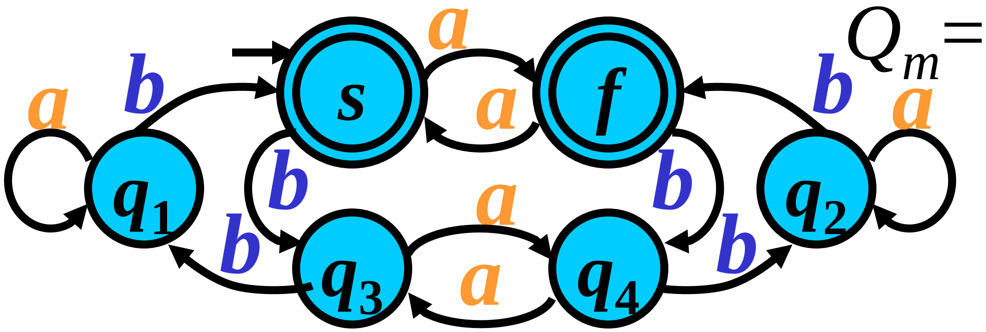
---

1) $X = \{s,f\}$: **From one set**

$d = a$: $sa \rightarrow f$, $fa \rightarrow s$ $\quad$ $\boxed{\begin{matrix} f \\ s \end{matrix}}$

$d = b$: $sb \rightarrow q_3$, $fb \rightarrow q_4$

Minimization: Example 1/4



$$Q_m = \{\underbrace{\{s,f\}}_{\text{Final States}}, \underbrace{\{q_1,q_2,q_3,q_4\}}_{\text{Other States}}\}$$

---

1) $X = \{s,f\}$:

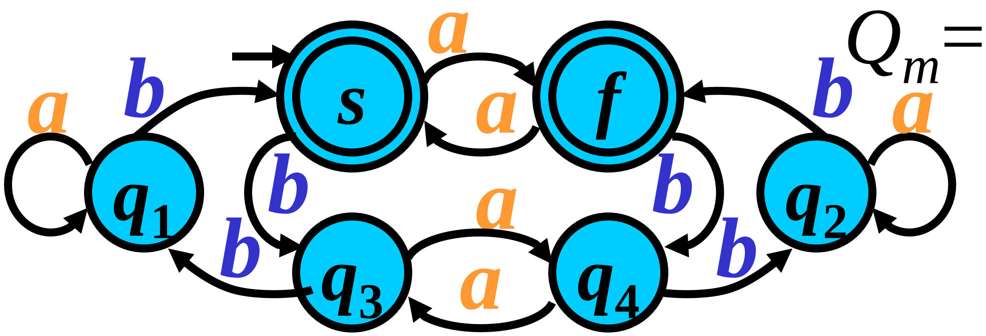
From one set

$$d = a:\quad \begin{array}{l} sa \rightarrow \\ fa \rightarrow \end{array} \boxed{\begin{array}{c} f \\ s \end{array}}$$

From one set

$$d = b:\quad \begin{array}{l} sb \rightarrow \\ fb \rightarrow \end{array} \boxed{\begin{array}{c} q_3 \\ q_4 \end{array}}$$

Minimization: Example 1/4



$$Q_m = \{\underbrace{\{s,f\}}_{\text{Final States}}, \underbrace{\{q_1,q_2,q_3,q_4\}}_{\text{Other States}}\}$$

---

1) $X = \{s,f\}$:

From one set

$d = a$: $sa \rightarrow f$
$fa \rightarrow s$

From one set

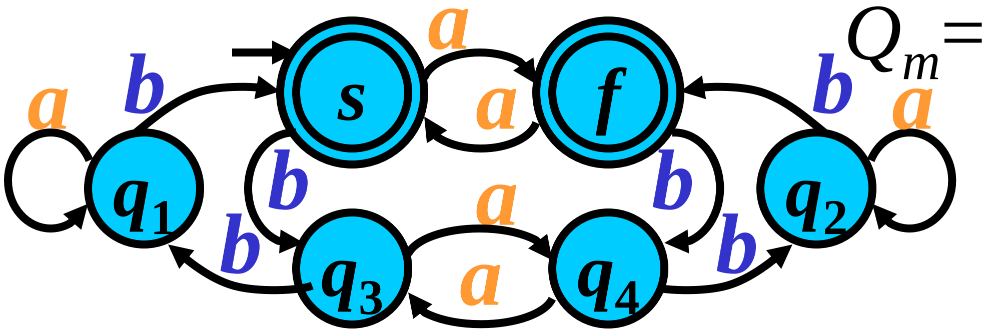
$d = b$: $sb \rightarrow q_3$
$fb \rightarrow q_4$

---

2) $X = \{q_1,q_2,q_3,q_4\}$:

