# Jumping Finite Automata: New Results

Part Two: New Models

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- Motivation
- n-Parallel Jumping Finite Automata
- Double-Jumping Finite Automata
- One-Way Jumping Finite Automata

# Motivation Why study other models?

# Motivation – Jumping Finite Automata



## Possible Advantages

- completely discontinuous reading
- can accept some CF and CS languages



## Possible Advantages

- completely discontinuous reading
- can accept some CF and CS languages

## Possible Disadvantages

- cannot guarantee any specific reading order
- therefore it cannot accept languages like a\*b\*
- heavily nondeterministic behavior

# Motivation – Right and Left Jumps



## Definition

A GJFA makes a right jump from  $w_pyxz$  to wxqz by  $py \rightarrow q$ :

 $W p y X Z_r \sim W X q Z$ 

where  $w, x, y, z \in \Sigma^*$ .

# Motivation – Right and Left Jumps



## Definition

A GJFA makes a right jump from  $w_pyxz$  to wxqz by  $py \rightarrow q$ :

 $W P Y X Z_r \cap W X Q Z$ 

where  $w, x, y, z \in \Sigma^*$ .

## Definition

A GJFA makes a left jump from wxpyz to wqxz by  $py \rightarrow q$ :

WXDYZ I ~ WQXZ

where  $w, x, y, z \in \Sigma^*$ .



## Properties of Right Jumps

- consider the configuration u p v, where  $p \in Q$ ,  $u, v \in \Sigma^*$
- the automaton will get stuck for any |u| > 0
- result: the same power as FAs



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## Properties of Left Jumps

- open problem
- can define some non-regular languages



## Motivation for New Models

- partially discontinuous reading
- partially continuous reading
- explore new possibilities
- more deterministic behavior

# n-Parallel Jumping Finite Automata

Based on

Radim Kocman and Alexander Meduna On Parallel Versions of Jumping Finite Automata Proceedings of SDOT 2015





## **Example Derivations**

## $S \Rightarrow ABC \Rightarrow aAbBcC \Rightarrow aaAbbBccC \Rightarrow aaabbbccc$



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 $S \Rightarrow ABC \Rightarrow aAbBcC \Rightarrow aaAbbBccC \Rightarrow aaabbbccc$ 

- rarely used in classical automata (multiple tapes, more heads reading the same input, ...)
- What if the parallelism is combined with the jumping?



An *n*-parallel general jumping finite automaton (*n*-PGJFA) is a quintuple

$$M = (Q, \Sigma, R, \frac{S}{S}, F)$$

where

- $\bigcirc$  is a finite set of states;
- $\Sigma$  is an input alphabet,  $Q \cap \Sigma = \emptyset$ ;
- *R* is a finite set of rules:  $py \rightarrow q$ , where  $p, q \in Q$ ,  $y \in \Sigma^*$ ;
- S is a set of start state strings,  $S \subseteq Q^n$ ;
- F is a set of final states.

- arbitrary splits the input into *n* parts
- steps of all heads are synchronized
- different types of the jumping:
  - unrestricted jumps each part is processed as in JFA
  - right jumps each part is processed as in FA



## Example

Consider the 3-PGJFA

 $M = (\{s, r, p\}, \Sigma, R, \{srp\}, \{s, r, p\}),$ 

where  $\Sigma = \{a, b, c\}$  and *R* consists of the rules

$$sa \rightarrow s, rb \rightarrow r, pc \rightarrow p.$$

 $L(M,3-r) = \{a^n b^n c^n \mid n \ge 0\}$ 



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## Example Steps (for n = 3 with only right jumps)

aaa bbb ccc  $\sim$  aa bb cc  $\sim$  a b c  $\sim$ 



#### Theorem

For every *n*-PRLG  $G = (N_1, ..., N_n, T, S1, P)$ , there is an *n*-PGJFA using only right *n*-jumps  $M = (Q, \Sigma, R, S2, F)$ , such that L(M, n-r) = L(G).

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# n-Parallel JFAs – Characterization



#### Theorem

 $_r$ **]-PGJFA** =  $_r$ **GJFA** = **REG**.

## Theorem

 $_{r}$ 2-PGJFA  $\subset$  CF.

## Theorem

 $_r$ *n***-PGJFA** ⊂ **CS** and there exist non-context-free languages in  $_r$ *n***-PGJFA** for all *n* > 2.

## Theorem

For all  $n \in \mathbb{N}$ ,  $_r n$ -PGJFA  $\subset _r (n+1)$ -PGJFA.