$d = a$: $q_1a \rightarrow q_1$
$q_2a \rightarrow q_2$
$q_3a \rightarrow q_4$
$q_4a \rightarrow q_3$

Minimization: Example 1/4



$$Q_m = \{\underbrace{\{s,f\}}_{\text{Final States}}, \underbrace{\{q_1,q_2,q_3,q_4\}}_{\text{Other States}}\}$$

---

1) $X = \{s,f\}$:

$$d = a: \quad \begin{matrix} sa \to \\ fa \to \end{matrix} \boxed{\begin{matrix} f \\ s \end{matrix}}$$

From one set

$$d = b: \quad \begin{matrix} sb \to \\ fb \to \end{matrix} \boxed{\begin{matrix} q_3 \\ q_4 \end{matrix}}$$

From one set

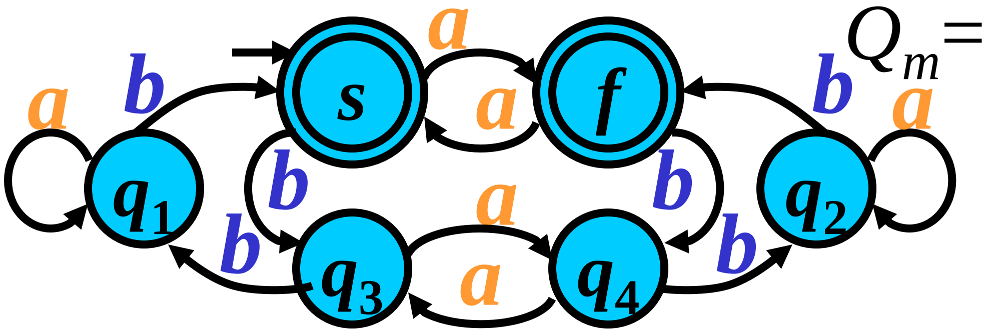
---

2) $X = \{q_1,q_2,q_3,q_4\}$:

$$d = a: \quad \begin{matrix} q_1a \to \\ q_2a \to \\ q_3a \to \\ q_4a \to \end{matrix} \boxed{\begin{matrix} q_1 \\ q_2 \\ q_4 \\ q_3 \end{matrix}}$$

From one set

Minimization: Example 1/4



$$Q_m = \{\underbrace{\{s,f\}}_{\boxed{\text{Final States}}}, \underbrace{\{q_1,q_2,q_3,q_4\}}_{\boxed{\text{Other States}}}\}$$

---

1) $X = \{s,f\}$:

From one set

$$d = a: \quad \begin{array}{l} sa \rightarrow \\ fa \rightarrow \end{array} \boxed{\begin{array}{c} f \\ s \end{array}}$$

From one set

$$d = b: \quad \begin{array}{l} sb \rightarrow \\ fb \rightarrow \end{array} \boxed{\begin{array}{c} q_3 \\ q_4 \end{array}}$$

---

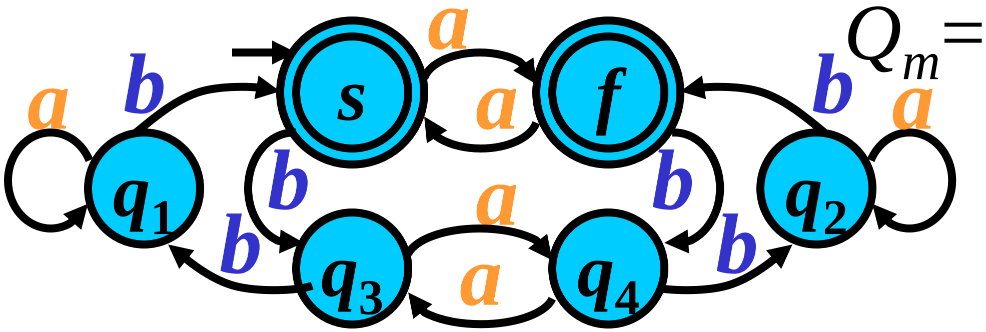
2) $X = \{q_1,q_2,q_3,q_4\}$:

From one set

$$d = a: \quad \begin{array}{l} q_1a \rightarrow \\ q_2a \rightarrow \\ q_3a \rightarrow \\ q_4a \rightarrow \end{array} \boxed{\begin{array}{c} q_1 \\ q_2 \\ q_4 \\ q_3 \end{array}}$$

$$d = b: \quad \begin{array}{l} q_1b \rightarrow s \\ q_2b \rightarrow f \\ q_3b \rightarrow q_1 \\ q_4b \rightarrow q_2 \end{array}$$

Minimization: Example 1/4



$Q_m = \{\underbrace{\{s,f\}}_{\text{Final States}}, \underbrace{\{q_1,q_2,q_3,q_4\}}_{\text{Other States}}\}$

Final States

Other States

---

1) $X = \{s,f\}$:

From one set **From one set**

$d = a$: $sa \rightarrow f$, $fa \rightarrow s$ $\quad$ $d = b$: $sb \rightarrow q_3$, $fb \rightarrow q_4$

---

2) $X = \{q_1,q_2,q_3,q_4\}$:

From one set

$d = a$:

$q_1a \rightarrow q_1$

$q_2a \rightarrow q_2$

$q_3a \rightarrow q_4$

$q_4a \rightarrow q_3$

$d = b$:

$q_1b \rightarrow s$

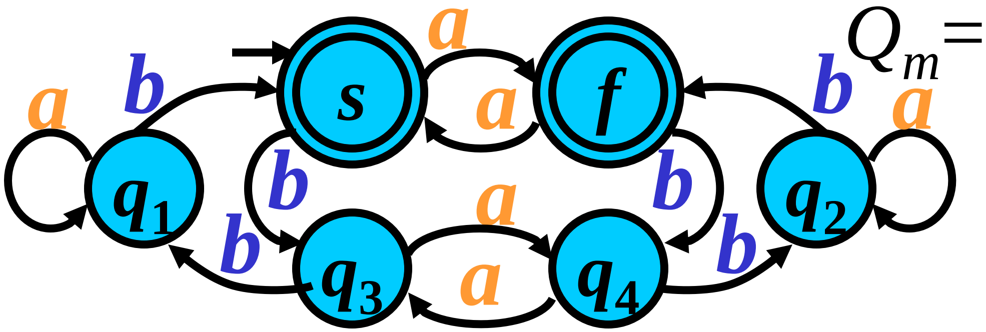
$q_2b \rightarrow f$

$q_3b \rightarrow q_1$

$q_4b \rightarrow q_2$

$\{s, f\} \subseteq Q_1 = \{s, f\}$

Minimization: Example 1/4



$Q_m = \{\underbrace{\{s,f\}}_{\text{Final States}},\ \underbrace{\{q_1,q_2,q_3,q_4\}}_{\text{Other States}}\}$

---

1) $X = \{s,f\}$:

$d = a$: $sa \rightarrow f$, $fa \rightarrow s$ — $\boxed{f, s}$ From one set

$d = b$: $sb \rightarrow q_3$, $fb \rightarrow q_4$ — $\boxed{q_3, q_4}$ From one set

---

2) $X = \{q_1,q_2,q_3,q_4\}$:

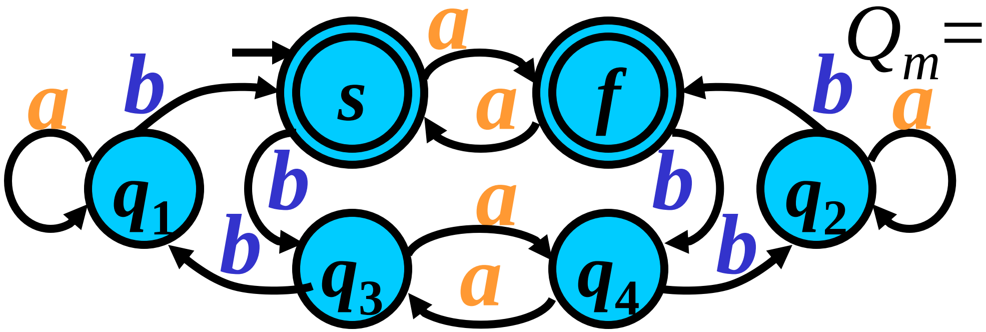
$d = a$: $q_1a \rightarrow q_1$, $q_2a \rightarrow q_2$, $q_3a \rightarrow q_4$, $q_4a \rightarrow q_3$ — $\boxed{q_1, q_2, q_4, q_3}$ From one set

$d = b$: $q_1b \rightarrow s$, $q_2b \rightarrow f$, $q_3b \rightarrow q_1$, $q_4b \rightarrow q_2$

$\boxed{s, f} \subseteq Q_1 = \{s, f\}$

$\{q_1,q_2\} \cap Q_1 = \varnothing$

Minimization: Example 1/4



$Q_m = \{\underbrace{\{s,f\}}_{\text{Final States}},\ \underbrace{\{q_1,q_2,q_3,q_4\}}_{\text{Other States}}\}$

---

1) $X = \{s,f\}$:

From one set

$d = a$: $sa \rightarrow f$, $fa \rightarrow s$ $\boxed{f,\ s}$

From one set

$d = b$: $sb \rightarrow q_3$, $fb \rightarrow q_4$ $\boxed{q_3,\ q_4}$

---

2) $X = \{q_1,q_2,q_3,q_4\}$:

From one set

$d = a$:

$q_1a \rightarrow q_1$

$q_2a \rightarrow q_2$

$q_3a \rightarrow q_4$

$q_4a \rightarrow q_3$

$d = b$:

$q_1b \rightarrow s$

$q_2b \rightarrow f$

$q_3b \rightarrow q_1$

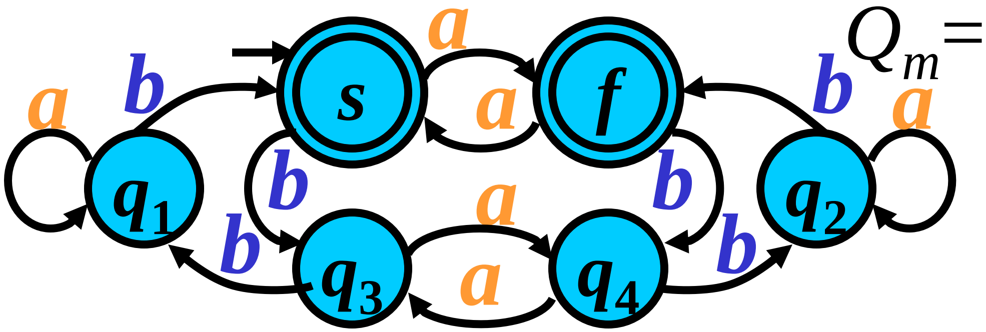
$q_4b \rightarrow q_2$

$\{s, f\} \subseteq Q_1 = \{s, f\}$

$\{q_1,q_2\} \cap Q_1 = \varnothing$

Division: $\{q_1,q_2,q_3,q_4\} \Rightarrow$

Minimization: Example 1/4



$Q_m = \{\underbrace{\{s, f\}}_{\text{Final States}}, \underbrace{\{q_1, q_2, q_3, q_4\}}_{\text{Other States}}\}$

---

1) $X = \{s, f\}$:

From one set **From one set**

$d = a$: $sa \rightarrow \boxed{f}$, $fa \rightarrow \boxed{s}$ $d = b$: $sb \rightarrow \boxed{q_3}$, $fb \rightarrow \boxed{q_4}$

---

2) $X = \{q_1, q_2, q_3, q_4\}$:

From one set

$d = a$:

$q_1a \rightarrow q_1$
$q_2a \rightarrow q_2$
$q_3a \rightarrow q_4$
$q_4a \rightarrow q_3$

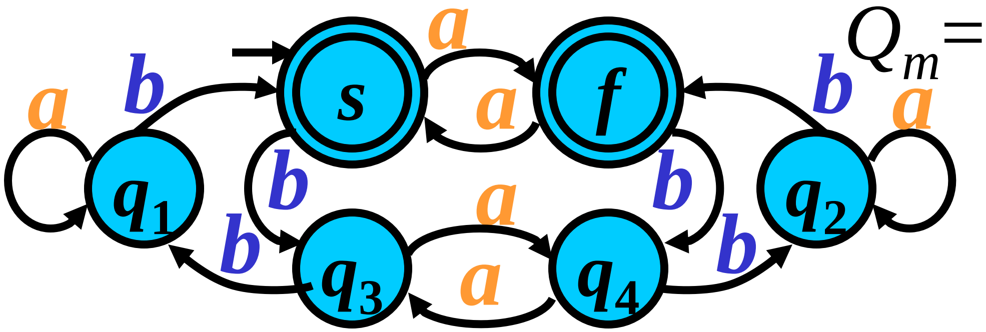
$d = b$:

$q_1b \rightarrow s$
$q_2b \rightarrow f$ $\subseteq Q_1 = \{s, f\}$
$q_3b \rightarrow q_1$
$q_4b \rightarrow q_2$

$\{q_1, q_2\} \cap Q_1 = \varnothing$

Division: $\{q_1, q_2, q_3, q_4\} \Rightarrow \underbrace{\{q_1, q_2\}}_{X_1},$

Minimization: Example 1/4



$$Q_m = \{\underbrace{\{s, f\}}_{\text{Final States}}, \underbrace{\{q_1, q_2, q_3, q_4\}}_{\text{Other States}}\}$$

---

1) $X = \{s, f\}$:

From one set

$d = a$: $sa \rightarrow f$, $fa \rightarrow s$ $\quad \boxed{f, s}$

From one set

$d = b$: $sb \rightarrow q_3$, $fb \rightarrow q_4$ $\quad \boxed{q_3, q_4}$

---

2) $X = \{q_1, q_2, q_3, q_4\}$:

From one set

$d = a$: $q_1a \rightarrow q_1$, $q_2a \rightarrow q_2$, $q_3a \rightarrow q_4$, $q_4a \rightarrow q_3$ $\quad \boxed{q_1, q_2, q_4, q_3}$

$d = b$: $q_1b \rightarrow s$, $q_2b \rightarrow f$ $\quad \boxed{s, f} \subseteq Q_1 = \{s, f\}$