# Double-Jumping Finite Automata

Based on

Radim Kocman, Zbyněk Křivka and Alexander Meduna On Double-Jumping Finite Automata Proceedings of NCMA 2016

# Double-JFAs



## Definition

A general jumping finite automaton (GJFA) is a quintuple

$$M = \left(Q, \Sigma, R, \underline{s}, F\right)$$

## where

- Q is a finite set of states;
- Σ is the input alphabet;
- *R* is a finite set of rules of the form

 $py \rightarrow q$   $(p, q \in Q, y \in \Sigma^*)$ 

- s is the start state;
- F is a set of final states.



# Used Symbols ▶ - Right Jump ◄ - Left Jump ♦ - Both Directions

## Studied Modes

- $\bullet \bullet \frown$  Unrestricted 2-Jumps
- ▶ ⊲ へ Right-Left 2-Jumps
- ▶ > > − Right-Right 2-Jumps

- $_{\clubsuit}$   $\sim$  Left-Right 2-Jumps



#### 

## Studied Modes

- $\bullet \bullet \frown$  Unrestricted 2-Jumps
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 $_{\clubsuit}$   $\sim$  – Left-Right 2-Jumps

## Example

$$L(M_{\triangleleft \blacktriangleright \frown}) = \{ uvw \mid u, v, w \in \Sigma^*, usvsw \triangleleft_{\blacktriangleright} \frown^* ff, f \in F \}.$$



## Conditions for 2-Jumps

- both jumps follow the same rule
- the jumps cannot ever cross each other



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- the jumps cannot ever cross each other

## Example with ${}_{\clubsuit} \frown$

- configuration: uu'apvpaw'w, where  $a, u, u', v, w, w' \in \Sigma^*, p \in Q$
- rule: (p, a, q)
- 2-jump: uu'apvpaw'w → ∩ uqu'vw'qw

Double-JFAs – Right-Left 2-Jumps (🛌 🔿)

## T FIT

## Properties

- required initial configuration: *sxs*, where  $x \in \Sigma^*$
- cannot jump over any symbols
- every  $x \in L(M_{\blacktriangleright \blacktriangleleft} \cap)$  can be written as  $x = u_1 u_2 \dots u_n u_n \dots u_2 u_1$ , where  $n \in \mathbb{N}$ , and  $u_i \in \Sigma^*$ ,  $1 \le i \le n$
- accept string palindromes of even length

Double-JFAs – Right-Left 2-Jumps (🛌 🔿)

## T FIT

## Properties

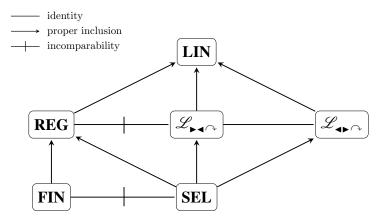
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- accept string palindromes of even length

## Language Family ( $\mathscr{L}_{\blacktriangleright \triangleleft \frown}$ )

- a subfamily of the family of linear languages
- the same as  $\mathscr{L}_{{\scriptscriptstyle lackbdar}}{\scriptscriptstyle \frown}$

# Double-JFAs – Comparison





Double-JFAs – Right-Right 2-Jumps ( $_{P} \land$ )

## T FIT

## Properties

- the first jump should not skip symbols
- the second jump can skip symbols

Double-JFAs – Right-Right 2-Jumps (

## T FIT

## **Properties**

- the first jump should not skip symbols
- the second jump can skip symbols

## **Example Behavior**

- $u_1 u'_1 u_2 u'_2 \dots u_n u'_n$ , where  $n \in \mathbb{N}$ ,  $u_i, u'_i \in \Sigma$ ,  $u_i = u'_i$ ,  $1 \le i \le n$
- red symbols can be also shifted to the right over blue symbols

Double-JFAs – Right-Right 2-Jumps (

## T FIT

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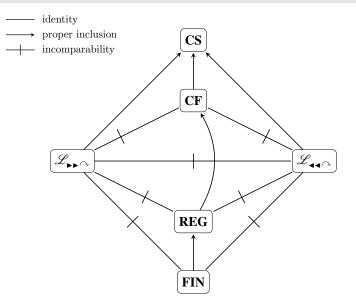
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## Language Family $(\mathscr{L}_{r})$

- a subfamily of the family of context-sensitive languages
- not the same as  $\mathscr{L}_{{\scriptscriptstyle \hspace*{-.5mm}\triangleleft}\,{\scriptscriptstyle \sim}\,{\scriptscriptstyle \sim}\,{\scriptscriptstyle \sim}}$