$q_3b \rightarrow q_1$, $q_4b \rightarrow q_2$ $\quad \boxed{q_1, q_2}$

$\{q_1, q_2\} \cap Q_1 = \emptyset$

Division: $\{q_1, q_2, q_3, q_4\} \Rightarrow \underbrace{\{q_1, q_2\}}_{X_1}, \underbrace{\{q_3, q_4\}}_{X_2}$

Minimization: Example 2/4

$Q_m = \{\{s,f\}, \{q_1,q_2\}, \{q_3,q_4\}\}$

Minimization: Example 2/4

$Q_m = \{\{s,f\}, \{q_1,q_2\}, \{q_3,q_4\}\}$

---

1) $X = \{s,f\}$:

$d = a$: $sa \rightarrow f$

$fa \rightarrow s$

Minimization: Example 2/4

$Q_m = \{\{s,f\}, \{q_1,q_2\}, \{q_3,q_4\}\}$

---

1) $X = \{s,f\}$:

From one set

$$d = a: \quad \begin{array}{l} sa \rightarrow \\ fa \rightarrow \end{array} \boxed{\begin{array}{c} f \\ s \end{array}}$$

Minimization: Example 2/4

$Q_m = \{\{s,f\}, \{q_1,q_2\}, \{q_3,q_4\}\}$

---

1) $X = \{s,f\}$:

From one set

$$d = a: \quad \begin{array}{l} sa \rightarrow \\ fa \rightarrow \end{array} \boxed{\begin{array}{c} f \\ s \end{array}} \qquad\qquad d = b: \quad \begin{array}{l} sb \rightarrow q_3 \\ fb \rightarrow q_4 \end{array}$$

Minimization: Example 2/4

$Q_m = \{\{s,f\}, \{q_1,q_2\}, \{q_3,q_4\}\}$

---

1) $X = \{s,f\}$:

From one set

$$d = a: \quad \begin{array}{l} sa \rightarrow \\ fa \rightarrow \end{array} \boxed{\begin{array}{c} f \\ s \end{array}}$$

From one set

$$d = b: \quad \begin{array}{l} sb \rightarrow \\ fb \rightarrow \end{array} \boxed{\begin{array}{c} q_3 \\ q_4 \end{array}}$$

Minimization: Example 2/4

$Q_m = \{\{s,f\}, \{q_1,q_2\}, \{q_3,q_4\}\}$

---

1) $X = \{s,f\}$:

From one set

$d = a$: $sa \rightarrow f$
$fa \rightarrow s$

From one set

$d = b$: $sb \rightarrow q_3$
$fb \rightarrow q_4$

---

2) $X = \{q_1,q_2\}$:

$d = a$: $q_1a \rightarrow q_1$
$q_2a \rightarrow q_2$

Minimization: Example 2/4

$Q_m = \{\{s,f\}, \{q_1,q_2\}, \{q_3,q_4\}\}$

---

1) $X = \{s,f\}$:

From one set

$$d = a: \quad \begin{array}{l} sa \to \\ fa \to \end{array} \boxed{\begin{array}{c} f \\ s \end{array}}$$

From one set

$$d = b: \quad \begin{array}{l} sb \to \\ fb \to \end{array} \boxed{\begin{array}{c} q_3 \\ q_4 \end{array}}$$

---

2) $X = \{q_1,q_2\}$:

From one set

$$d = a: \quad \begin{array}{l} q_1a \to \\ q_2a \to \end{array} \boxed{\begin{array}{c} q_1 \\ q_2 \end{array}}$$

Minimization: Example 2/4

$Q_m = \{\{s,f\}, \{q_1,q_2\}, \{q_3,q_4\}\}$

---

1) $X = \{s,f\}$:

From one set

$$d = a:\quad \begin{array}{l} sa \rightarrow \\ fa \rightarrow \end{array} \boxed{\begin{array}{c} f \\ s \end{array}}$$

From one set

$$d = b:\quad \begin{array}{l} sb \rightarrow \\ fb \rightarrow \end{array} \boxed{\begin{array}{c} q_3 \\ q_4 \end{array}}$$

---

2) $X = \{q_1,q_2\}$:

From one set

$$d = a:\quad \begin{array}{l} q_1a \rightarrow \\ q_2a \rightarrow \end{array} \boxed{\begin{array}{c} q_1 \\ q_2 \end{array}}$$

$$d = b:\quad \begin{array}{l} q_1b \rightarrow s \\ q_2b \rightarrow f \end{array}$$

Minimization: Example 2/4

$Q_m = \{\{s,f\}, \{q_1,q_2\}, \{q_3,q_4\}\}$

---

1) $X = \{s,f\}$:

From one set

$$d = a: \quad \begin{array}{l} sa \rightarrow \\ fa \rightarrow \end{array} \boxed{\begin{array}{c} f \\ s \end{array}}$$

From one set

$$d = b: \quad \begin{array}{l} sb \rightarrow \\ fb \rightarrow \end{array} \boxed{\begin{array}{c} q_3 \\ q_4 \end{array}}$$

---

2) $X = \{q_1,q_2\}$:

From one set

$$d = a: \quad \begin{array}{l} q_1a \rightarrow \\ q_2a \rightarrow \end{array} \boxed{\begin{array}{c} q_1 \\ q_2 \end{array}}$$

From one set

$$d = b: \quad \begin{array}{l} q_1b \rightarrow \\ q_2b \rightarrow \end{array} \boxed{\begin{array}{c} s \\ f \end{array}}$$

Minimization: Example 2/4

$Q_m = \{\{s, f\}, \{q_1, q_2\}, \{q_3, q_4\}\}$

1) $X = \{s, f\}$:

From one set

$d = a$: $sa \to f$
$fa \to s$

From one set

$d = b$: $sb \to q_3$
$fb \to q_4$

2) $X = \{q_1, q_2\}$:

From one set

$d = a$: $q_1a \to q_1$
$q_2a \to q_2$

From one set

$d = b$: $q_1b \to s$
$q_2b \to f$

3) $X = \{q_3, q_4\}$:

$d = a$: $q_3a \to q_3$
$q_4a \to q_4$

Minimization: Example 2/4

$Q_m = \{\{s,f\}, \{q_1,q_2\}, \{q_3,q_4\}\}$

1) $X = \{s,f\}$:

From one set

$$d = a: \quad \begin{matrix} sa \rightarrow \\ fa \rightarrow \end{matrix} \boxed{\begin{matrix} f \\ s \end{matrix}}$$

From one set

$$d = b: \quad \begin{matrix} sb \rightarrow \\ fb \rightarrow \end{matrix} \boxed{\begin{matrix} q_3 \\ q_4 \end{matrix}}$$

2) $X = \{q_1,q_2\}$:

From one set

$$d = a: \quad \begin{matrix} q_1a \rightarrow \\ q_2a \rightarrow \end{matrix} \boxed{\begin{matrix} q_1 \\ q_2 \end{matrix}}$$

From one set

$$d = b: \quad \begin{matrix} q_1b \rightarrow \\ q_2b \rightarrow \end{matrix} \boxed{\begin{matrix} s \\ f \end{matrix}}$$

3) $X = \{q_3,q_4\}$:

From one set

$$d = a: \quad \begin{matrix} q_3a \rightarrow \\ q_4a \rightarrow \end{matrix} \boxed{\begin{matrix} q_3 \\ q_4 \end{matrix}}$$

Minimization: Example 2/4

$Q_m = \{\{s,f\}, \{q_1,q_2\}, \{q_3,q_4\}\}$

---

1) $X = \{s,f\}$:

From one set

$$d = a: \quad \begin{matrix} sa \to \\ fa \to \end{matrix} \boxed{\begin{matrix} f \\ s \end{matrix}}$$

From one set

$$d = b: \quad \begin{matrix} sb \to \\ fb \to \end{matrix} \boxed{\begin{matrix} q_3 \\ q_4 \end{matrix}}$$

---

2) $X = \{q_1,q_2\}$:

From one set

$$d = a: \quad \begin{matrix} q_1a \to \\ q_2a \to \end{matrix} \boxed{\begin{matrix} q_1 \\ q_2 \end{matrix}}$$

From one set

$$d = b: \quad \begin{matrix} q_1b \to \\ q_2b \to \end{matrix} \boxed{\begin{matrix} s \\ f \end{matrix}}$$

---

3) $X = \{q_3,q_4\}$:

From one set

$$d = a: \quad \begin{matrix} q_3a \to \\ q_4a \to \end{matrix} \boxed{\begin{matrix} q_3 \\ q_4 \end{matrix}}$$

$$d = b: \quad \begin{matrix} q_3b \to q_1 \\ q_4b \to q_2 \end{matrix}$$

Minimization: Example 2/4

$Q_m = \{\{s,f\}, \{q_1,q_2\}, \{q_3,q_4\}\}$

1) $X = \{s,f\}$:

From one set

$$d = a:\quad \begin{array}{l} sa \rightarrow \\ fa \rightarrow \end{array} \boxed{\begin{array}{c} f \\ s \end{array}}$$

From one set

$$d = b:\quad \begin{array}{l} sb \rightarrow \\ fb \rightarrow \end{array} \boxed{\begin{array}{c} q_3 \\ q_4 \end{array}}$$

2) $X = \{q_1,q_2\}$:

From one set

$$d = a:\quad \begin{array}{l} q_1a \rightarrow \\ q_2a \rightarrow \end{array} \boxed{\begin{array}{c} q_1 \\ q_2 \end{array}}$$