# Double-JFAs – Comparison





# Double-JFAs – Closure Properties\*



	$\mathscr{L}_{FA^{n}}, \mathscr{L}_{AF^{n}}$	$\mathscr{L}_{\textup{PP}} \sim$	$\mathscr{L}_{{\scriptscriptstyle \P}{\scriptscriptstyle \P}{\scriptscriptstyle \land}}$
endmarking (both sides)	- (+)	- (-)	- (-)
concatenation	_	_	_
square (L <sup>2</sup> )	_	_	—
shuffle	_	—	—
union	+	+	+
complement	_	_	_
intersection	+	_	_
int. with regular languages	+	_	_
mirror image	+	_	_
finite substitution	_	_	_
homomorphism	+	_	_
$\varepsilon$ -free homomorphism	+	_	_
inverse homomorphism	—		_

## **One-Way Jumping Finite Automata**

Based on

Hiroyuki Chigahara, Szilárd Zsolt Fazekas and Akihiro Yamamura One-way Jumping Finite Automata Int. J. Found. Comput. Sci. 27, 391 (2016)

Szilárd Zsolt Fazekas and Akihiro Yamamura On Regular Languages accepted by One-Way Jumping Finite Automata Short Papers of NCMA 2016



A right one-way jumping finite automaton (ROWJFA) is a quintuple  $M = (Q, \Sigma, R, s, F)$ , where  $Q, \Sigma, R, s$  and F are defined as in a DFA.



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## Definition

The right one-way jumping relation, symbolically denoted by  $\circlearrowright$ , over  $Q\Sigma^*$ , is defined as follows. Suppose that x and y belong to  $\Sigma^*$ , a belongs to  $\Sigma$ , p and q are states in Q and  $pa \rightarrow q \in R$ . Then the ROWJFA M makes a jump from the configuration pxay to the configuration qyx, written as

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if x belongs to  $\{\Sigma \setminus \Sigma_{\rho}\}^*$  where  $\Sigma_{\rho} = \{b \in \Sigma \mid (\rho, b, q) \in R \text{ for some } q \in Q\}.$ 



The language accepted by M, denoted by L(M), is defined as

 $L(M) = \{ w \in \Sigma^* \mid sw \circlearrowright^* f, f \in F \}$ 

The language accepted by M, denoted by L(M), is defined as

$$L(M) = \{ w \in \Sigma^* \mid sw \circlearrowright^* f, f \in F \}$$

- fully deterministic behavior
- There is also a similar definition for the left one-way jumping finite automaton.

# One-Way JFAs – Examples

## Example 1

Let  $M_1$  be a ROWJFA given by

 $M_1 = (\{q_0, q_1, q_2\}, \Sigma, R, q_0, \{q_0\}),$ 

where  $\Sigma = \{a, b, c\}$  and *R* consists of the rules

 $q_0 a \rightarrow q_1, \quad q_1 b \rightarrow q_2, \quad q_2 c \rightarrow q_0.$ 

 $L(M_1) = \{ w \in \Sigma \mid |w|_a = |w|_b = |w|_c \}$ 

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# One-Way JFAs – Examples

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 $L(M_1) = \{ w \in \Sigma \mid |w|_a = |w|_b = |w|_c \}$ 

## Example 2

Let  $M_2$  be a ROWJFA given by

 $M_2 = (\{q_0, q_1\}, \Sigma, R, q_0, \{q_0, q_1\}),$ 

where  $\Sigma = \{a, b\}$  and *R* consists of the rules

$$q_0 a \rightarrow q_0, \quad q_0 b \rightarrow q_1, \quad q_1 b \rightarrow q_1.$$

 $L(M_2) = a^*b^*$ 



## Theorem

ROWJ properly includes REG.

#### Theorem

ROWJ and LOWJ are incomparable.

Theorem

**ROWJ**  $\not\subset$  **JFA**.

#### Theorem

CF and ROWJ are incomparable.

# One-Way JFAs – Characterization

## Theorem

## The class **ROWJ** is not closed under

- intersection,
- concatenation,
- reversal,
- intersection with regular languages,
- concatenation with regular languages,
- substitution,
- Kleene star,
- Kleene plus.

## Theorem

Let *M* be a ROWJFA. If there exists a constant *k*, such that for any word  $w \in L(M)$  the number of sweeps needed by *M* to process *w* is at most *k*, then the language L(M) is regular.

## **Overall Conclusion**

*n*-Parallel Jumping Finite Automata – combination of the parallel and jumping behavior

Double-Jumping Finite Automata – parallel combination of different jumping modes

One-Way Jumping Finite Automata – fully deterministic behavior

# Thank you for your attention!