From one set

$$d = b:\quad \begin{array}{l} q_1b \rightarrow \\ q_2b \rightarrow \end{array} \boxed{\begin{array}{c} s \\ f \end{array}}$$

3) $X = \{q_3,q_4\}$:

From one set

$$d = a:\quad \begin{array}{l} q_3a \rightarrow \\ q_4a \rightarrow \end{array} \boxed{\begin{array}{c} q_3 \\ q_4 \end{array}}$$

From one set

$$d = b:\quad \begin{array}{l} q_3b \rightarrow \\ q_4b \rightarrow \end{array} \boxed{\begin{array}{c} q_1 \\ q_2 \end{array}}$$

Minimization: Example 2/4

$Q_m = \{\{s,f\}, \{q_1,q_2\}, \{q_3,q_4\}\}$

---

1) $X = \{s,f\}$:

From one set

$$d = a: \quad \begin{matrix} sa \rightarrow \\ fa \rightarrow \end{matrix} \boxed{\begin{matrix} f \\ s \end{matrix}}$$

From one set

$$d = b: \quad \begin{matrix} sb \rightarrow \\ fb \rightarrow \end{matrix} \boxed{\begin{matrix} q_3 \\ q_4 \end{matrix}}$$

---

2) $X = \{q_1,q_2\}$:

From one set

$$d = a: \quad \begin{matrix} q_1a \rightarrow \\ q_2a \rightarrow \end{matrix} \boxed{\begin{matrix} q_1 \\ q_2 \end{matrix}}$$

From one set

$$d = b: \quad \begin{matrix} q_1b \rightarrow \\ q_2b \rightarrow \end{matrix} \boxed{\begin{matrix} s \\ f \end{matrix}}$$

---

3) $X = \{q_3,q_4\}$:

From one set

$$d = a: \quad \begin{matrix} q_3a \rightarrow \\ q_4a \rightarrow \end{matrix} \boxed{\begin{matrix} q_3 \\ q_4 \end{matrix}}$$

From one set

$$d = b: \quad \begin{matrix} q_3b \rightarrow \\ q_4b \rightarrow \end{matrix} \boxed{\begin{matrix} q_1 \\ q_2 \end{matrix}}$$

No next divisions !!!

Minimization: Example 3/4

$Q_m = \{\{s,f\}, \{q_1,q_2\}, \{q_3,q_4\}\}$

$$\left.\begin{array}{l} sa \to f \in R: \\ fa \to s \in R: \end{array}\right\} \Rightarrow \{s,f\}a \to \{s,f\} \in R_m$$

$$\left.\begin{array}{l} sb \to q_3 \in R: \\ fb \to q_4 \in R: \end{array}\right\} \Rightarrow \{s,f\}b \to \{q_3,q_4\} \in R_m$$

$$\left.\begin{array}{l} q_1a \to q_1 \in R: \\ q_2a \to q_2 \in R: \end{array}\right\} \Rightarrow \{q_1,q_2\}a \to \{q_1,q_2\} \in R_m$$

$$\left.\begin{array}{l} q_1b \to s \in R: \\ q_2b \to f \in R: \end{array}\right\} \Rightarrow \{q_1,q_2\}b \to \{s,f\} \in R_m$$

$$\left.\begin{array}{l} q_3a \to q_3 \in R: \\ q_4a \to q_4 \in R: \end{array}\right\} \Rightarrow \{q_3,q_4\}a \to \{q_3,q_4\} \in R_m$$

$$\left.\begin{array}{l} q_3b \to q_1 \in R: \\ q_4b \to q_2 \in R: \end{array}\right\} \Rightarrow \{q_3,q_4\}b \to \{q_1,q_2\} \in R_m$$

Minimization: Example 4/4

$\mathbf{s} \in \{\mathbf{s},\mathbf{f}\}$ ⇒ $\mathbf{s_m} := \{\mathbf{s},\mathbf{f}\}$

$\left.\begin{array}{l} \mathbf{s} \in F: \\ \mathbf{f} \in F: \end{array}\right\}$ ⇒ $\{\mathbf{s},\mathbf{f}\} \in F_m$

$M_m = (Q_m, \Sigma, R_m, s_m, F_m)$, where: $\Sigma = \{\mathbf{a}, \mathbf{b}\}$, $s_m = \{\mathbf{s},\mathbf{f}\}$

$Q_m = \{\{\mathbf{s},\mathbf{f}\}, \{\mathbf{q_1},\mathbf{q_2}\}, \{\mathbf{q_3},\mathbf{q_4}\}\}$, $F_m = \{\{\mathbf{s},\mathbf{f}\}\}$

$R_m = \{\{\mathbf{s},\mathbf{f}\}\mathbf{a} \rightarrow \{\mathbf{s},\mathbf{f}\}, \{\mathbf{s},\mathbf{f}\}\mathbf{b} \rightarrow \{\mathbf{q_3},\mathbf{q_4}\}, \{\mathbf{q_1},\mathbf{q_2}\}\mathbf{a} \rightarrow \{\mathbf{q_1},\mathbf{q_2}\},$
$\{\mathbf{q_1},\mathbf{q_2}\}\mathbf{b} \rightarrow \{\mathbf{s},\mathbf{f}\}, \{\mathbf{q_3},\mathbf{q_4}\}\mathbf{a} \rightarrow \{\mathbf{q_3},\mathbf{q_4}\}, \{\mathbf{q_3},\mathbf{q_4}\}\mathbf{b} \rightarrow \{\mathbf{q_1},\mathbf{q_2}\}\}$

Minimization: Example 4/4

$s \in \{s,f\} \Rightarrow s_m := \{s,f\}$

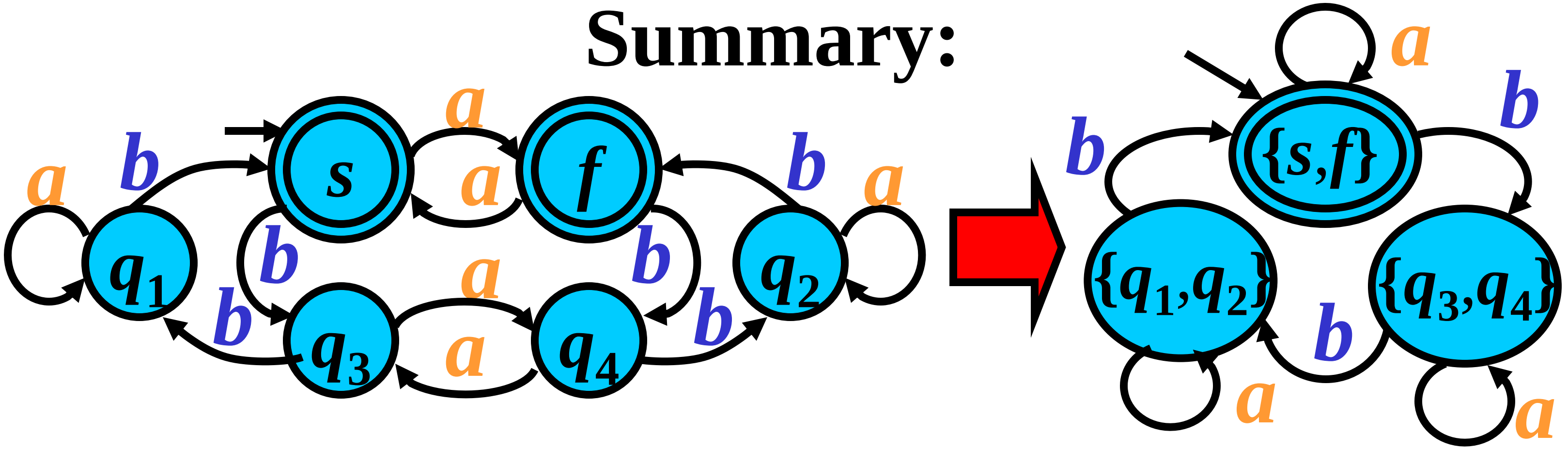
$\left.\begin{array}{l} s \in F: \\ f \in F: \end{array}\right\} \Rightarrow \{s,f\} \in F_m$

$M_m = (Q_m, \Sigma, R_m, s_m, F_m)$, where: $\Sigma = \{a, b\}$, $s_m = \{s,f\}$

$Q_m = \{\{s,f\}, \{q_1,q_2\}, \{q_3,q_4\}\}$, $F_m = \{\{s,f\}\}$

$R_m = \{\{s,f\}a \rightarrow \{s,f\}, \{s,f\}b \rightarrow \{q_3,q_4\}, \{q_1,q_2\}a \rightarrow \{q_1,q_2\},$
$\{q_1,q_2\}b \rightarrow \{s,f\}, \{q_3,q_4\}a \rightarrow \{q_3,q_4\}, \{q_3,q_4\}b \rightarrow \{q_1,q_2\}\}$

Summary:



Variants of FA: Summary

	FA	ε-free FA	DFA	Complete FA	WSFA	Min-State FA
Number of rules of the form $p \to q$, where $p, q \in Q$	**0-*n***	**0**	**0**	**0**	**0**	**0**
Number of rules of the form $pa \to q$, for any $p \in Q$, $a \in \Sigma$	**0-*n***	**0-*n***	**0-1**	**1**	**1**	**1**
Number of inaccessible states	**0-*n***	**0-*n***	**0-*n***	**0-*n***	**0**	**0**
Number of nonterminating states	**0-*n***	**0-*n***	**0-*n***	**0-*n***	**0-1**	**0-1**
Number of this FAs for any regular language.	**∞**	**∞**	**∞**	**∞**	**∞**	**1**